

# Longest Path

## CSCI 532

# Dynamic Programming

Trick-or-treat planning.



# Dynamic Programing

Trick-or-treating at the red house, blue house, and green house are the fewest stops you need to fill your 25-pound capacity sack.



# Dynamic Programming

Trick-or-treating at the red house, blue house, and green house are the fewest stops you need to fill your 25-pound capacity sack. The blue house gives you 5 pounds of candy. What can you conclude?



# Dynamic Programming

Trick-or-treating at the red house, blue house, and green house are the fewest stops you need to fill your 25-pound capacity sack. The blue house gives you 5 pounds of candy. What can you conclude?

The red house and the green house are the fewest stops you need to get 20+ pounds of candy.



# Dynamic Programming

Trick-or-treating at the red house, blue house, and green house are the fewest stops you need to fill your 25-pound capacity sack. The blue house gives you 5 pounds of candy. What can you conclude?

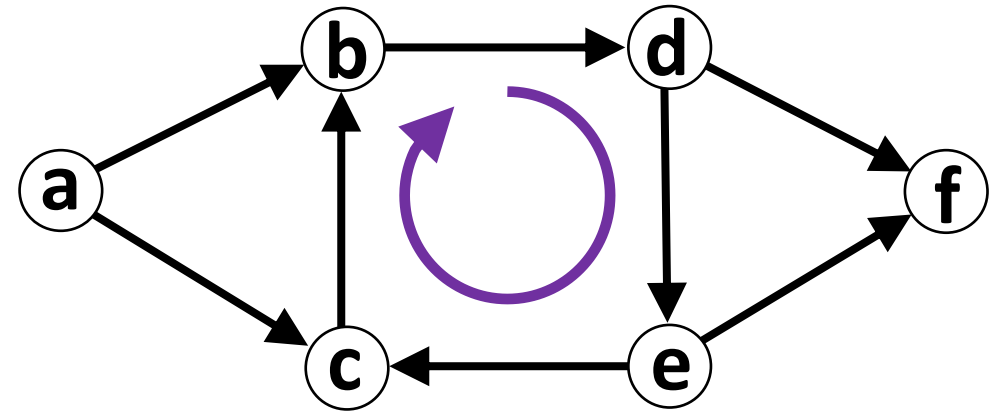
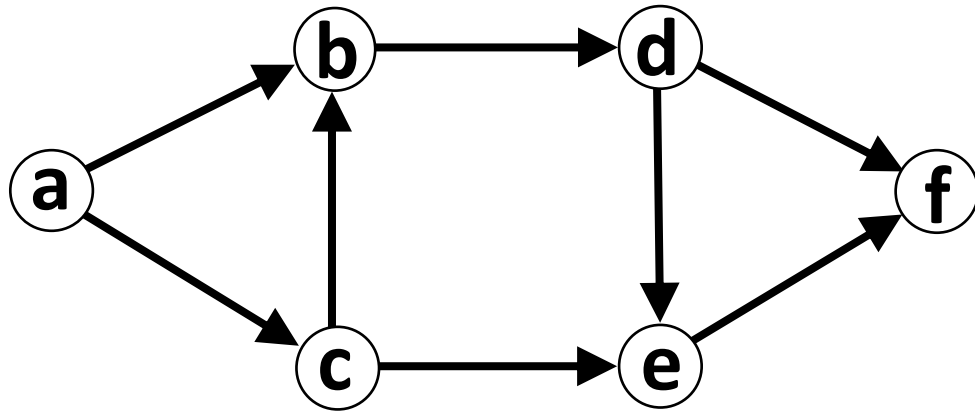
The red house and the green house are the fewest stops you need to get 20+ pounds of candy.

**A problem exhibits optimal substructure if removing part of an optimal solution results in an optimal solution to a smaller problem.**

Central tenant of Dynamic Programming: Leverage optimal sub-structure.

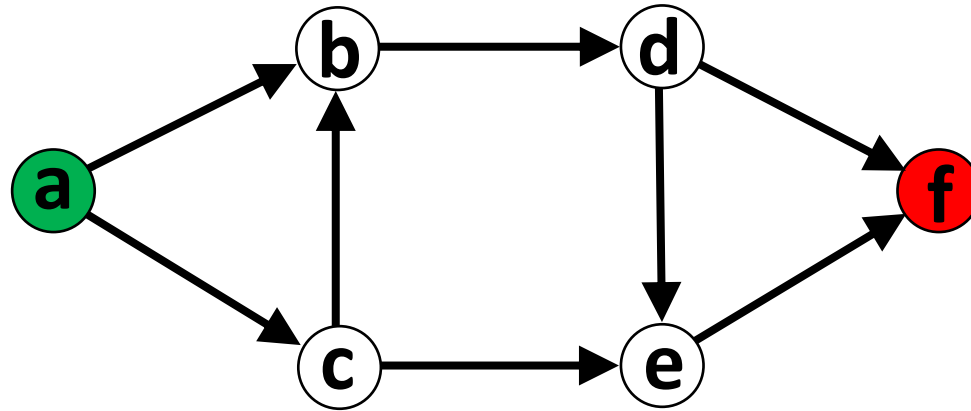
# Directed Acyclic Graph (DAG)

Directed Acyclic Graph (DAG) = Directed graph with no cycles.



# Longest Path in a DAG

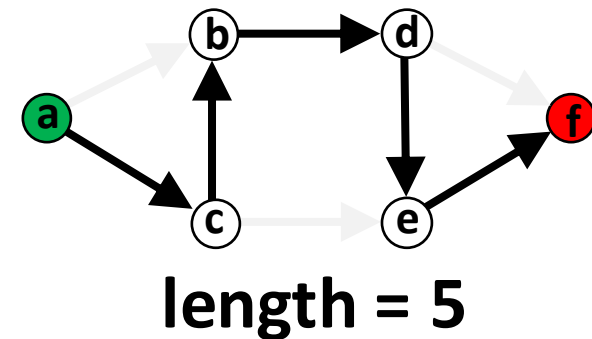
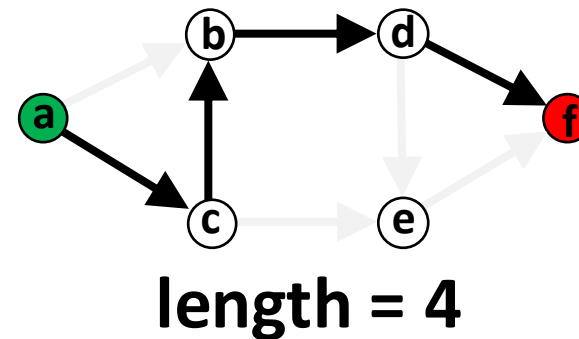
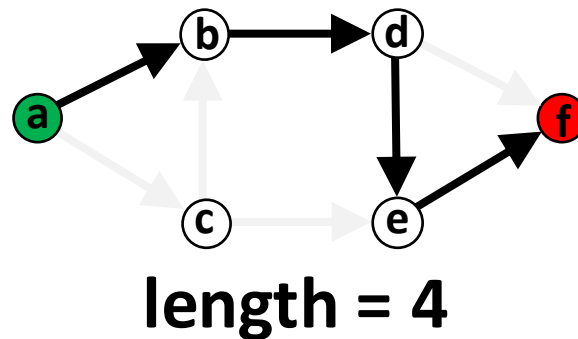
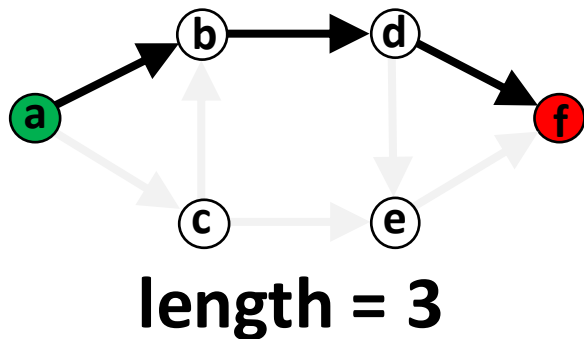
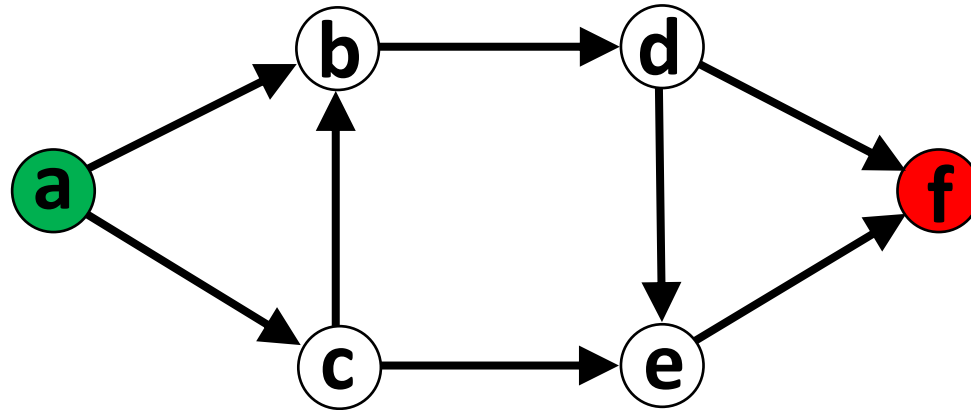
Given a DAG, find the longest path between any two vertices in the graph.





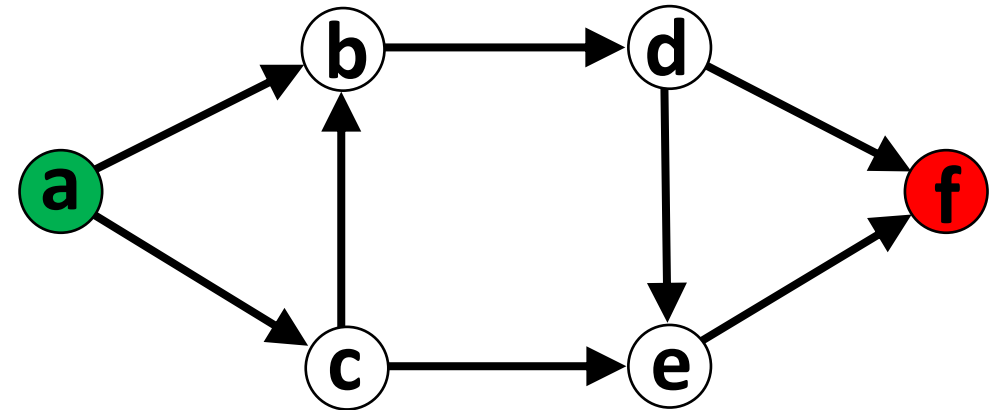
# Longest Path in a DAG

Given a DAG, find the longest path between any two vertices in the graph.



# Find the Longest Path in a DAG

Task	Description	Duration
a	Select location	2 days
b	Get permits	4 days
c	Select date/time	1 day
d	Hire vendors	2 days
e	Make flyers	1 day
f	Market event	1 day

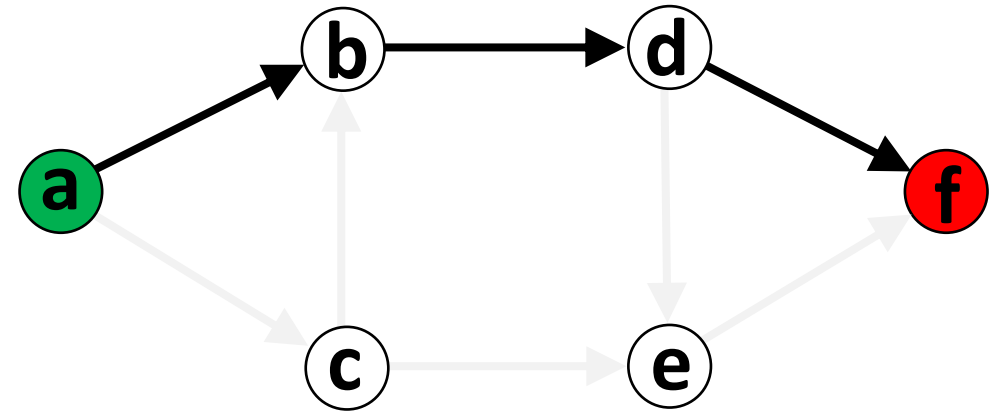


Critical Path: Sequence of dependent tasks that determines the minimum time to complete project.

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Length = 2 + 4 + 2 + 1 = 9 days

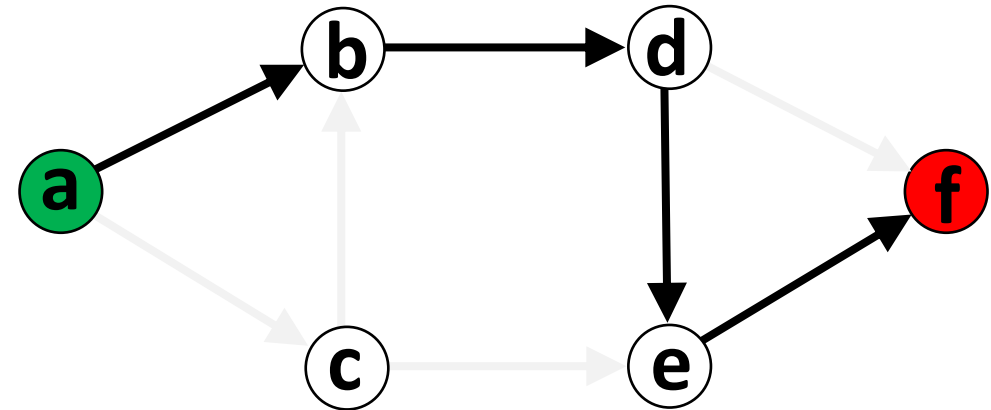


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e	Make flyers	1 day
f	Market event	1 day

Length = 2 + 4 + 2 + 1 + 1 = 10 days

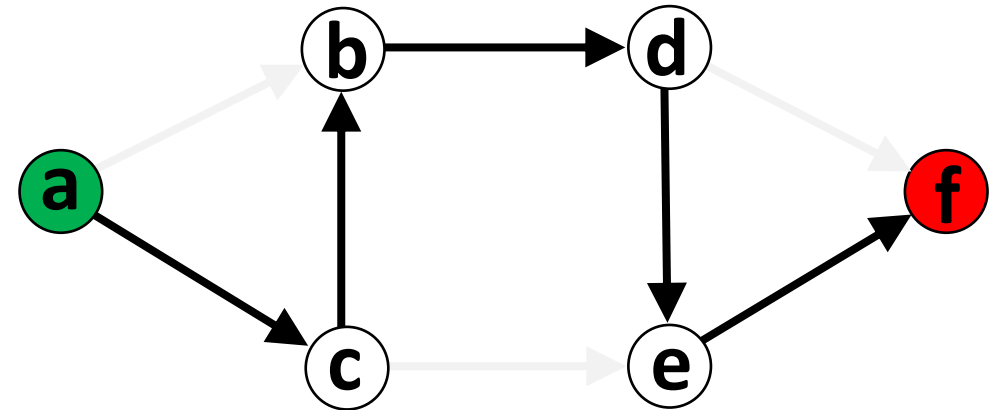


Critical Path: Sequence of dependent tasks that determines the minimum time to complete project.

