

# Longest Path

## CSCI 532

# Dynamic Programming

Trick-or-treat planning.



# Dynamic Programming

Trick-or-treating at the red house, blue house, and green house are the fewest stops you need to fill your 25-pound capacity sack.



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Trick-or-treating at the red house, blue house, and green house are the fewest stops you need to fill your 25-pound capacity sack. The blue house gives you 5 pounds of candy. What can you conclude?



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The red house and the green house are the fewest stops you need to get 20+ pounds of candy.



# Dynamic Programming

Trick-or-treating at the red house, blue house, and green house are the fewest stops you need to fill your 25-pound capacity sack. The blue house gives you 5 pounds of candy. What can you conclude?

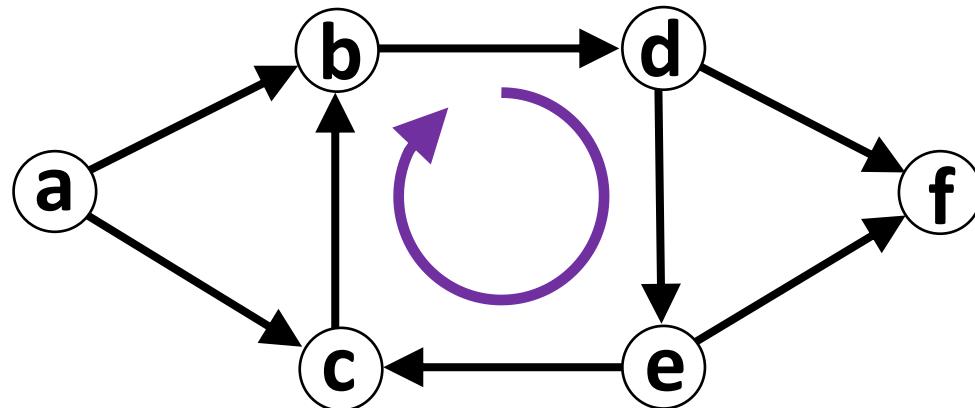
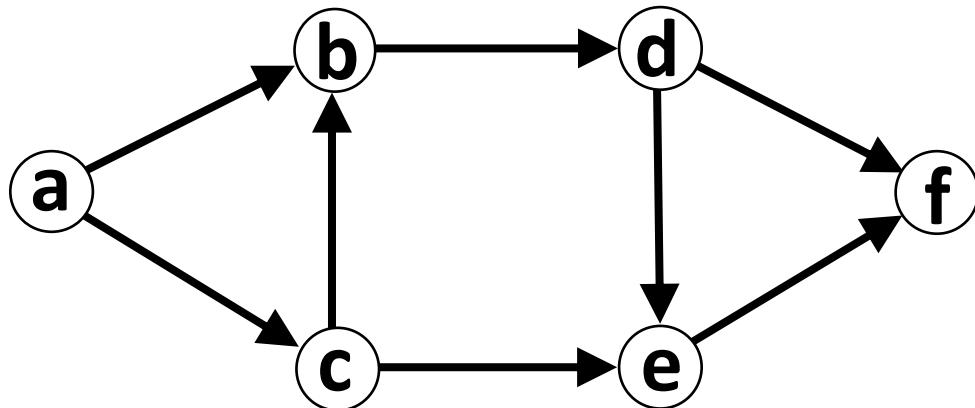
The red house and the green house are the fewest stops you need to get 20+ pounds of candy.

**A problem exhibits optimal substructure if removing part of an optimal solution results in an optimal solution to a smaller problem.**

Central tenant of Dynamic Programming: Leverage optimal sub-structure.

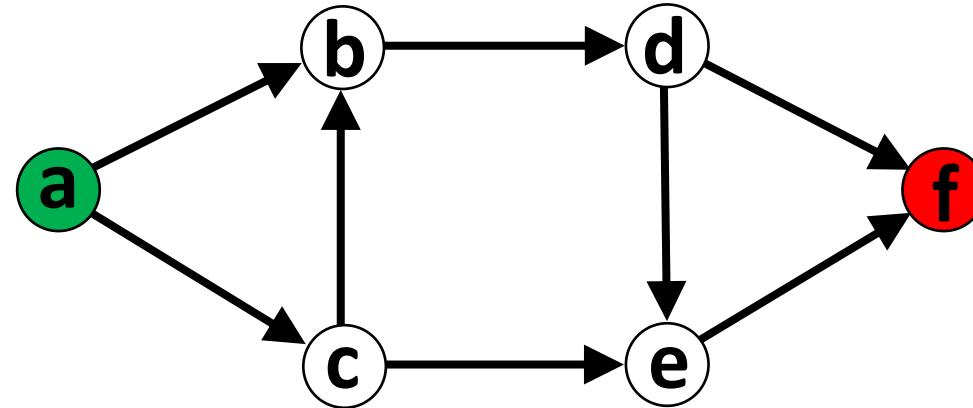
# Directed Acyclic Graph (DAG)

Directed Acyclic Graph (DAG) = Directed graph with no cycles.



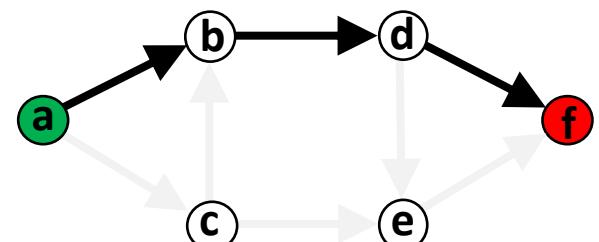
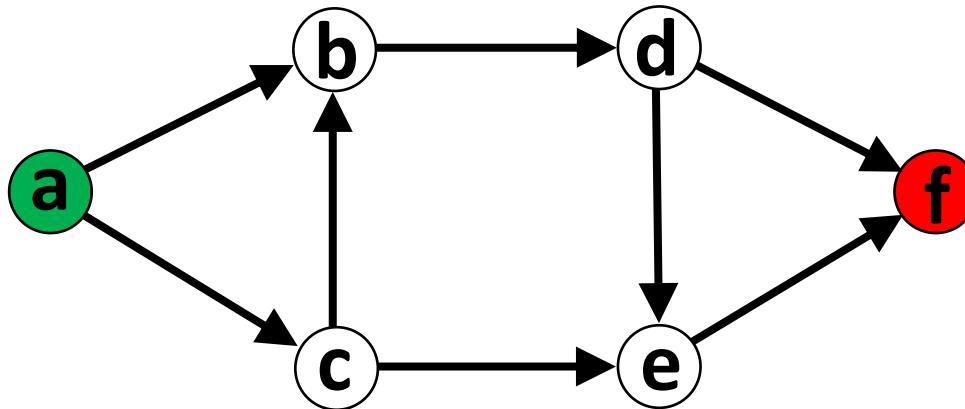
# Longest Path in a DAG

Given a DAG, find the longest path between any two vertices in the graph.

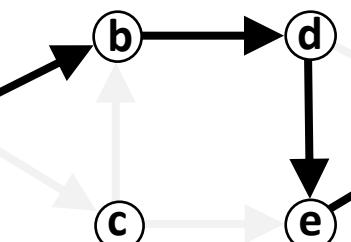


# Longest Path in a DAG

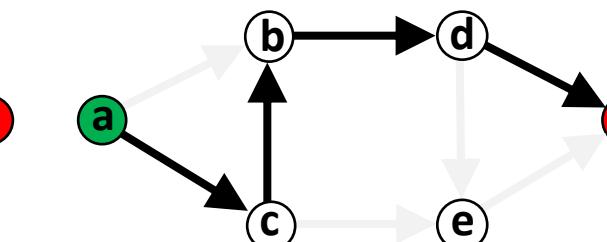
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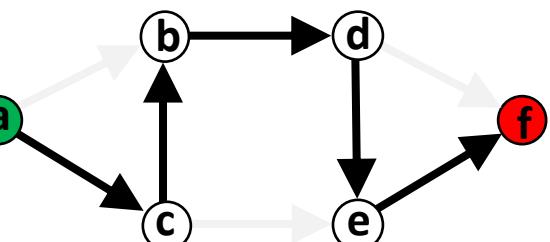
length = 3



length = 4



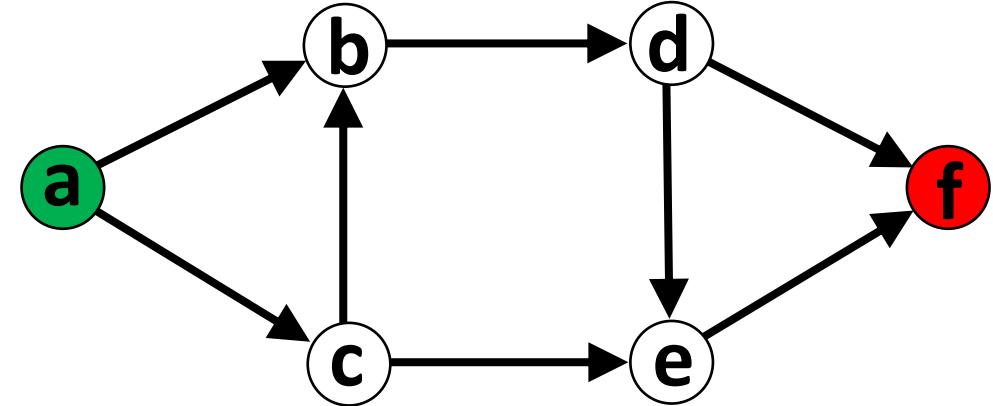
length = 4



length = 5

# Find the Longest Path in a DAG

Task	Description	Duration
a	Select location	2 days
b	Get permits	4 days
c	Select date/time	1 day
d	Hire vendors	2 days
e	Make flyers	1 day
f	Market event	1 day

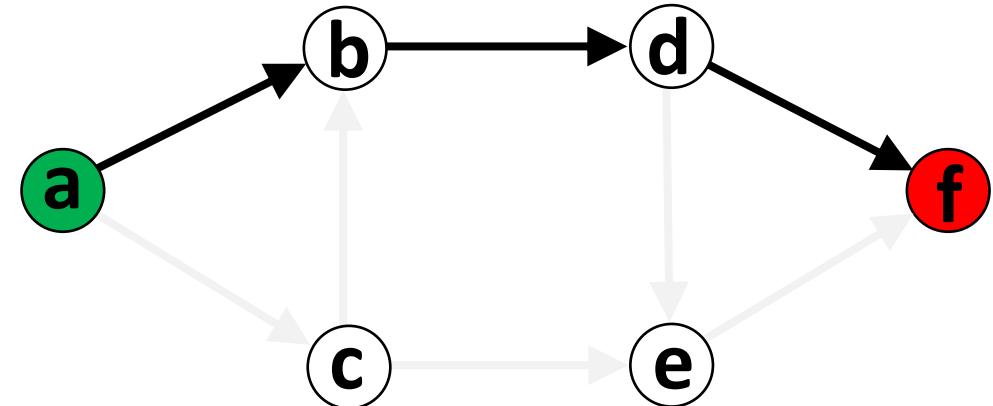


Critical Path: Sequence of dependent tasks that determines the minimum time to complete project.

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a	Select location	2 days
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f	Market event	1 day