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f	Market event	1 day

**Length = 2 + 1 + 4 + 2 + 1 + 1 = 11 days**

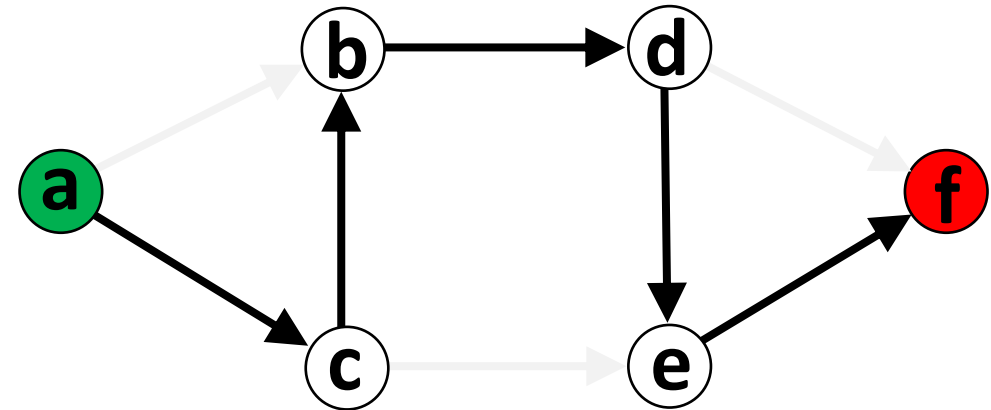


**Critical Path:** Sequence of dependent tasks that determines the minimum time to complete project.

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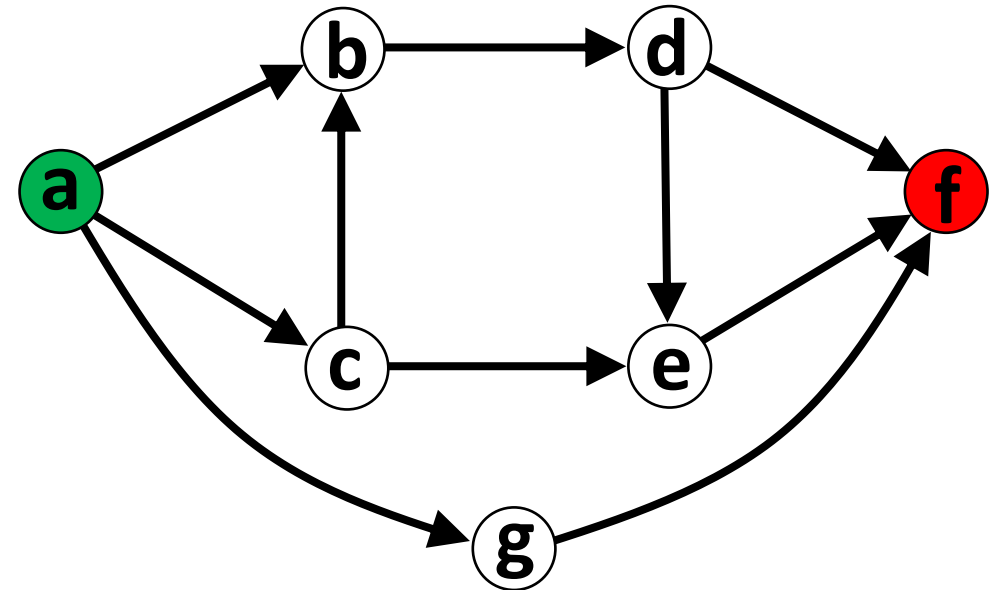


Critical Path: Sequence of dependent tasks that determines the minimum time to complete project.

**If any task on critical path is delayed, project is delayed.**

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a	Select location	2 days
b	Get permits	4 days
c	Select date/time	1 day
d	Hire vendors	2 days
e	Make flyers	1 day
f	Market event	1 day
g	Photograph venue	1 day



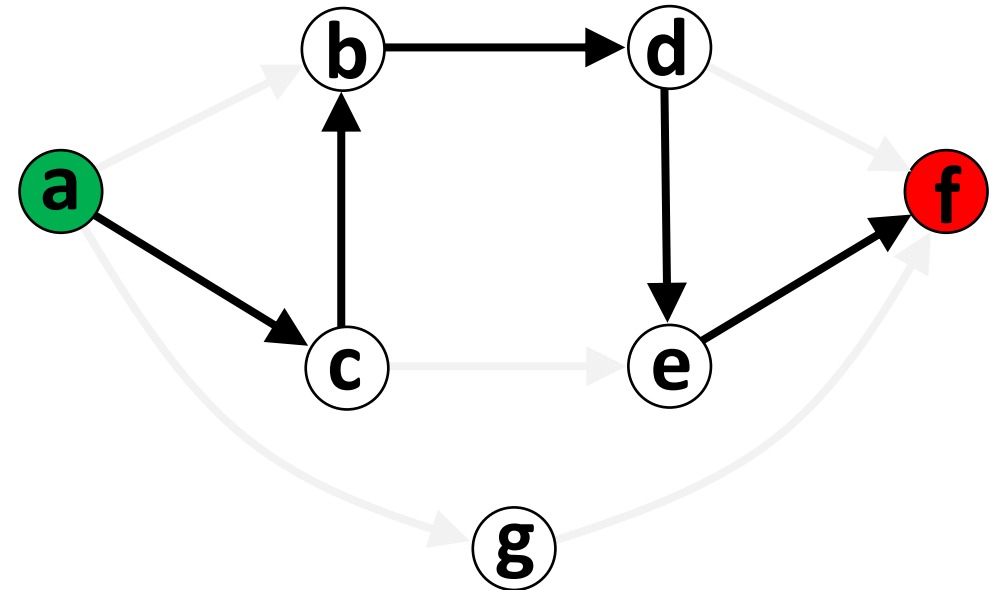
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**Length = 2 + 1 + 4 + 2 + 1 + 1 = 11 days**



Critical Path: Sequence of dependent tasks that determines the minimum time to complete project.

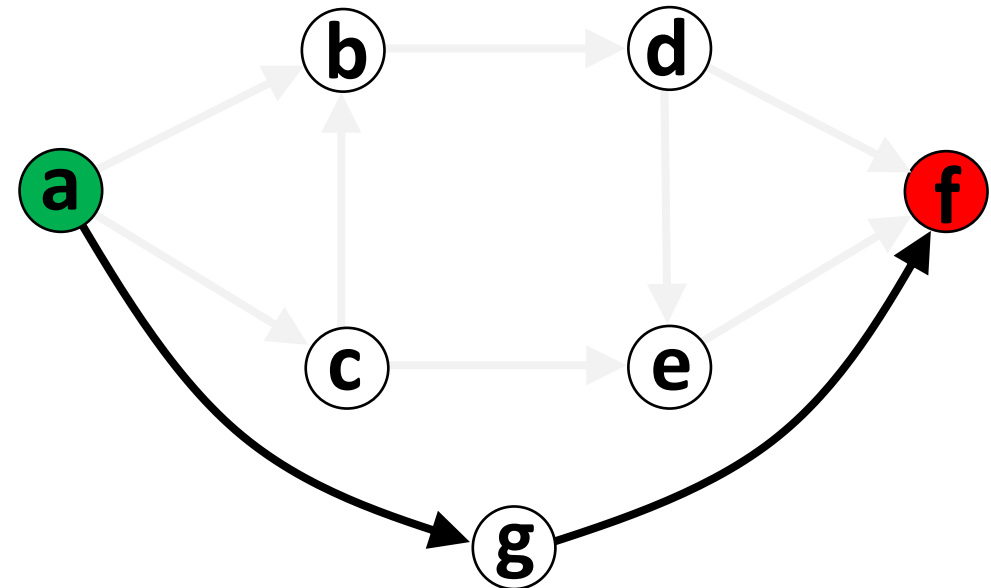
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a	Select location	2 days
b	Get permits	4 days
c	Select date/time	1 day
d	Hire vendors	2 days
e	Make flyers	1 day
f	Market event	1 day
g	Photograph venue	<b>10 days</b>

**Length = 2 + 10 + 1 = 13 days**



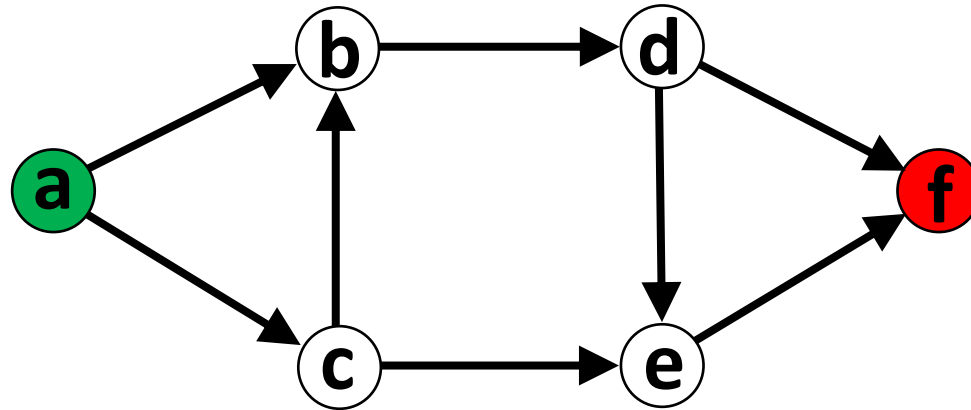
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# Find the Longest Path in a DAG

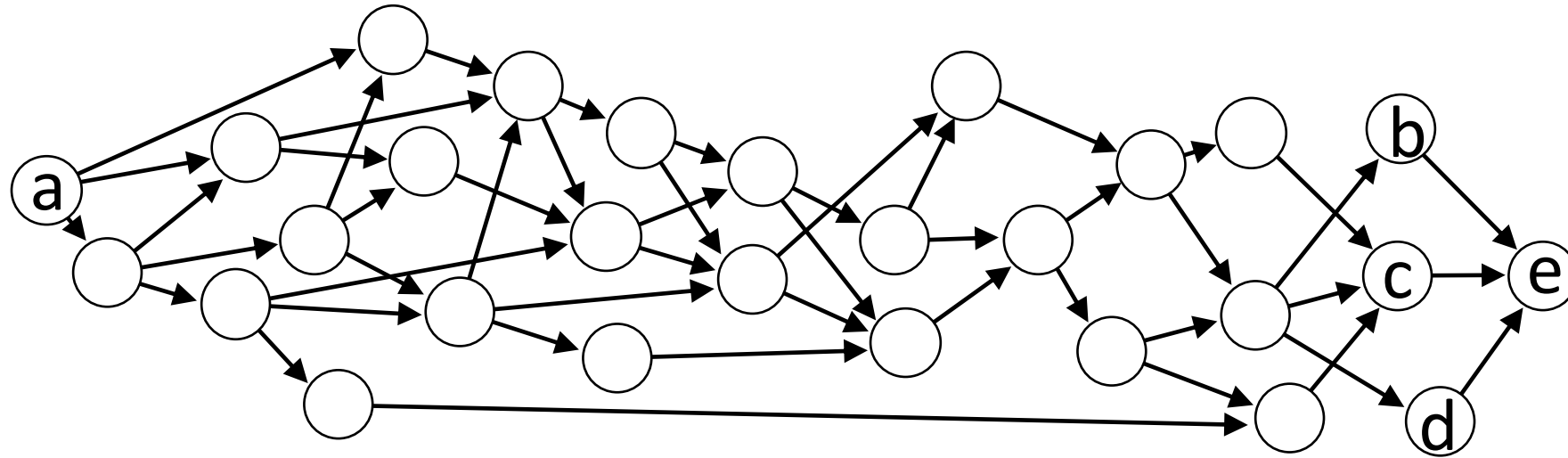
Number of edges.  
No vertex weights.

Given a DAG, find the longest path between any two vertices in the graph.



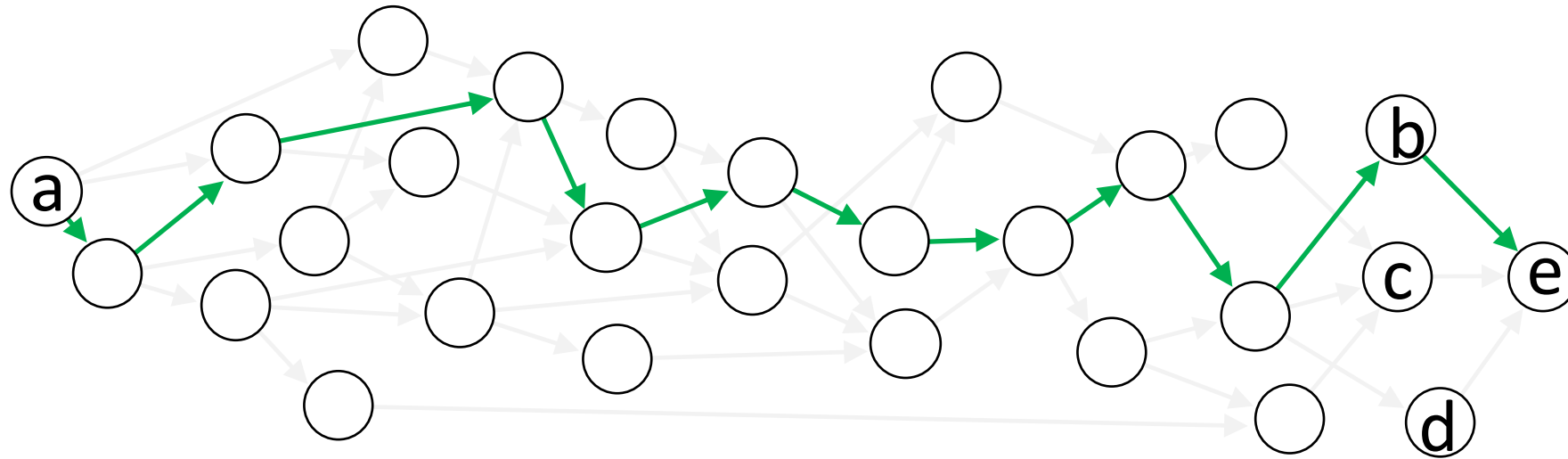
How do we do this?

# Find the Longest Path in a DAG



Interesting observations?

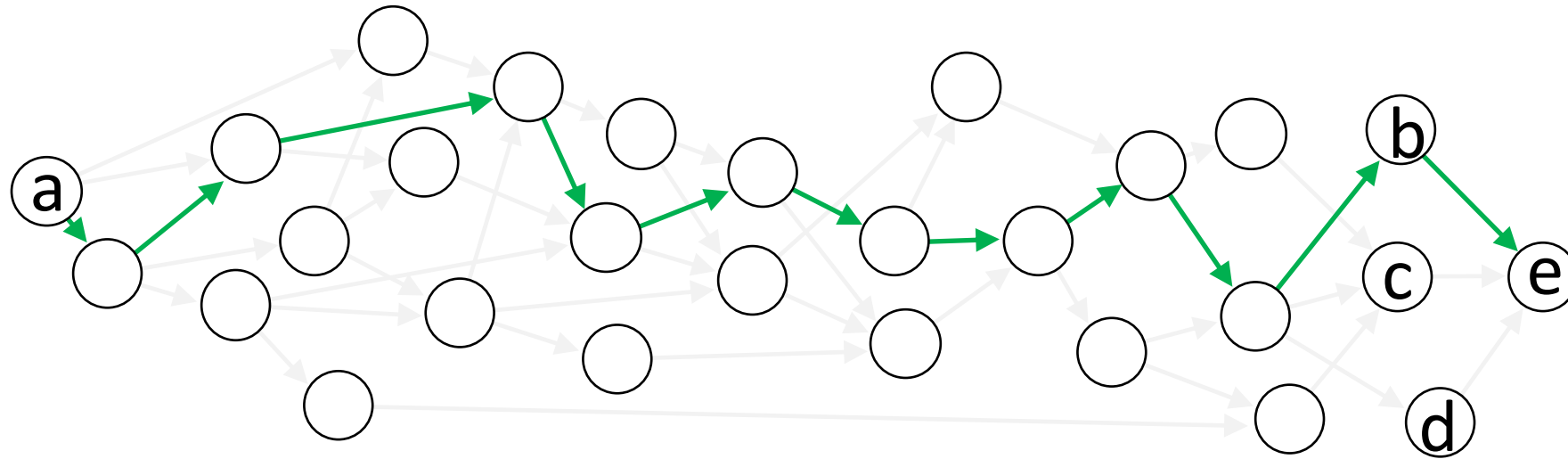
# Find the Longest Path in a DAG



Interesting observations?

If the longest path goes from **a** to **e** and passes through **b**, what could we say about the part of that path to **b**?

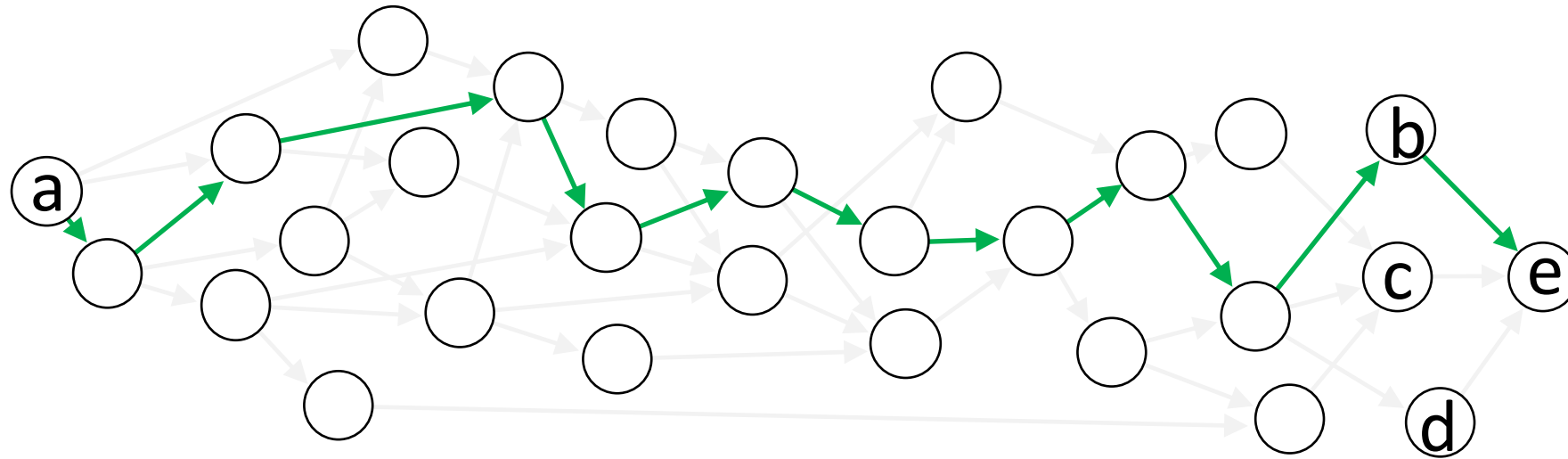
# Find the Longest Path in a DAG



Interesting observations?

If the longest path goes from **a** to **e** and passes through **b**, that must be the longest path that ends at **b**.

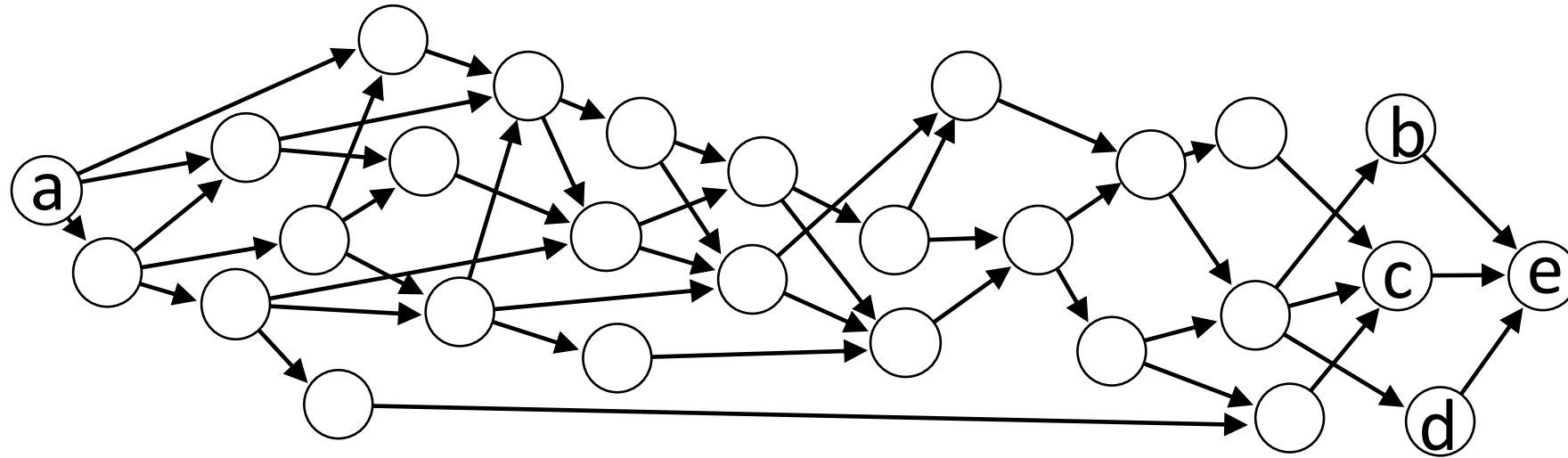
# Find the Longest Path in a DAG



Interesting observations?

If the longest path goes from **a** to **e** and passes through **b**, that must be the longest path that ends at **b**. If not, then we could make a longer path.

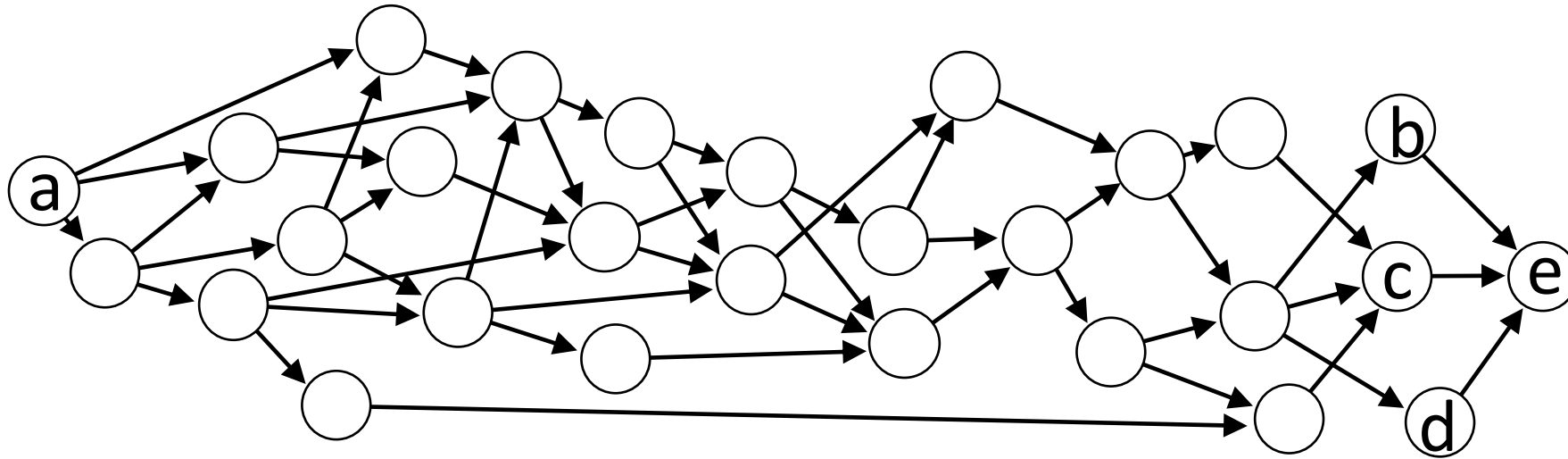
# Find the Longest Path in a DAG



Interesting observations?

The longest path to e = ??

# Find the Longest Path in a DAG

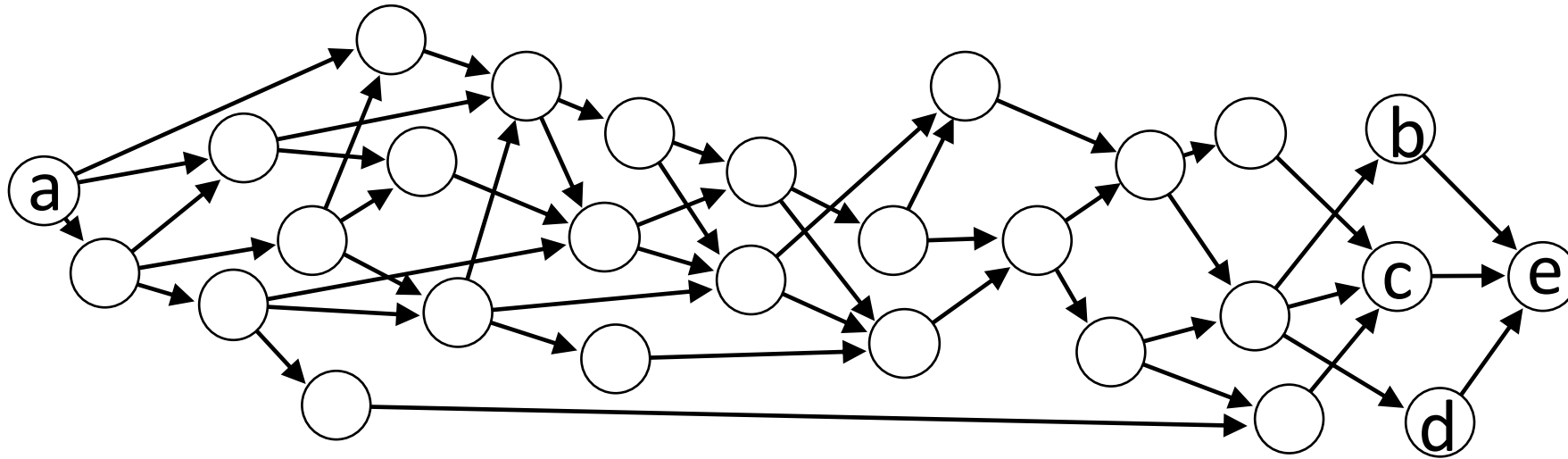


Interesting observations?

$$\text{The longest path to } e = \max \begin{pmatrix} \text{longest path to } b \\ \text{longest path to } c \\ \text{longest path to } d \end{pmatrix} + 1$$

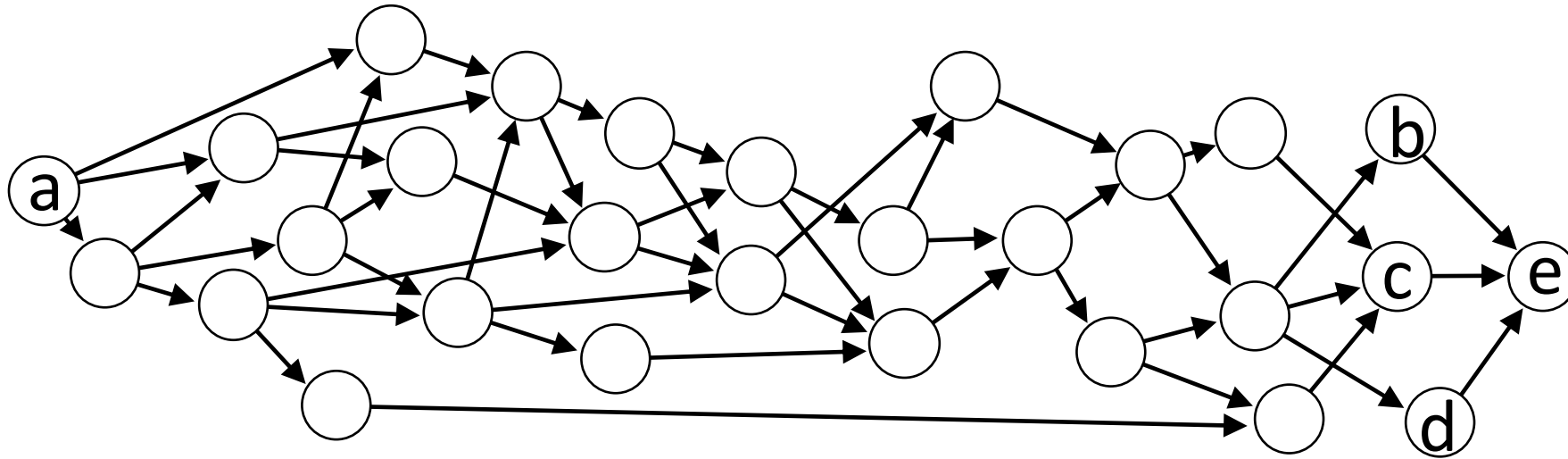


# Find the Longest Path in a DAG



$$\text{longest path to e} = \max \begin{pmatrix} \text{longest path to b} \\ \text{longest path to c} \\ \text{longest path to d} \end{pmatrix} + 1$$

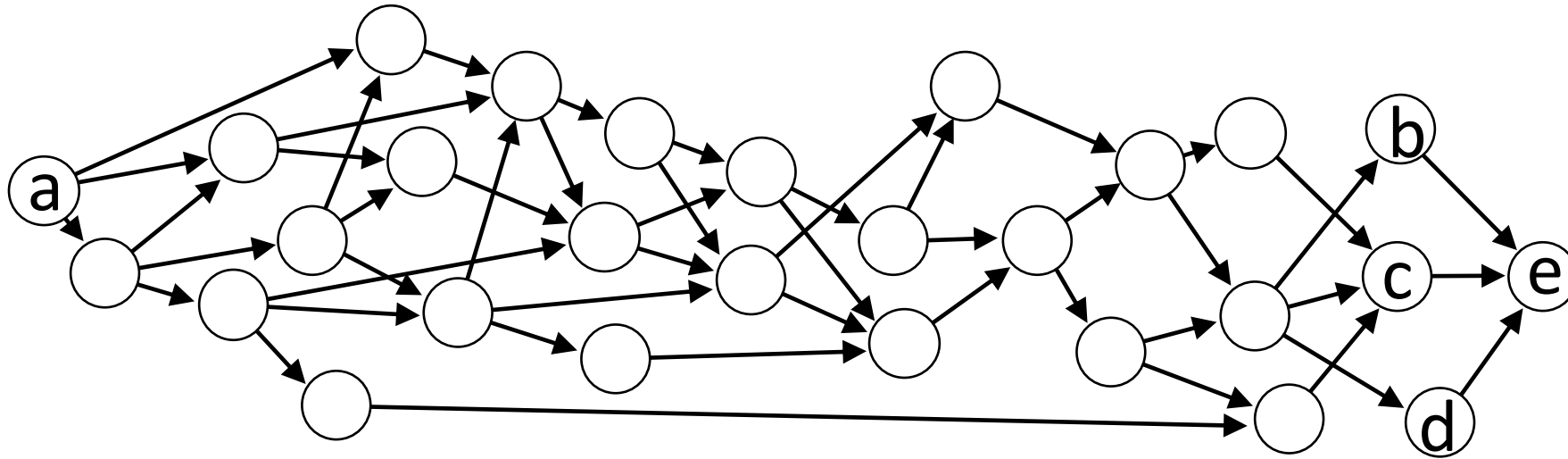
# Find the Longest Path in a DAG



When are we ready to calculate the longest path to e?