Length =  $2 + 4 + 2 + 1 = 9$  days

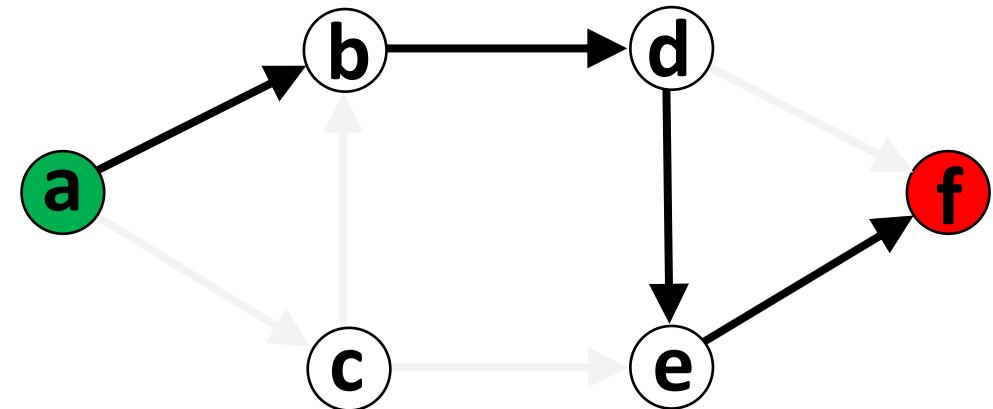


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f	Market event	1 day

$$\text{Length} = 2 + 4 + 2 + 1 + 1 = 10 \text{ days}$$

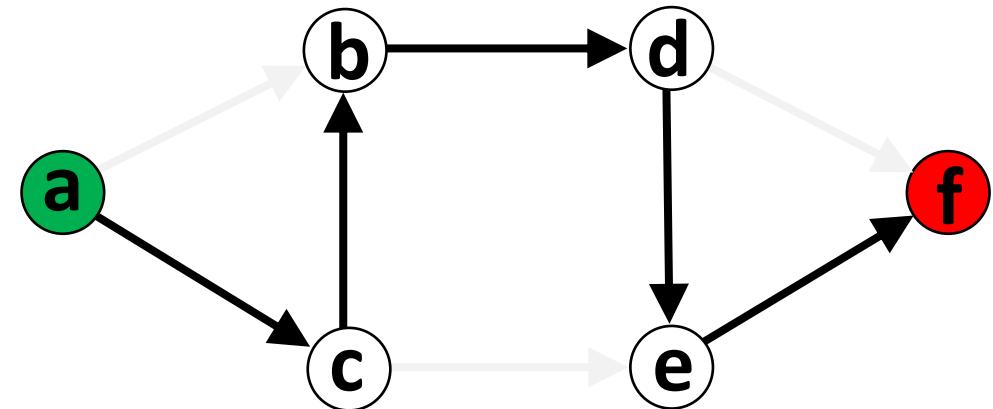


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f	Market event	1 day

$$\text{Length} = 2 + 1 + 4 + 2 + 1 + 1 = 11 \text{ days}$$

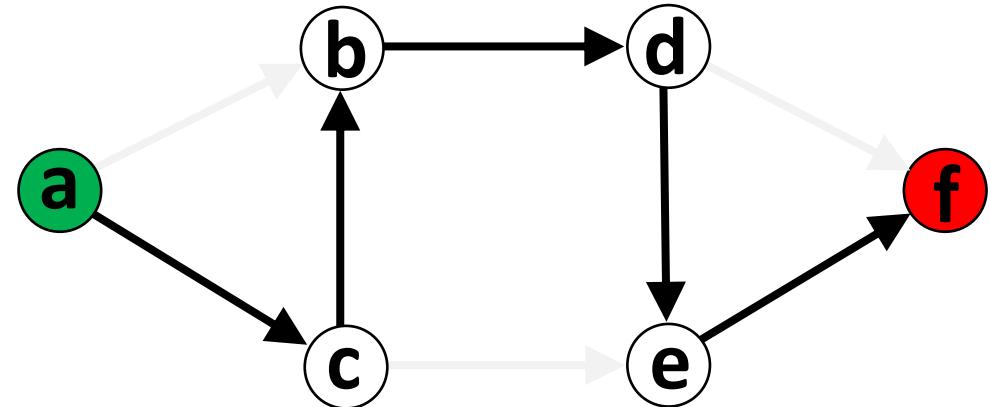


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a	Select location	2 days
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$$\text{Length} = 2 + 1 + 4 + 2 + 1 + 1 = 11 \text{ days}$$

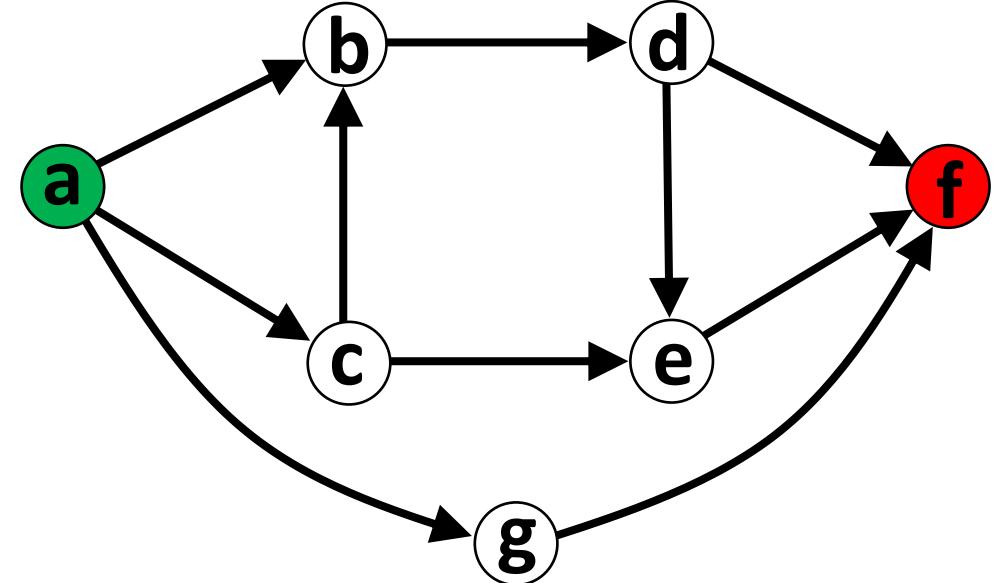


Critical Path: Sequence of dependent tasks that determines the minimum time to complete project.