$$\text{longest path to e} = \max \begin{pmatrix} \text{longest path to b} \\ \text{longest path to c} \\ \text{longest path to d} \end{pmatrix} + 1$$

# Find the Longest Path in a DAG

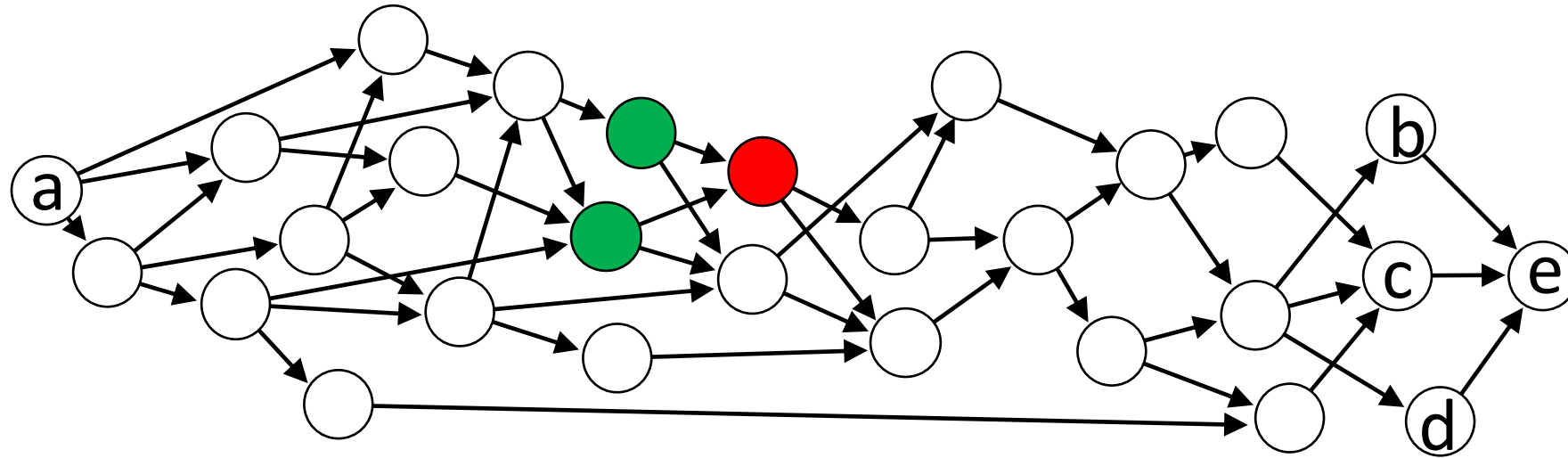


When are we ready to calculate the longest path to e?

When we have the longest paths to b, c, and d.

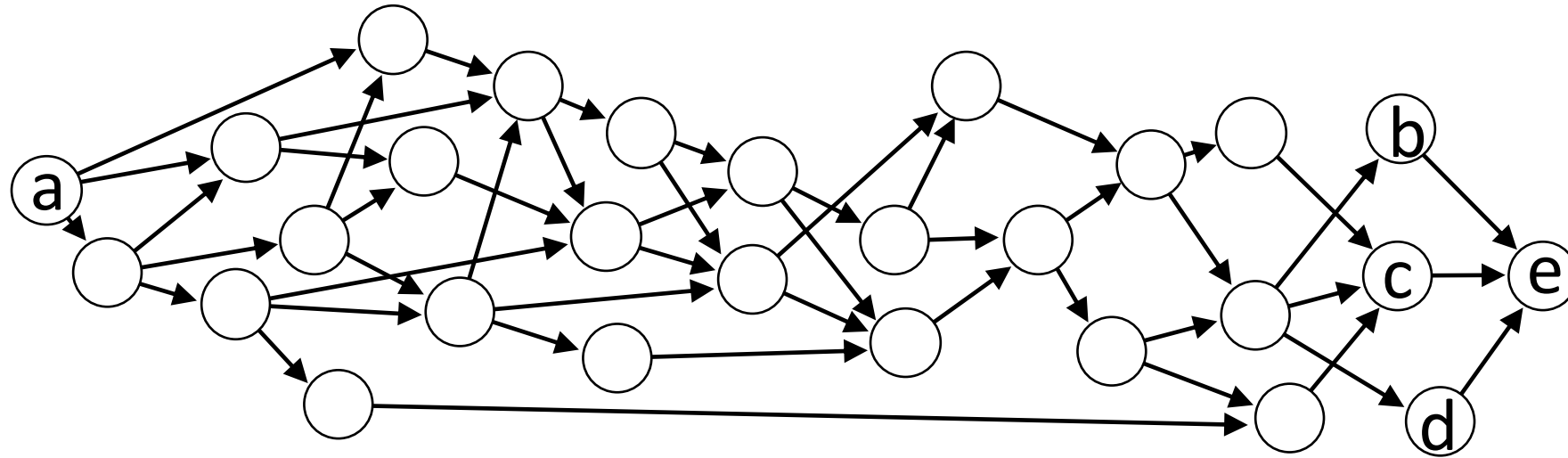
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# Find the Longest Path in a DAG



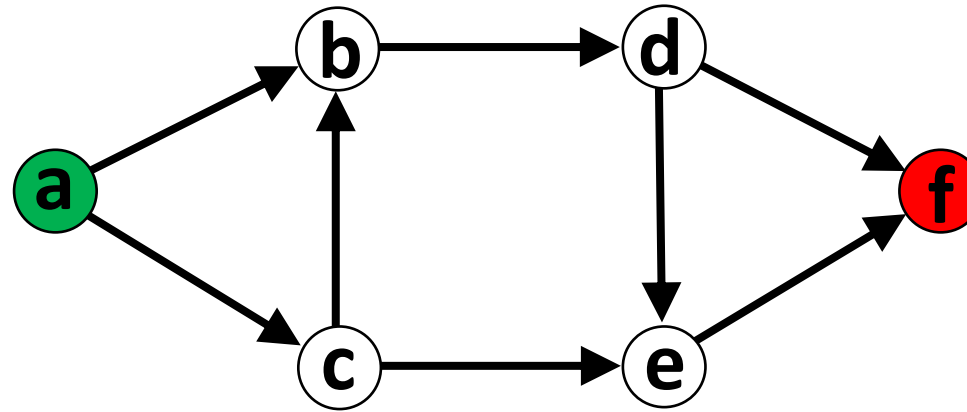
In general: We are ready to calculate the longest path to a vertex if we know the longest path for all incoming neighbors.

# Find the Longest Path in a DAG



Topological Ordering of a graph: ordering of its vertices such that for every directed edge  $(u, v)$ , vertex  $u$  comes before vertex  $v$  in the ordering.

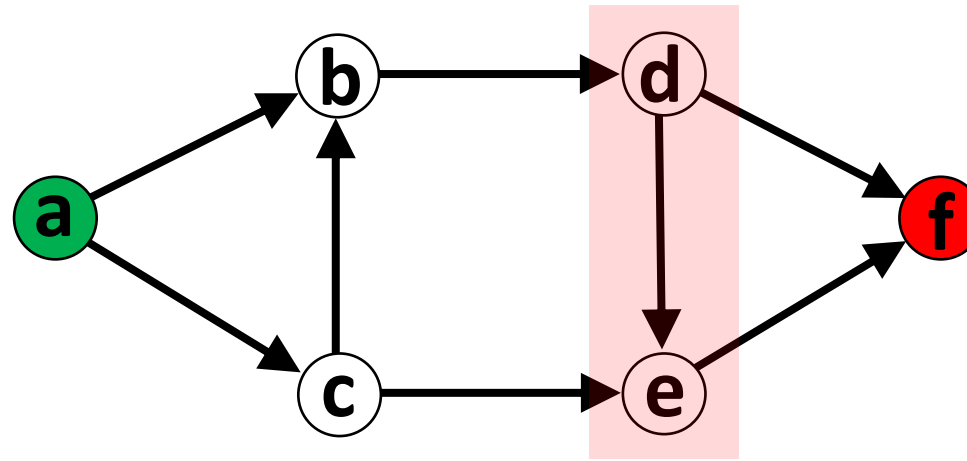
# Topological Ordering



Topologically Ordered:

{a, c, b, d, e, f} ✓

# Topological Ordering

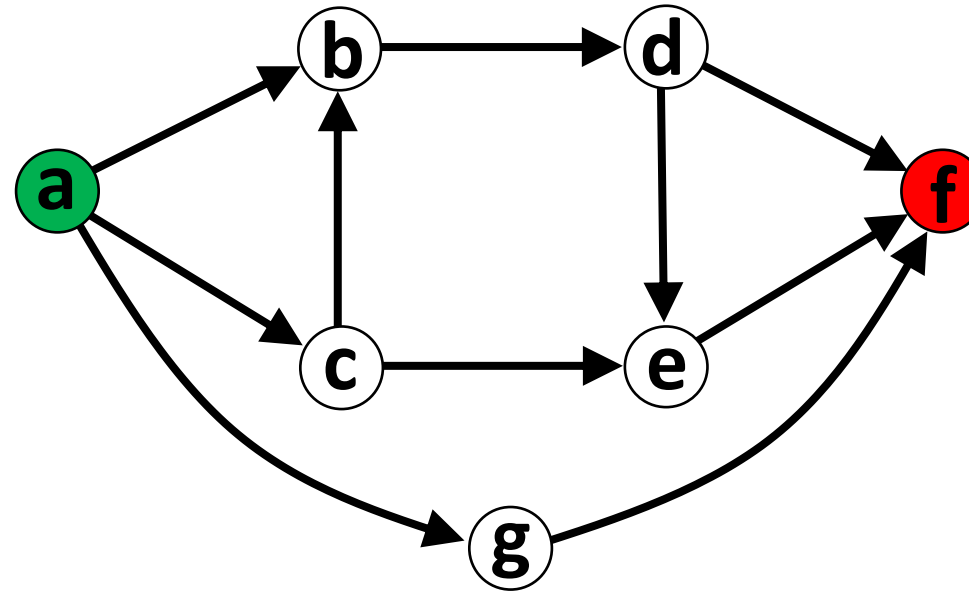


Topologically Ordered:

{a, c, b, d, e, f} ✓

{a, c, b, e, d, f} ✗

# Topological Ordering



Topologically Ordered:

{a, c, g, b, d, e, f}

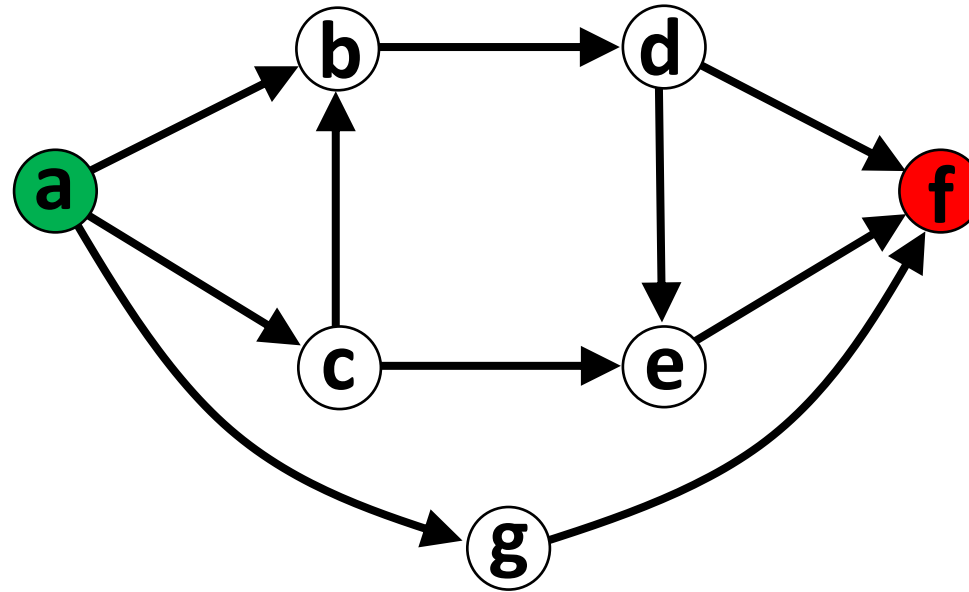


{a, c, b, d, e, g, f}





# Topological Ordering

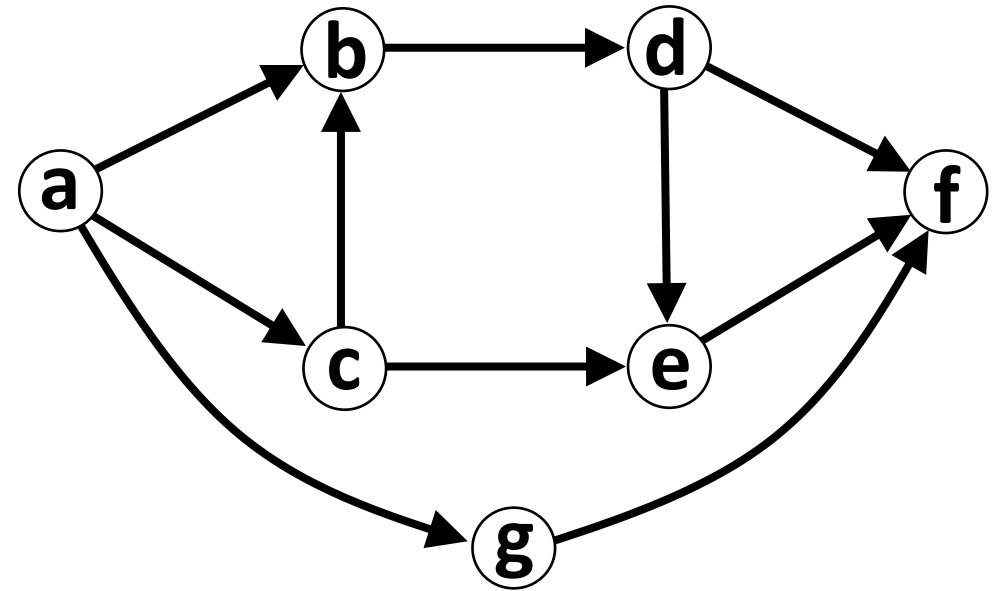


- There are various algorithms to find topological orderings
- Standard running time =  $O(|V| + |E|)$ .

# Find the Longest Path in a DAG

Plan:

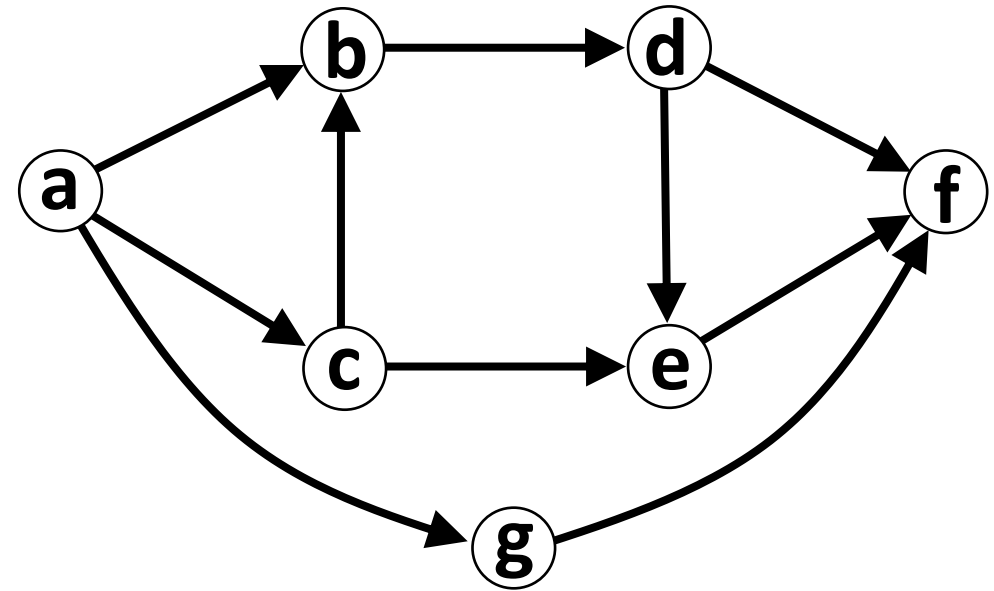
- ??