**If any task on critical path is delayed, project is delayed.**

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a	Select location	2 days
b	Get permits	4 days
c	Select date/time	1 day
d	Hire vendors	2 days
e	Make flyers	1 day
f	Market event	1 day
g	Photograph venue	1 day



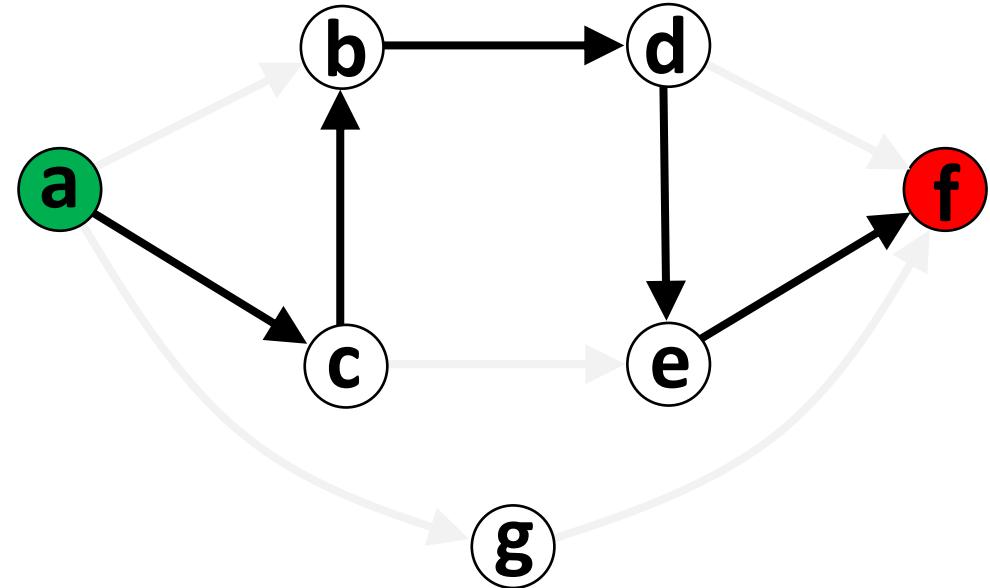
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$$\text{Length} = 2 + 1 + 4 + 2 + 1 + 1 = 11 \text{ days}$$



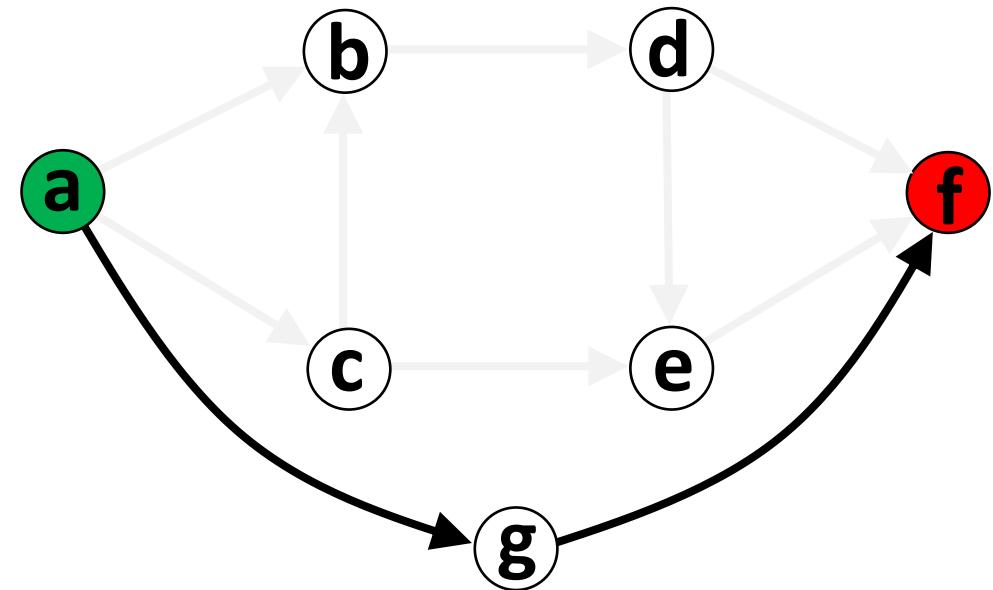
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c	Select date/time	1 day
d	Hire vendors	2 days
e	Make flyers	1 day
f	Market event	1 day
g	Photograph venue	10 days

Length =  $2 + 10 + 1 = 13$  days



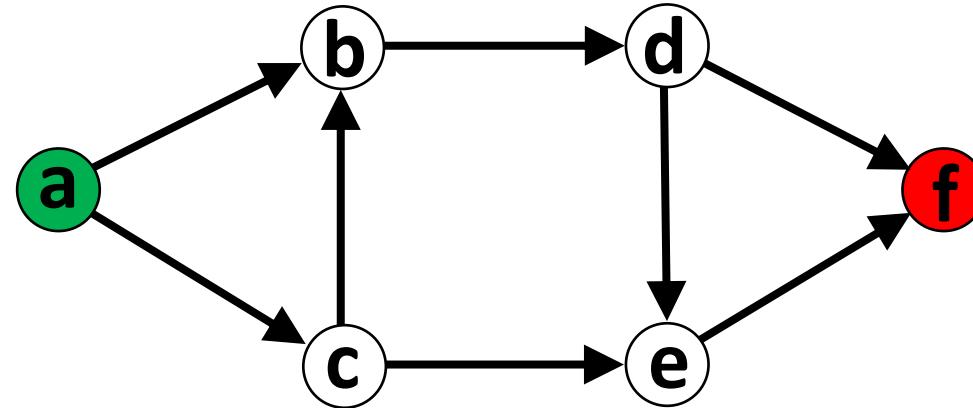
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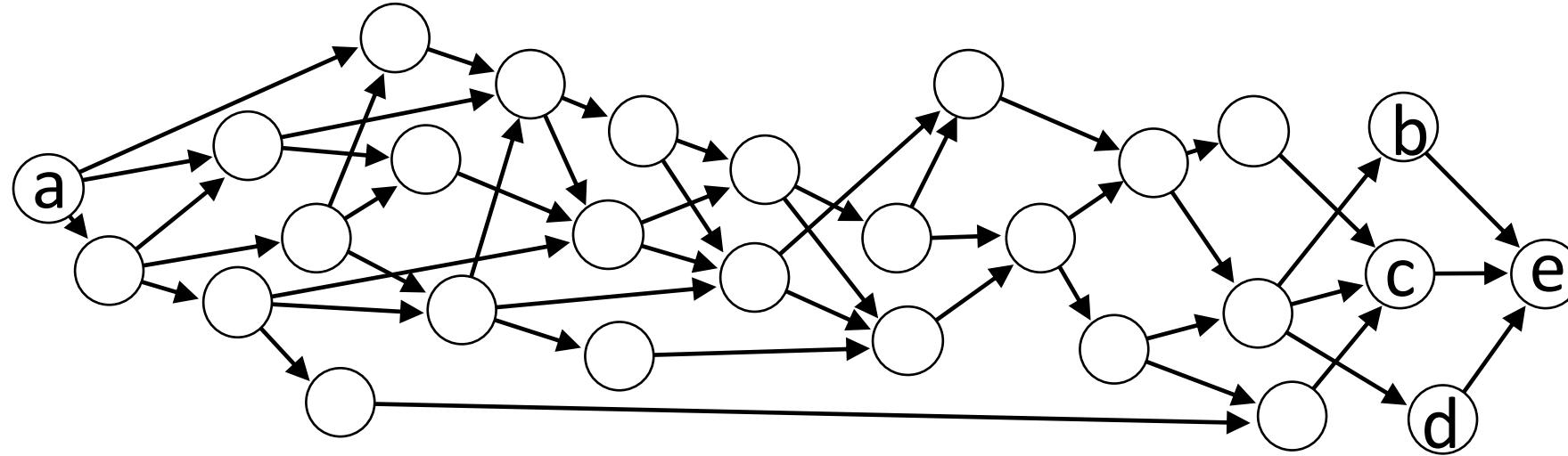
Number of edges.  
No vertex weights.

Given a DAG, find the longest path between any two vertices in the graph.



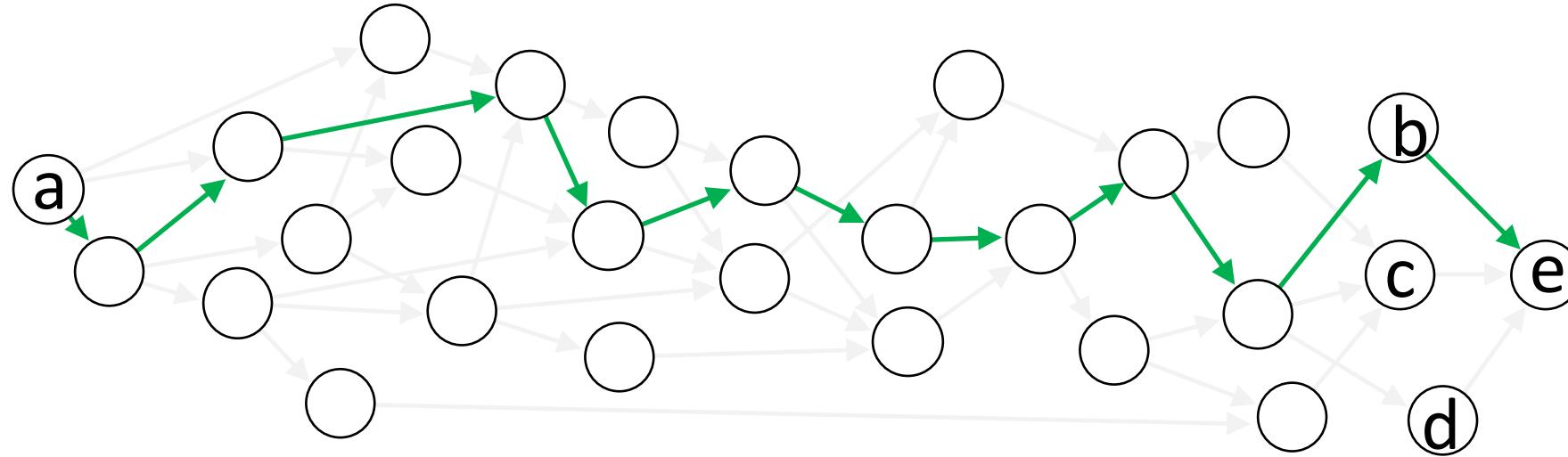
How do we do this?

# Find the Longest Path in a DAG



# Interesting observations?

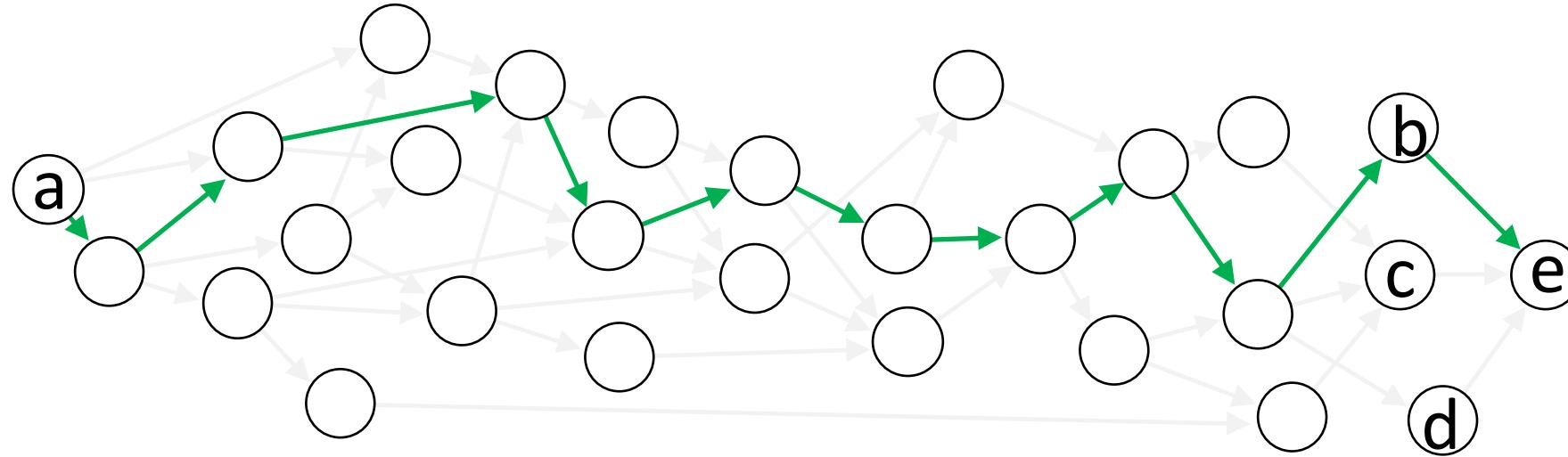
# Find the Longest Path in a DAG



Interesting observations?