# Find the Longest Path in a DAG

Plan:

- Topologically sort vertices.

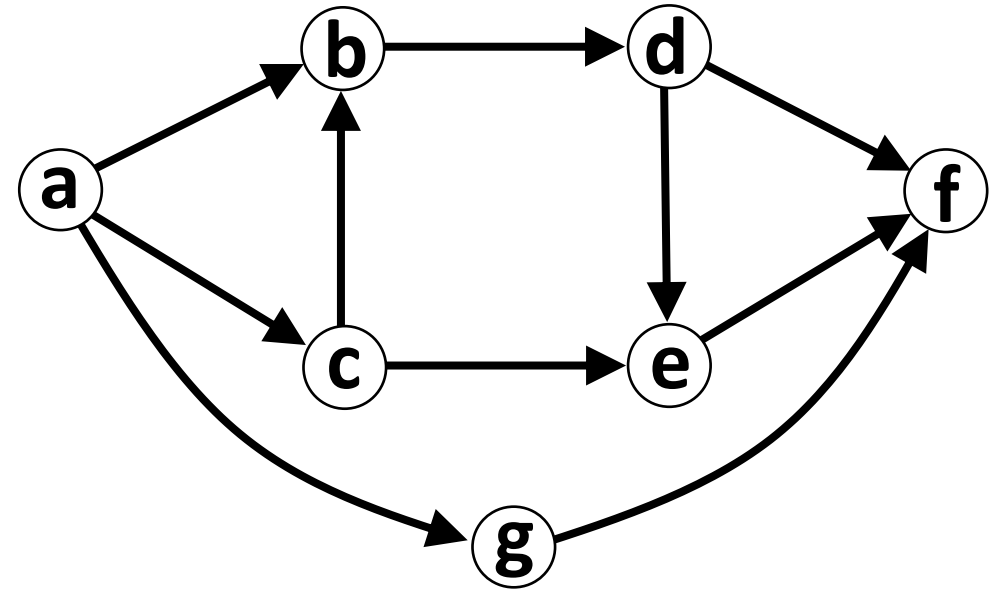


{a, c, g, b, d, e, f}

# Find the Longest Path in a DAG

Plan:

- Topologically sort vertices.
- Make array to store length of longest path that ends at each vertex.



{a, c, g, b, d, e, f}

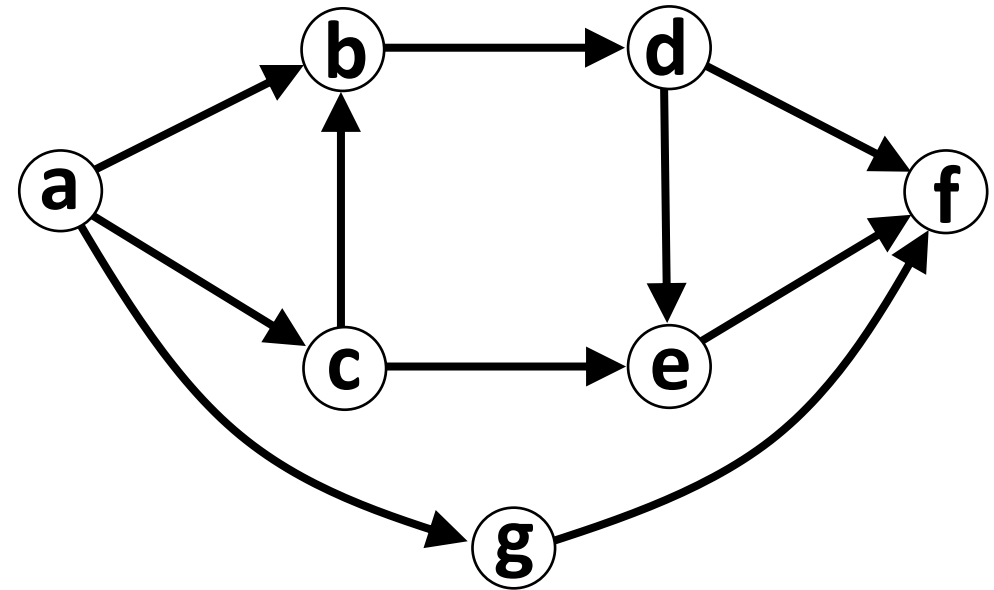
a	b	c	d	e	f	g
0	0	0	0	0	0	0

Length of longest  
path that ends at c.

# Find the Longest Path in a DAG

Plan:

- Topologically sort vertices.
- Make array to store length of longest path that ends at each vertex.
- For each vertex in order, calculate longest path as:  
$$\max_n (\text{longest path to } n) + 1,$$
  
for all incoming neighbors  $n$ .  
(Or 0 if there are no incoming neighbors)



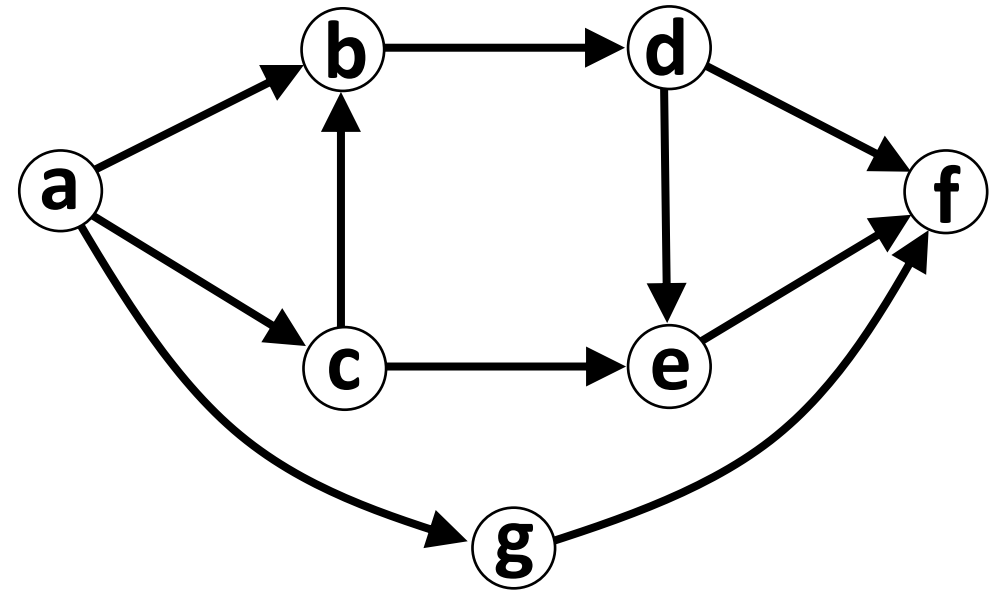
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	0	0	0	0	0

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0	0	0	0	0	0	0

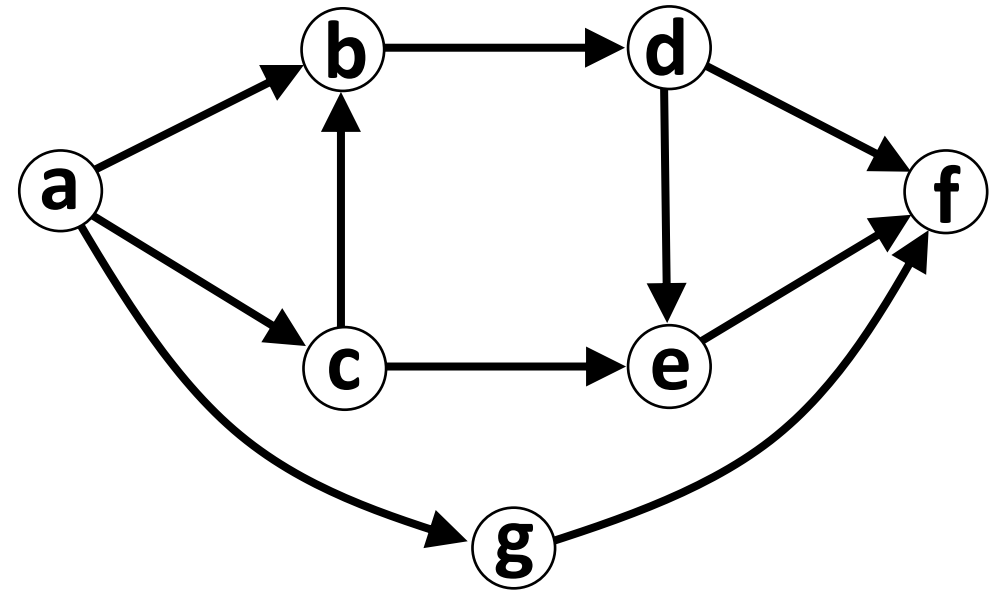
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{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	0	0	0	0	0

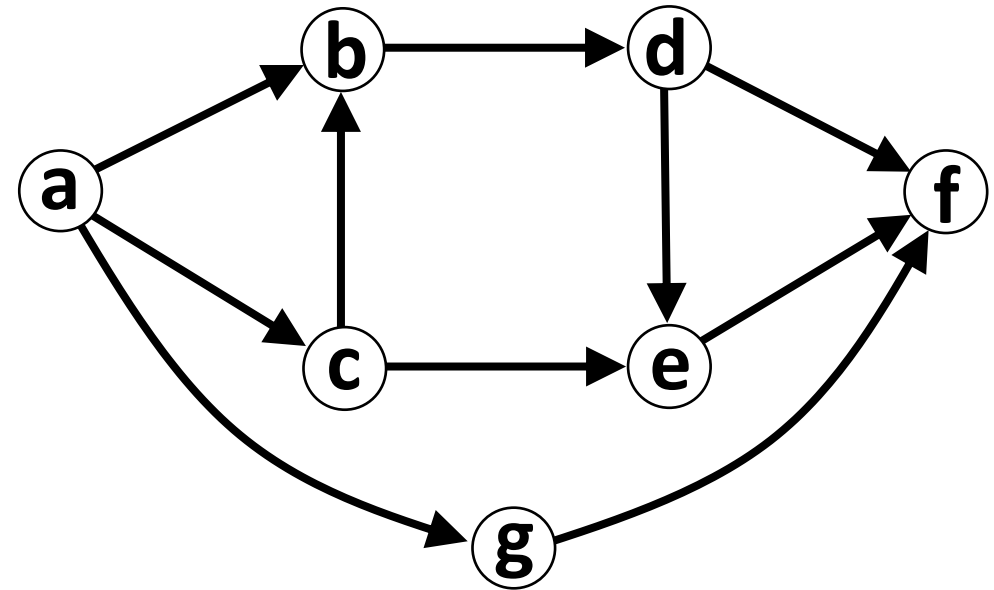
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{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	1	0	0	0	0



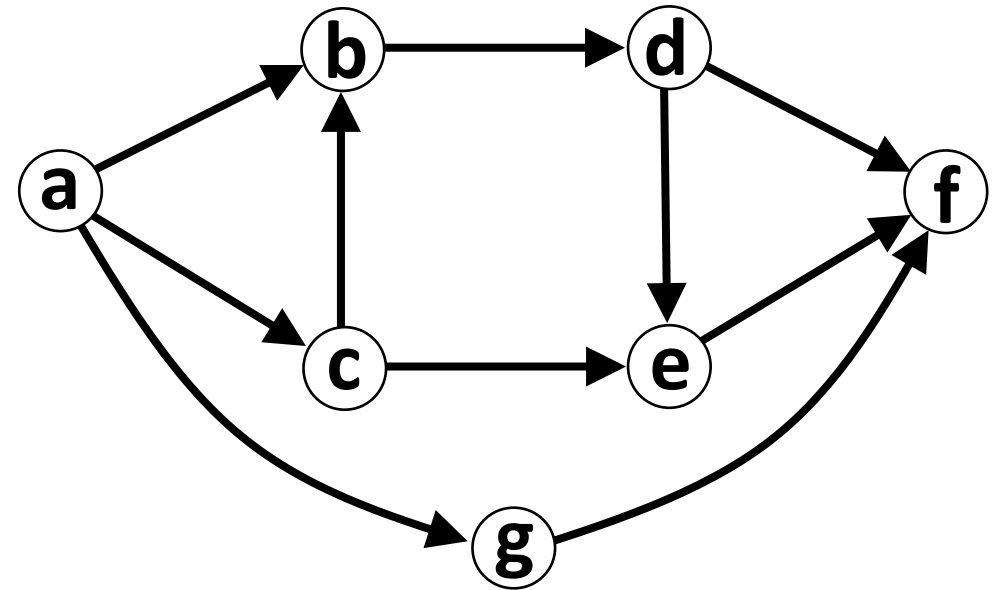
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{a, c, g, b, d, e, f}

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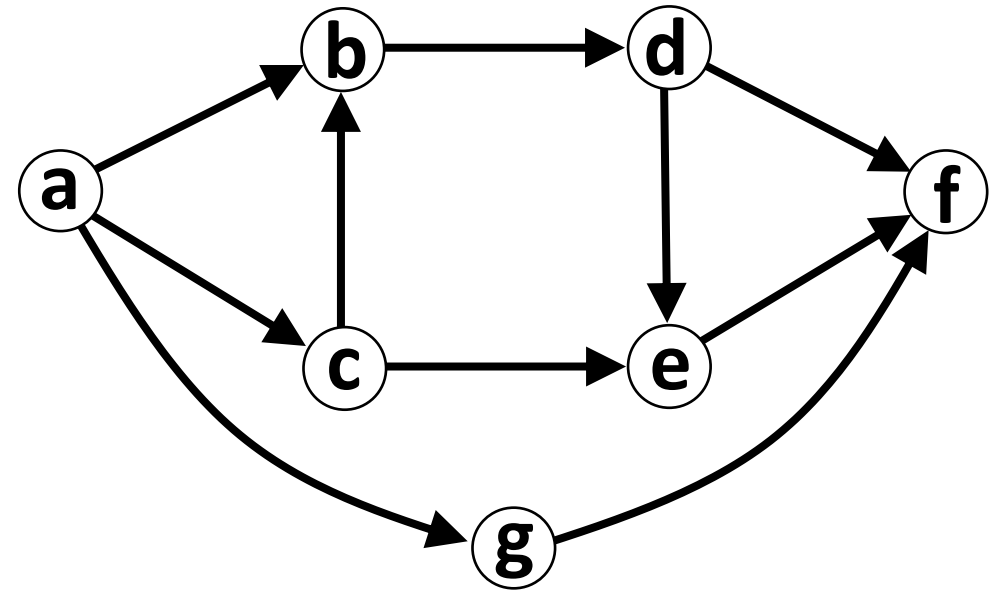
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{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	1	0	0	0	1