If the longest path goes from **a** to **e** and passes through **b**, what could we say about the part of that path to **b**?

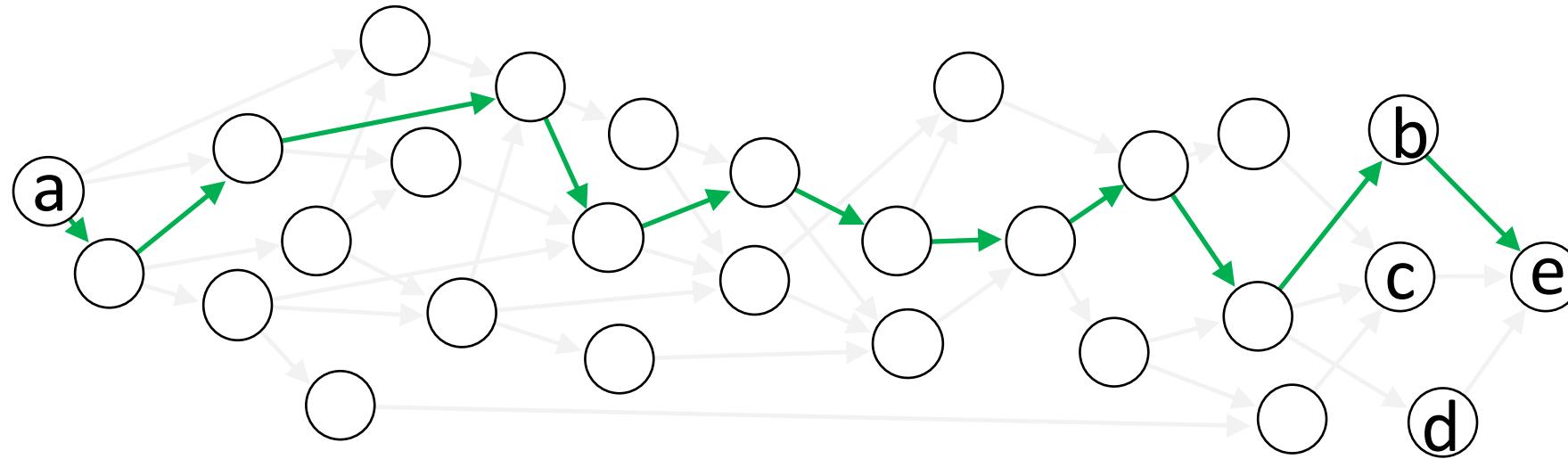
# Find the Longest Path in a DAG



Interesting observations?

If the longest path goes from **a** to **e** and passes through **b**, that must be the longest path that ends at **b**.

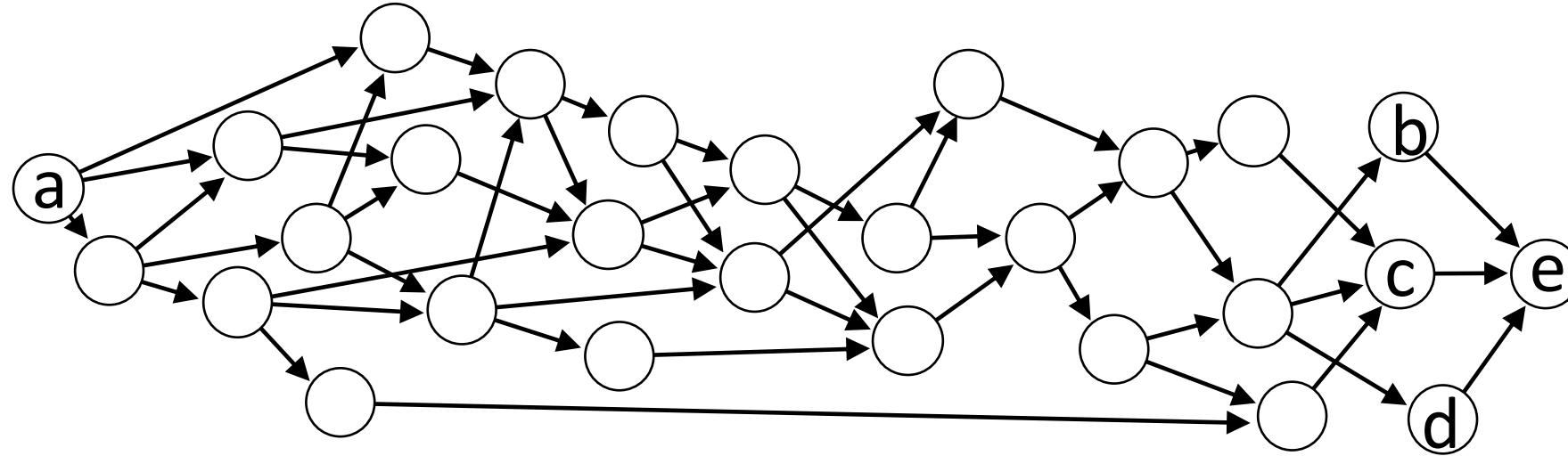
# Find the Longest Path in a DAG



Interesting observations?

If the longest path goes from **a** to **e** and passes through **b**, that must be the longest path that ends at **b**. If not, then we could make a longer path.