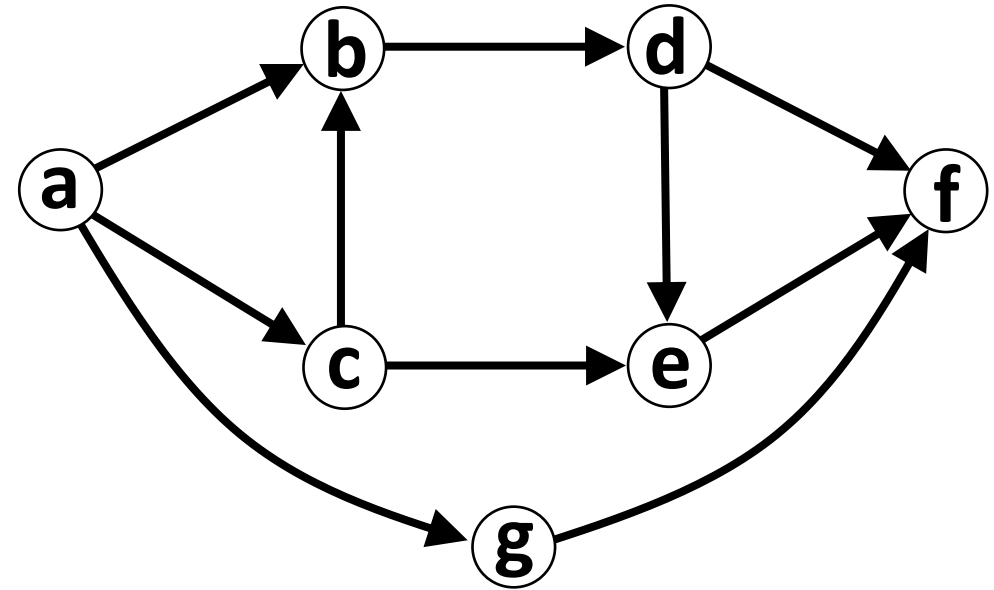
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{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	1	0	0	0	1

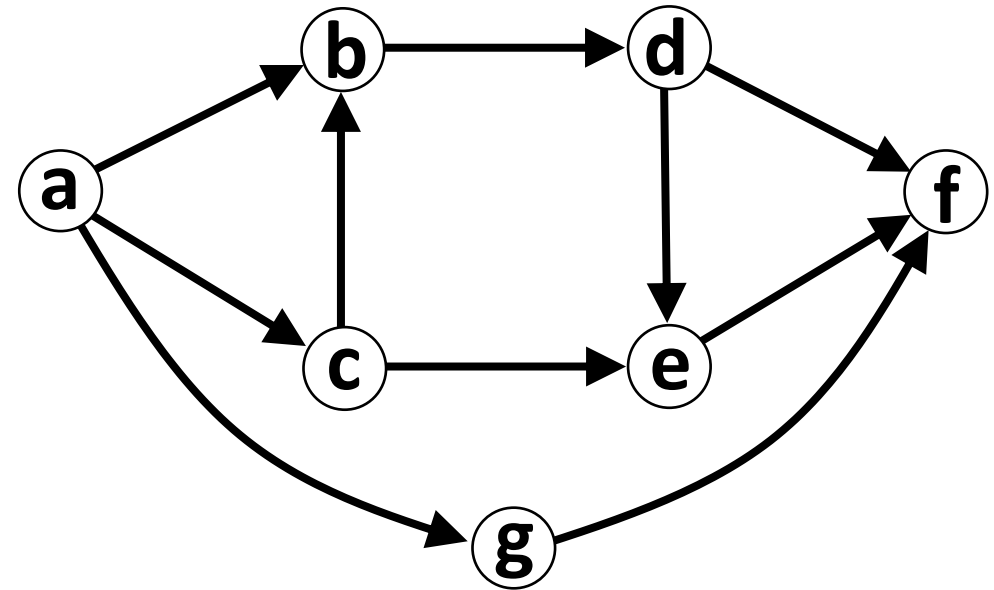
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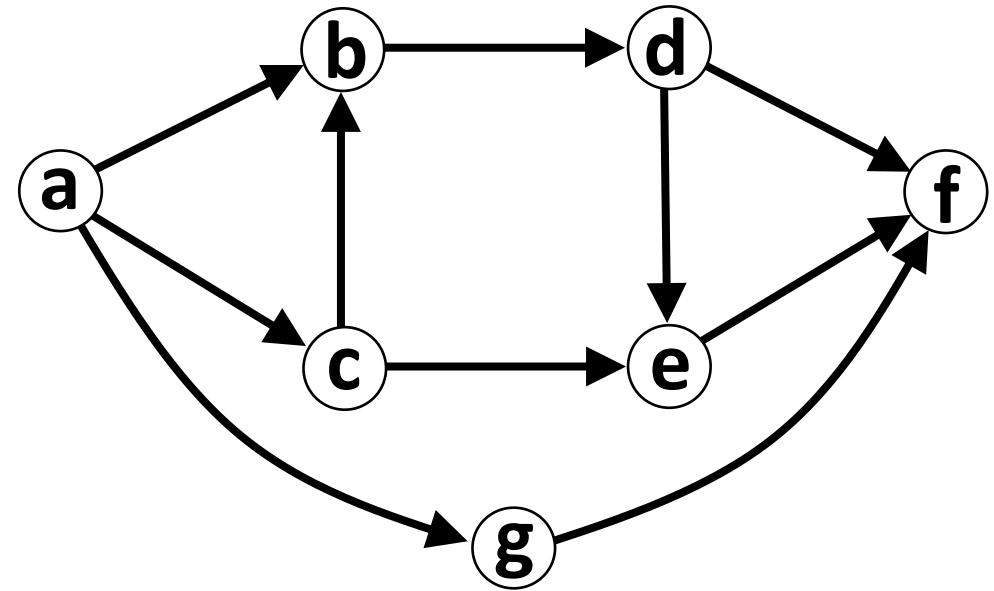
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	0	0	0	1

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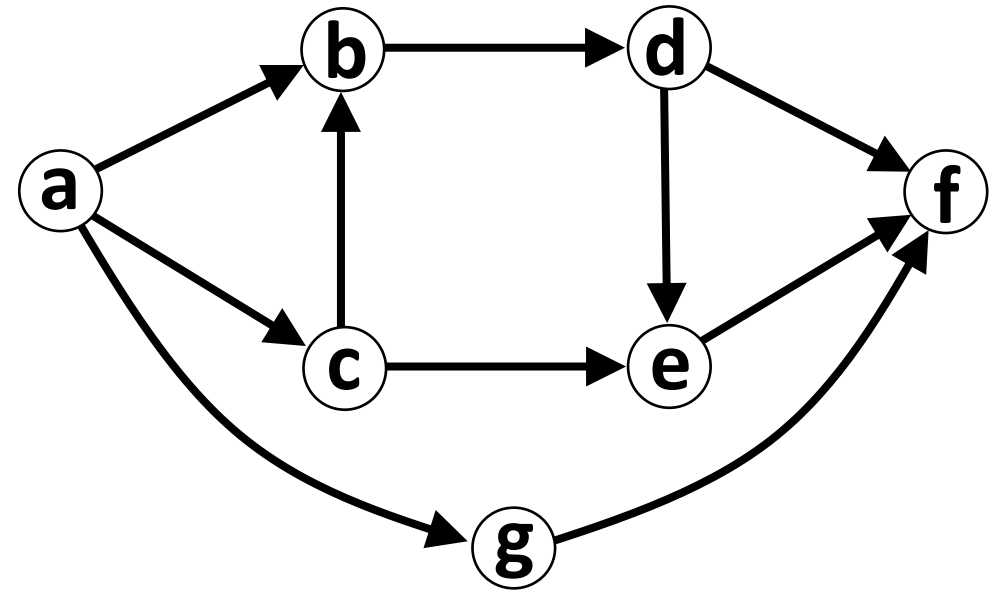
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1

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Plan:

- Topologically sort vertices.
- Make array to store length of longest path that ends at each vertex.
- For each vertex in order, calculate longest path as:  
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for all incoming neighbors  $n$ .
- Largest value in array = Longest path.



{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1

# Find the Longest Path in a DAG

```
longest_path(G=(V, E)):  
    pathLengths = [0, ..., 0]  
    Let  $V_{\text{sort}}$  be topologically sort vertices  
    for each vertex  $v$  in  $V_{\text{sort}}$ :  
        for each incoming neighbor  $n$  of  $v$ :  
            if pathLengths[n] + 1 > pathLengths[v]:  
                pathLengths[v] = pathLengths[n] + 1  
    return maxVal(pathLengths)
```

**Running time: ?**

# Find the Longest Path in a DAG

```
longest_path(G=(V, E)):  
    pathLengths = [0, ..., 0]  
    Let  $V_{\text{sort}}$  be topologically sort vertices  
    for each vertex  $v$  in  $V_{\text{sort}}$ :  
        for each incoming neighbor  $n$  of  $v$ :  
            if  $\text{pathLengths}[n] + 1 > \text{pathLengths}[v]$ :  
                 $\text{pathLengths}[v] = \text{pathLengths}[n] + 1$   
    return maxValue(pathLengths)
```

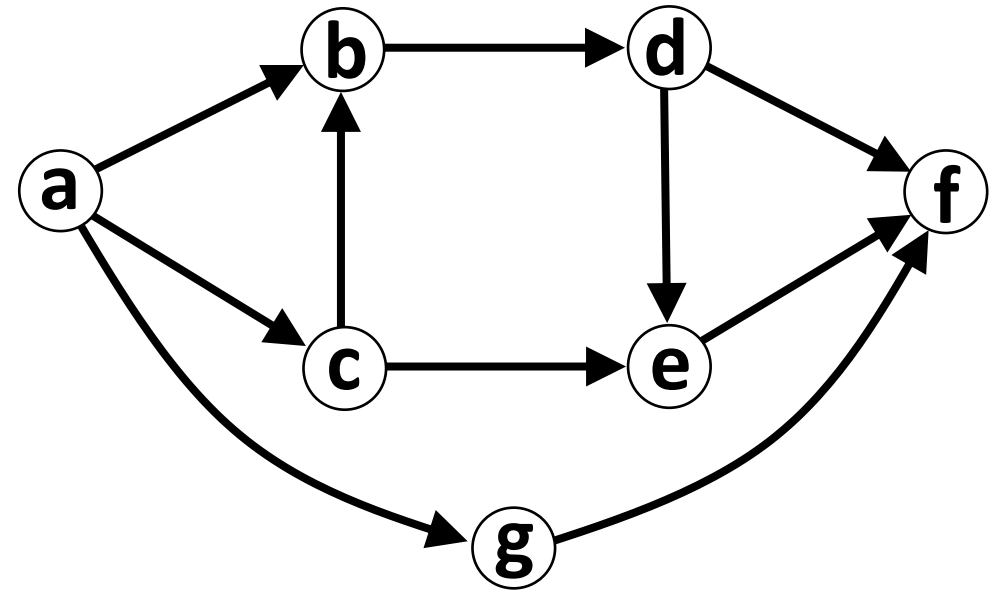
**Running time:  $O(\text{Topological Sort} + |V|^2) \in O(|V|^2)$**



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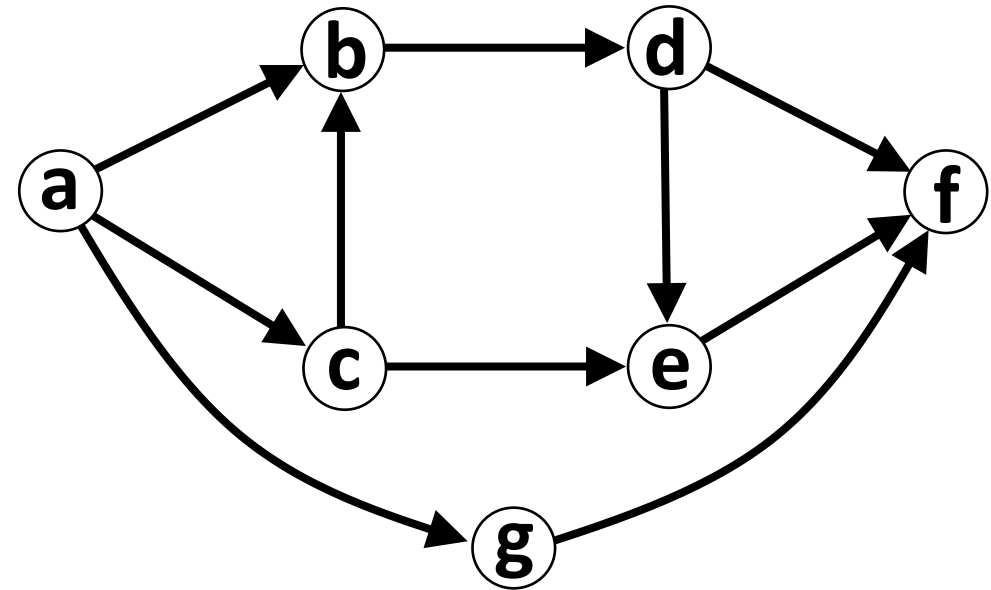
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1

# Find the Longest Path in a DAG

Plan:

- Topologically sort vertices.
- Make array to store length of longest path that ends at each vertex.
- For each vertex  $v$ , calculate longest path to  $v$  as  $\max(\text{longest path to } n) + 1$ , where  $n$  are incoming neighbors  $n$ .
- Largest value in array = Longest path.



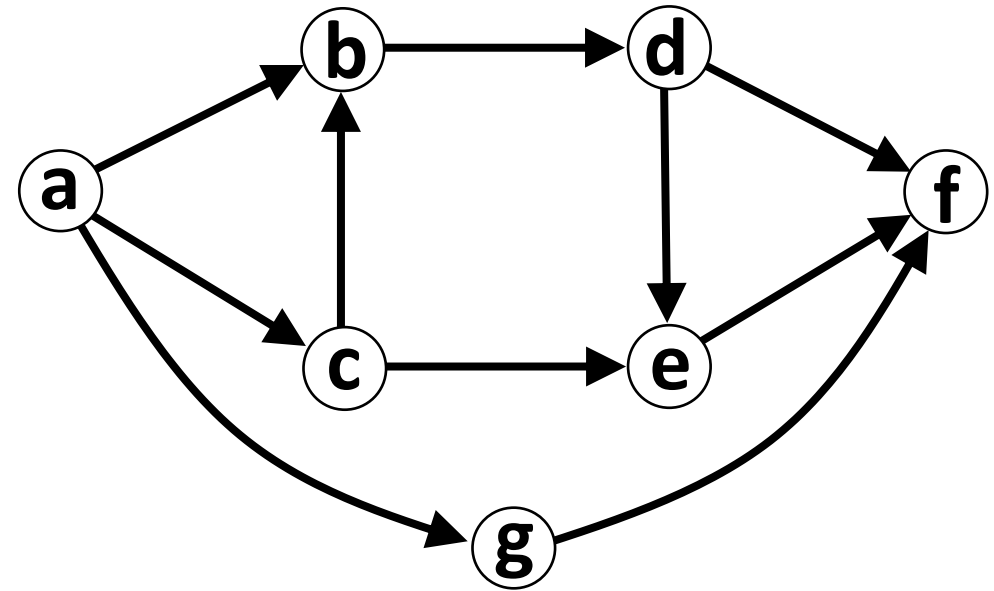
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.