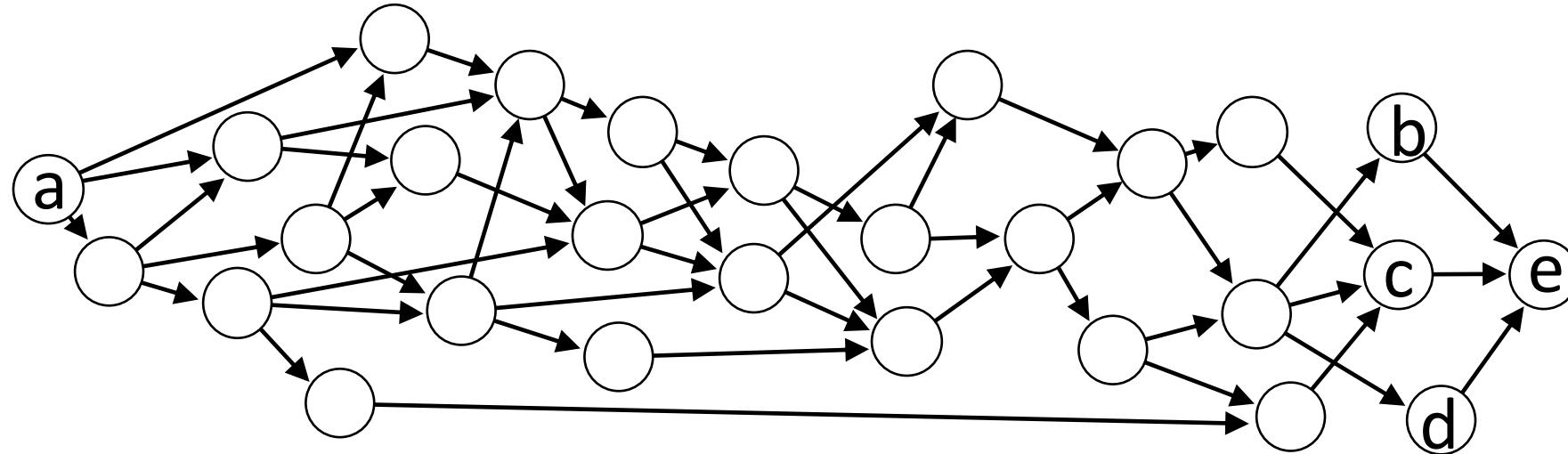
# Find the Longest Path in a DAG



# Interesting observations?

The longest path to e = ??

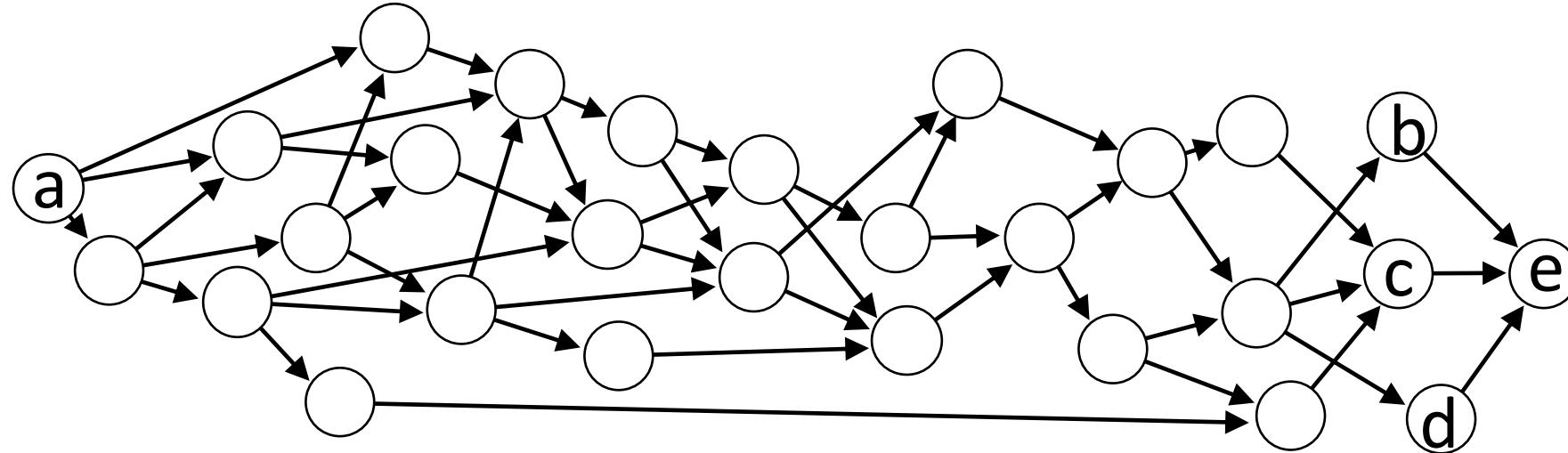
# Find the Longest Path in a DAG



Interesting observations?

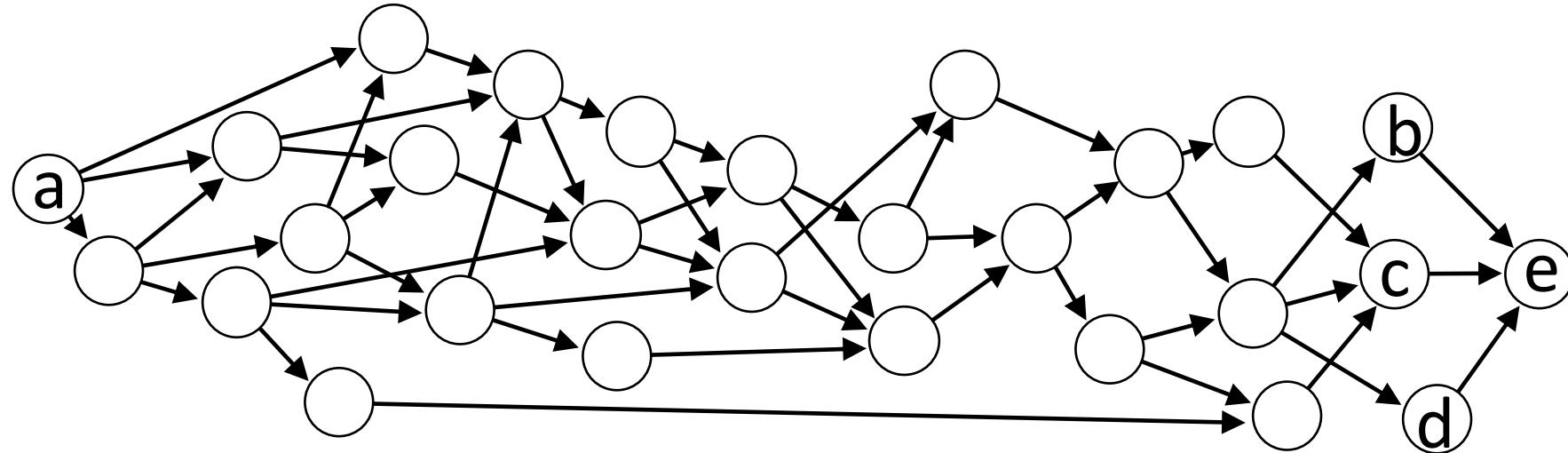
The longest path to  $e$  =  $\max \left( \begin{array}{l} \text{longest path to } b \\ \text{longest path to } c \\ \text{longest path to } d \end{array} \right) + 1$