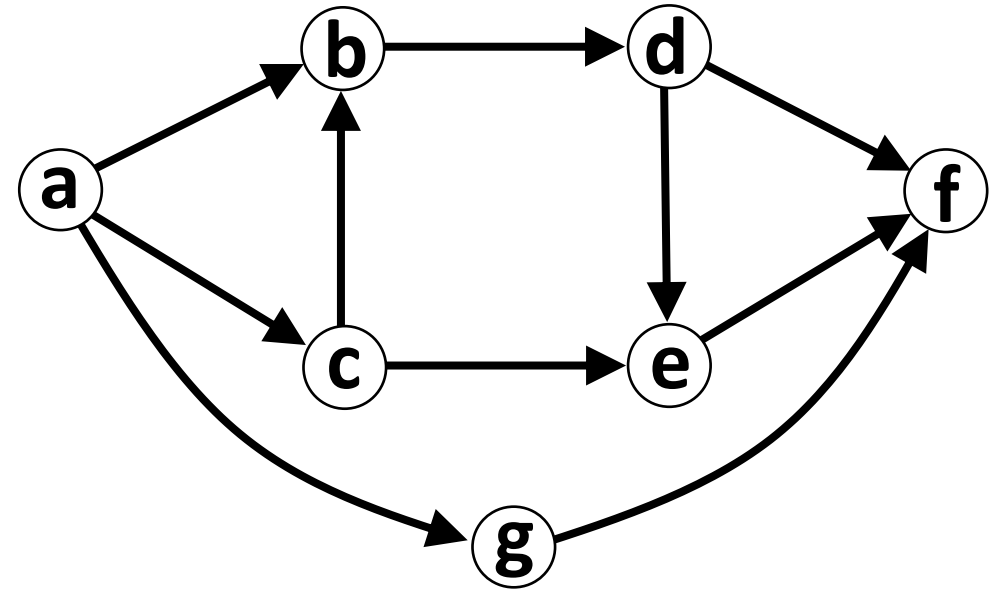
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	-	-	-	-	-	-

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.



{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	-	-	-	-	-	-

# Find the Longest Path in a DAG

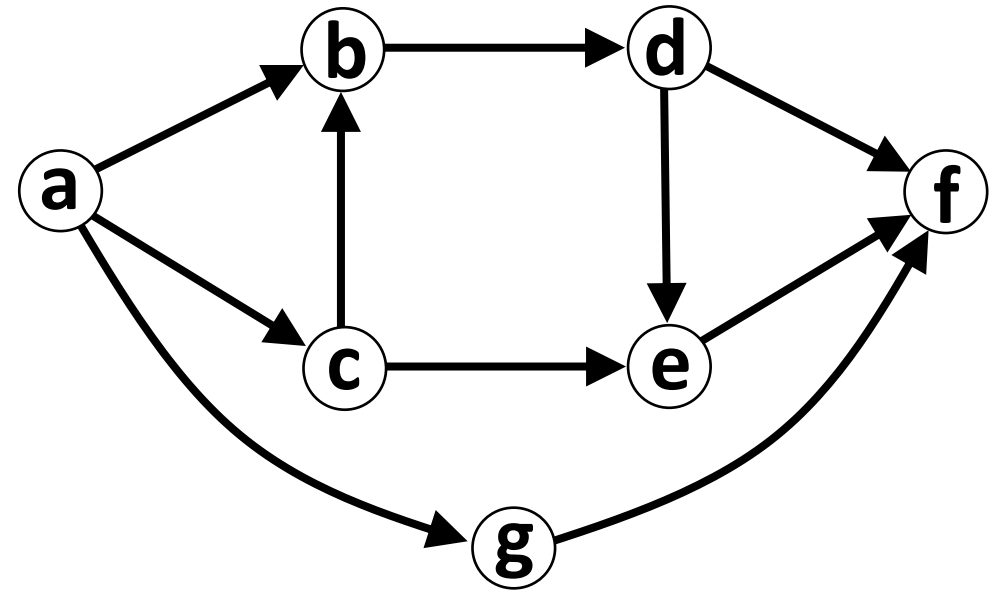
Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.

For each vertex in order, calculate longest path as:

$$\max_n (\text{longest path to } n) + 1,$$

for all incoming neighbors  $n$ .



{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	0	0	0	0	0
-	-	-	-	-	-	-

# Find the Longest Path in a DAG

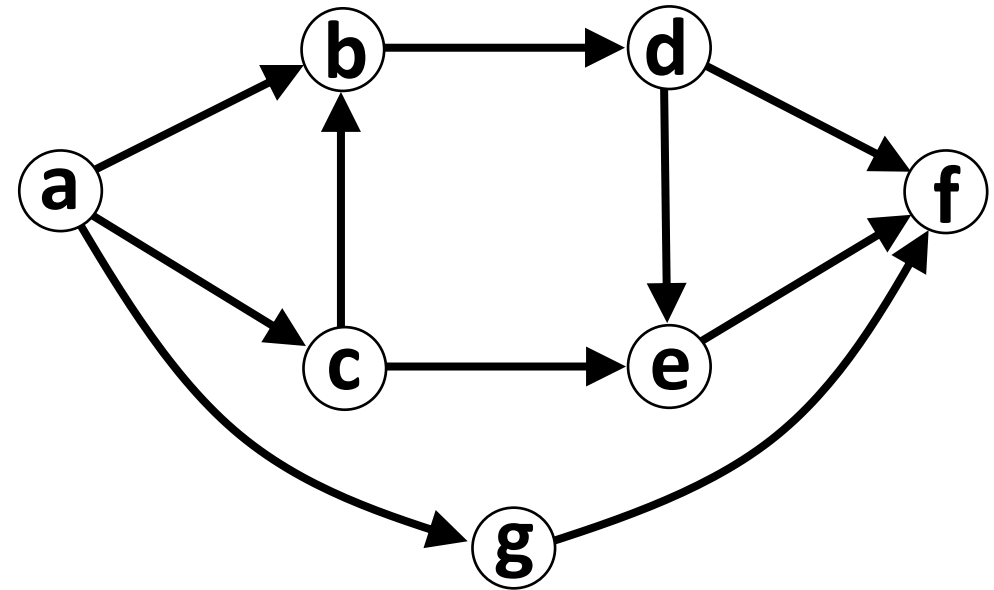
Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.

For each vertex in order, calculate longest path as:

$$\max_n (\text{longest path to } n) + 1,$$

for all incoming neighbors  $n$ .



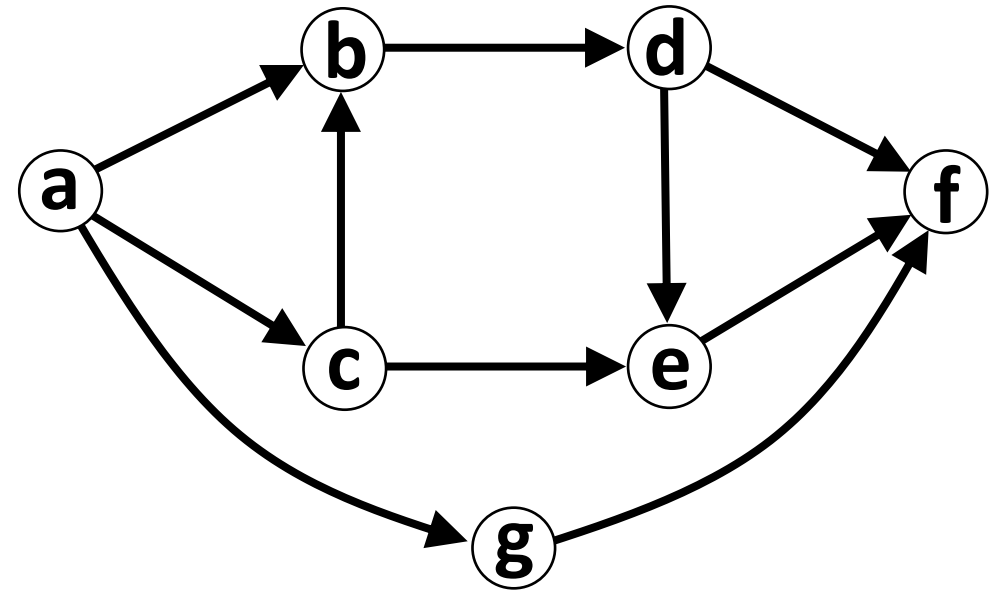
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	0	0	0	0	0
-	-	-	-	-	-	-

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.



{a, c, g, b, d, e, f}

For each vertex in order, calculate longest path as:

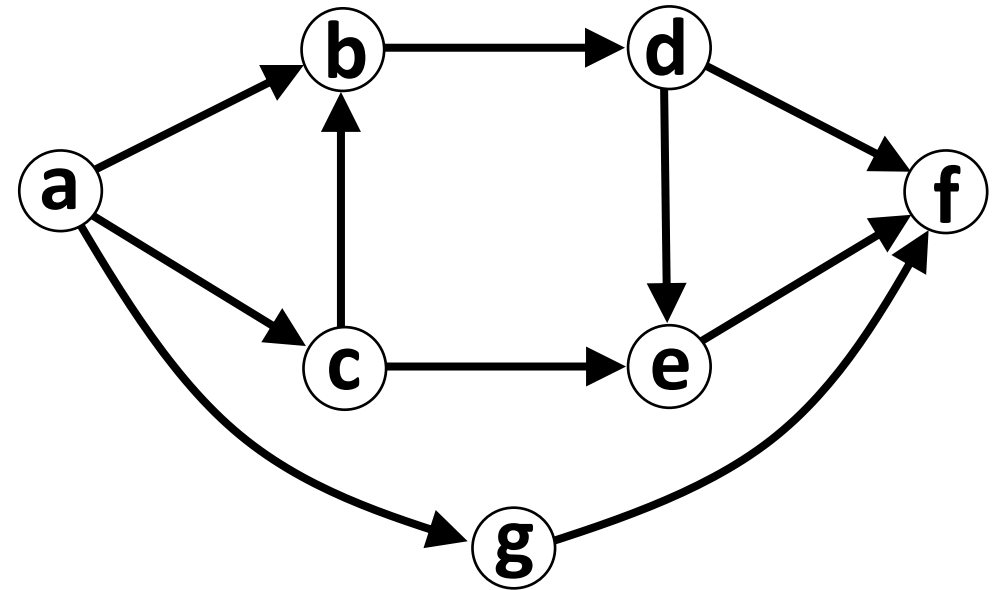
$\max_n (\text{longest path to } n) + 1,$   
for all incoming neighbors  $n$ .

a	b	c	d	e	f	g
0	0	0	0	0	0	0
-	-	-	-	-	-	-

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.



{a, c, g, b, d, e, f}

For each vertex in order, calculate longest path as:

$\max_n (\text{longest path to } n) + 1,$   
for all incoming neighbors  $n$ .

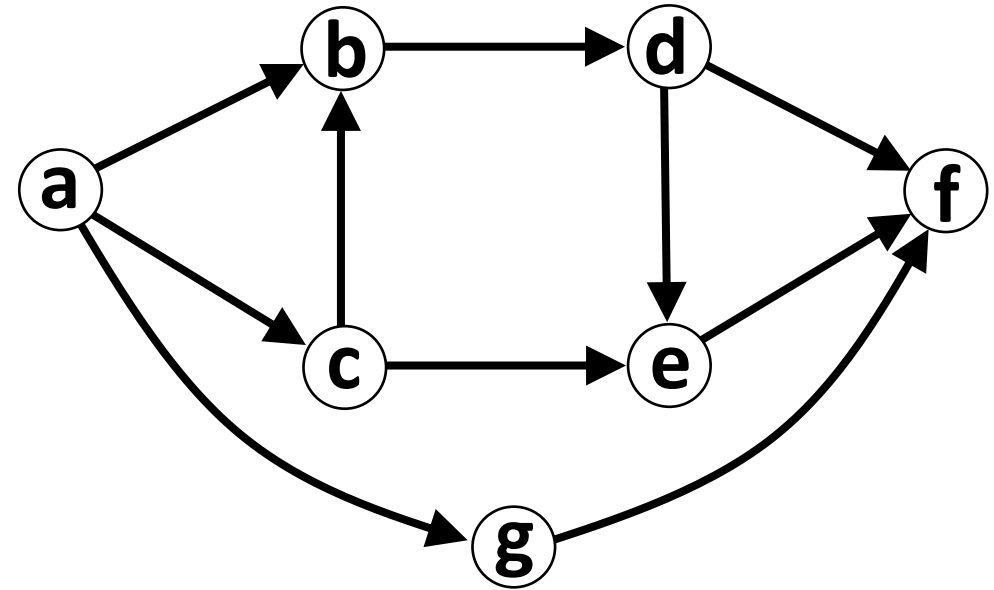
a	b	c	d	e	f	g
0	0	1	0	0	0	0
-	-	-	-	-	-	-



# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.



{a, c, g, b, d, e, f}

For each vertex in order, calculate longest path as:

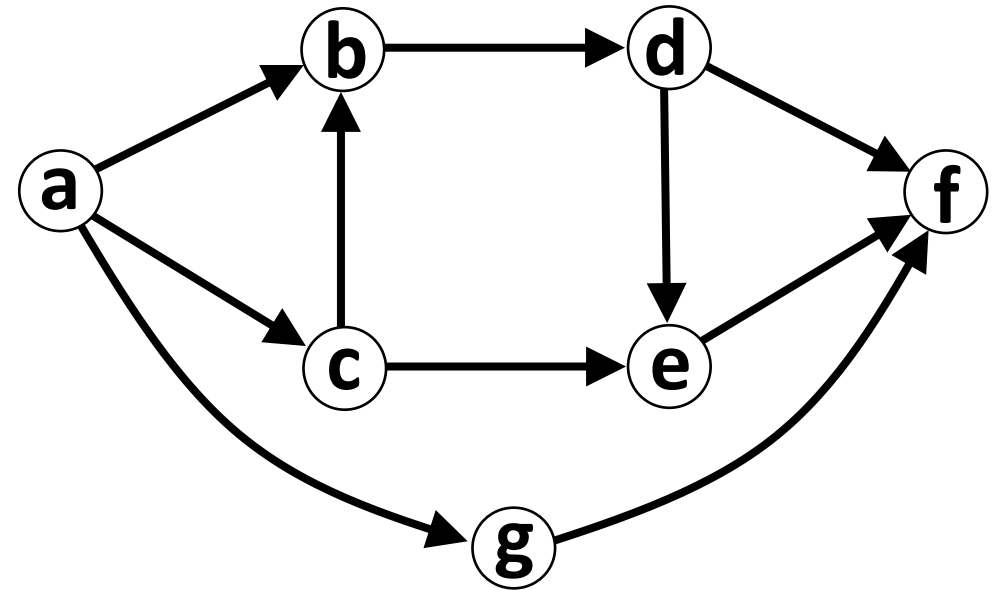
$\max_n (\text{longest path to } n) + 1,$   
for all incoming neighbors  $n$ .

a	b	c	d	e	f	g
0	0	1	0	0	0	0
-	-	a	-	-	-	-

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.



{a, c, g, b, d, e, f}

For each vertex in order, calculate longest path as:

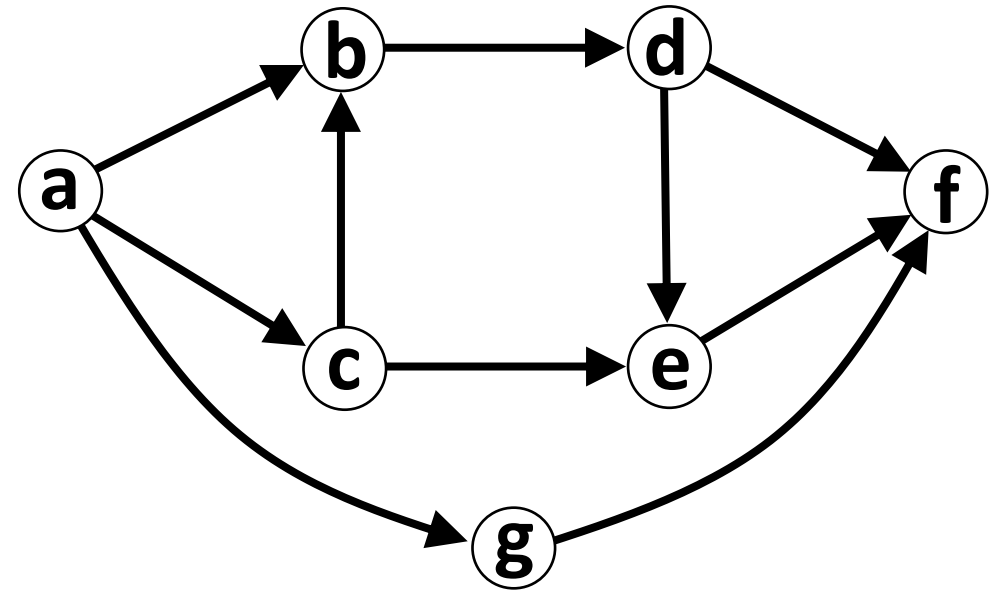
$\max_n (\text{longest path to } n) + 1,$   
for all incoming neighbors  $n$ .

a	b	c	d	e	f	g
0	0	1	0	0	0	1
-	-	a	-	-	-	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.



{a, c, g, **b**, d, e, f}

For each vertex in order, calculate longest path as:

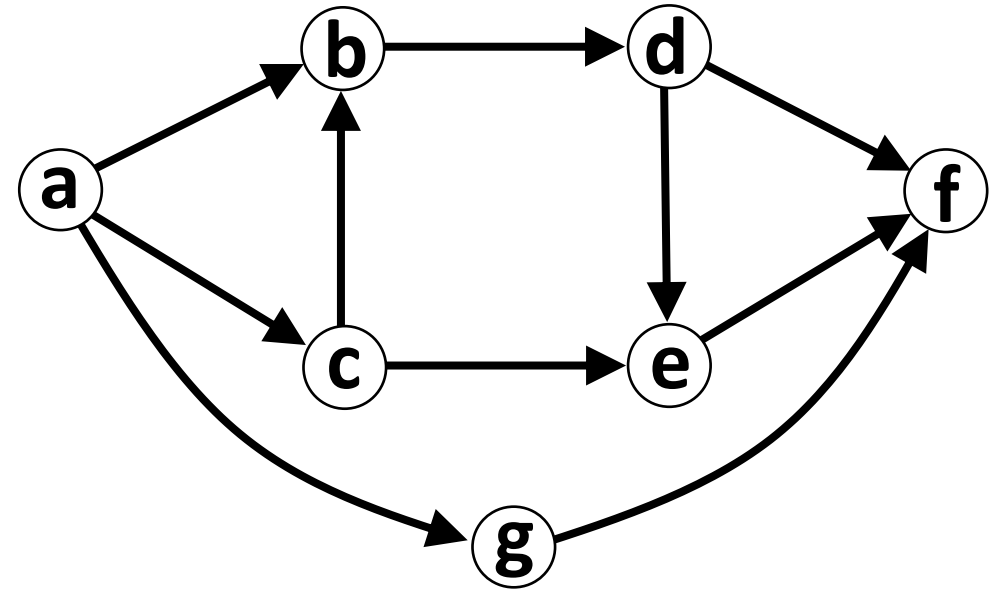
$\max_n (\text{longest path to } n) + 1,$   
for all incoming neighbors  $n$ .

a	<b>b</b>	c	d	e	f	g
0	<b>2</b>	1	0	0	0	1
-	<b>c</b>	a	-	-	-	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.



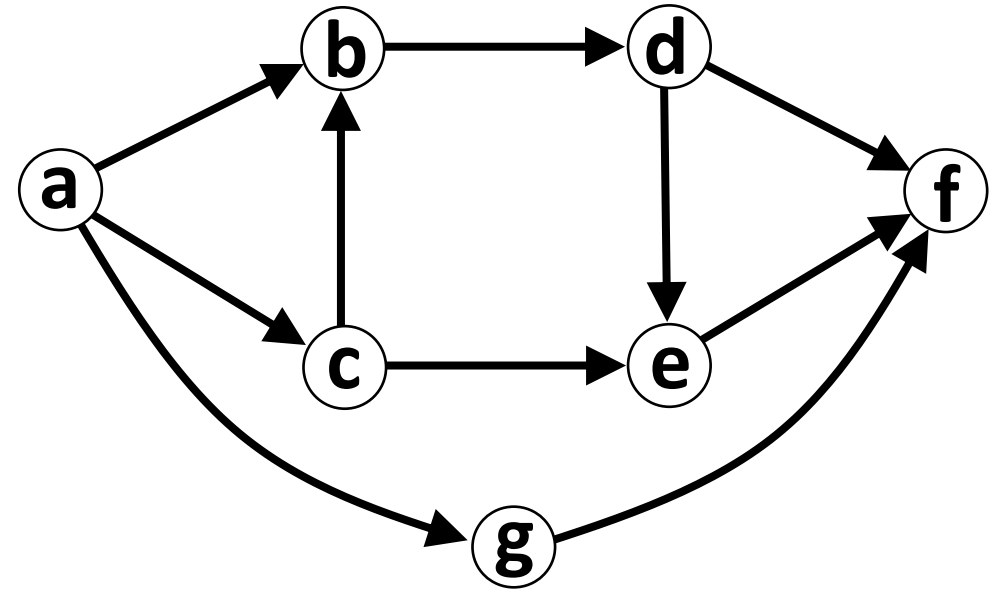
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.



{a, c, g, b, d, e, f}

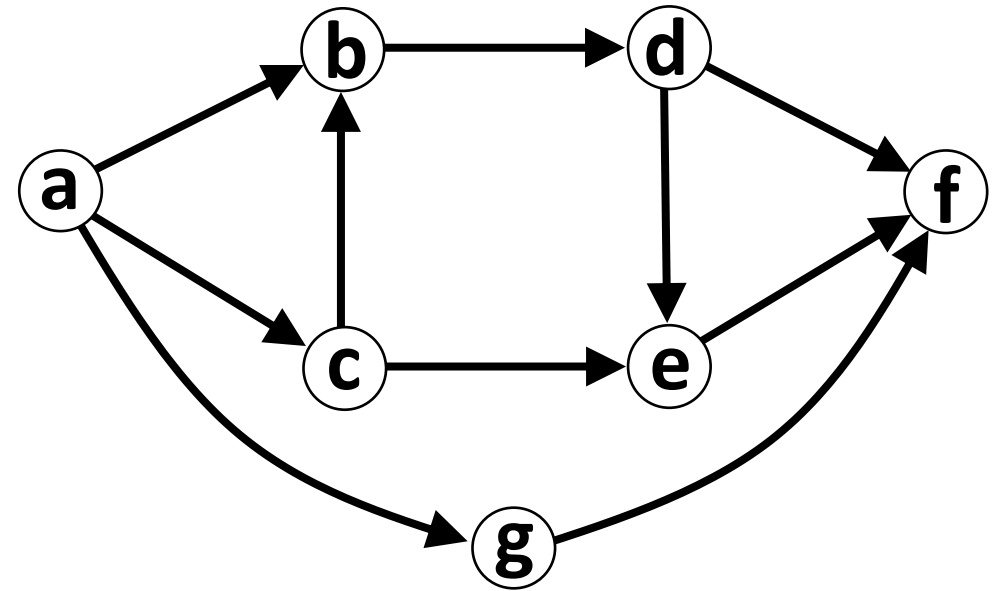
a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.

path: f



{a, c, g, b, d, e, f}

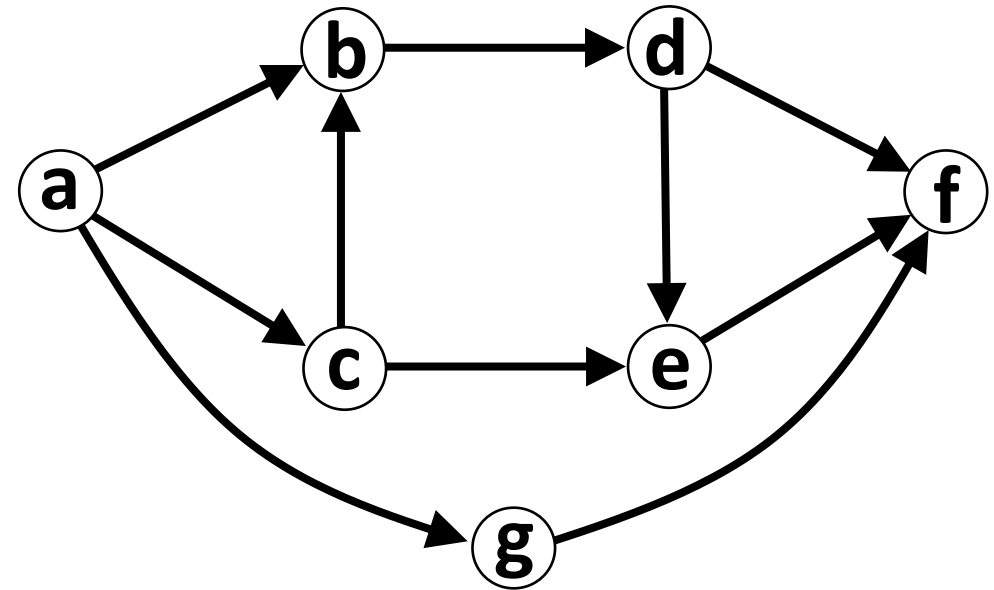
a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.

**path: f <- e**



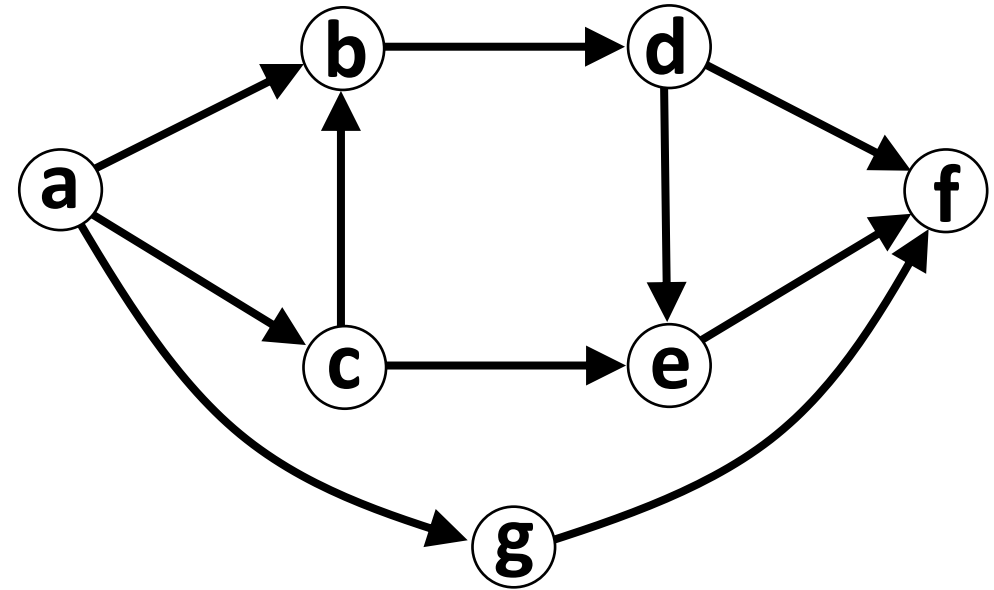
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

## Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.



{a, c, g, b, d, e, f}

**path: f <- e <- d**

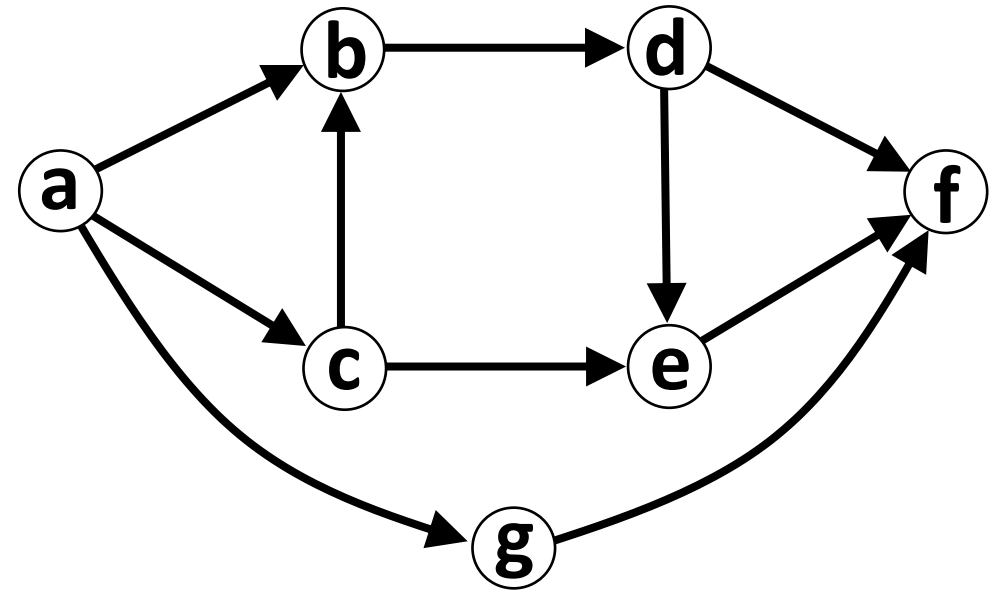
a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a



# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.



{a, c, g, b, d, e, f}

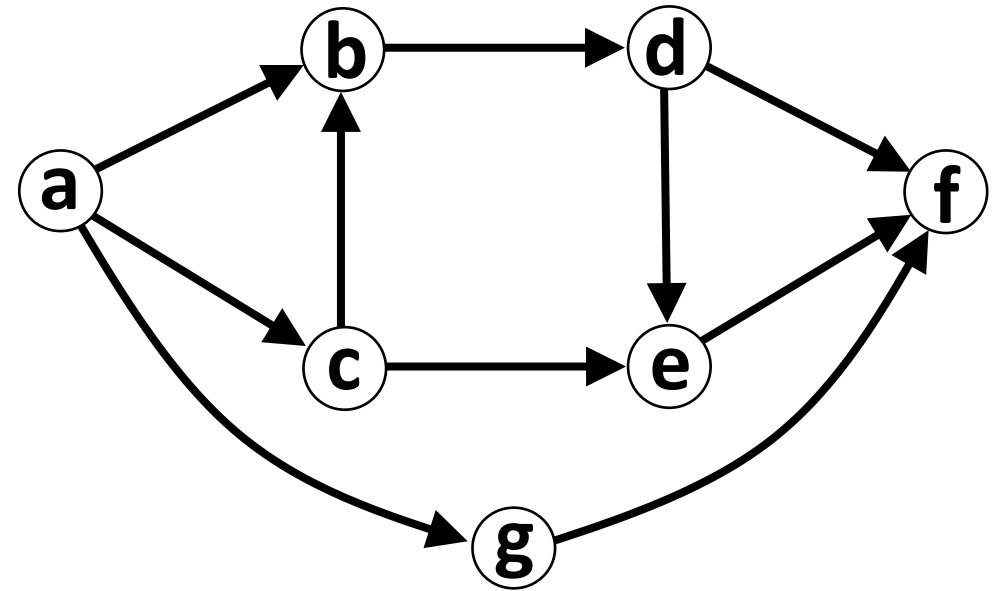
**path: f <- e <- d <- b**

a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

## Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.



{a, c, g, b, d, e, f}

**path: f <- e <- d <- b <- c <- a**

a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a