# Find the Longest Path in a DAG



$$\text{longest path to } e = \max \begin{pmatrix} \text{longest path to } b \\ \text{longest path to } c \\ \text{longest path to } d \end{pmatrix} + 1$$

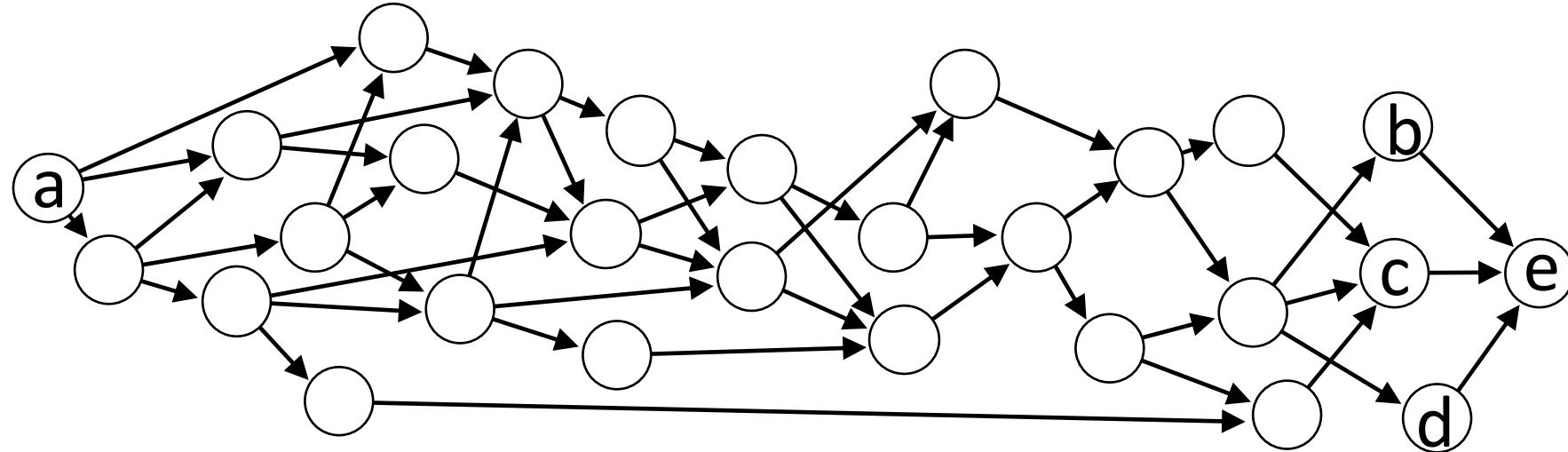
# Find the Longest Path in a DAG



When are we ready to calculate  
the longest path to e?

$$\text{longest path to e} = \max \begin{pmatrix} \text{longest path to b} \\ \text{longest path to c} \\ \text{longest path to d} \end{pmatrix} + 1$$

# Find the Longest Path in a DAG

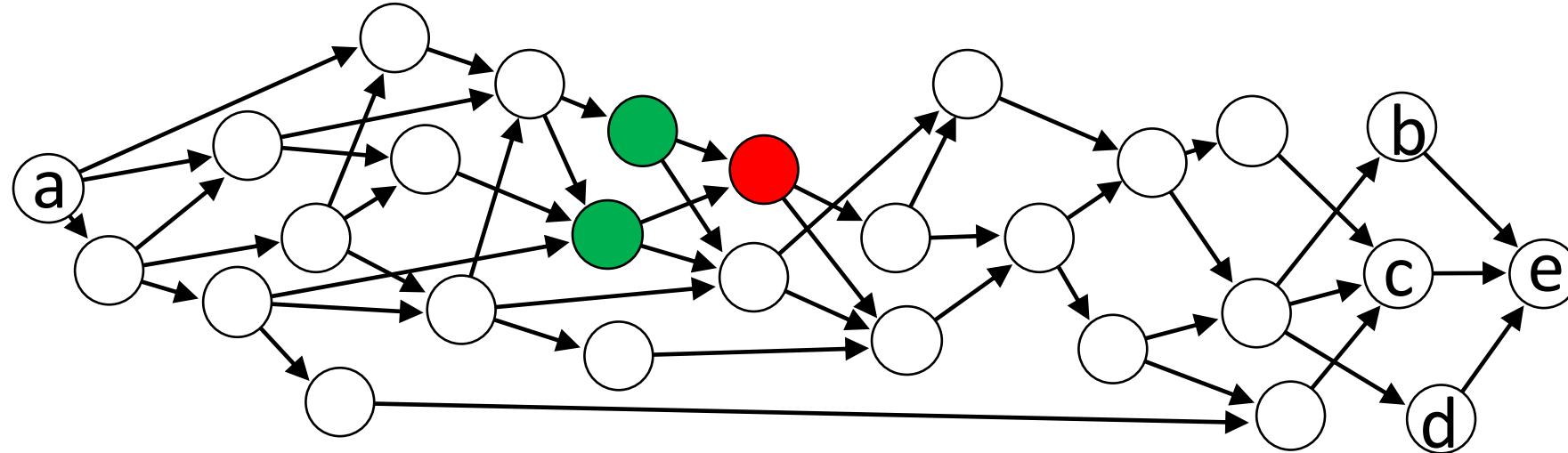


When are we ready to calculate  
the longest path to e?

When we have the longest  
paths to b, c, and d.

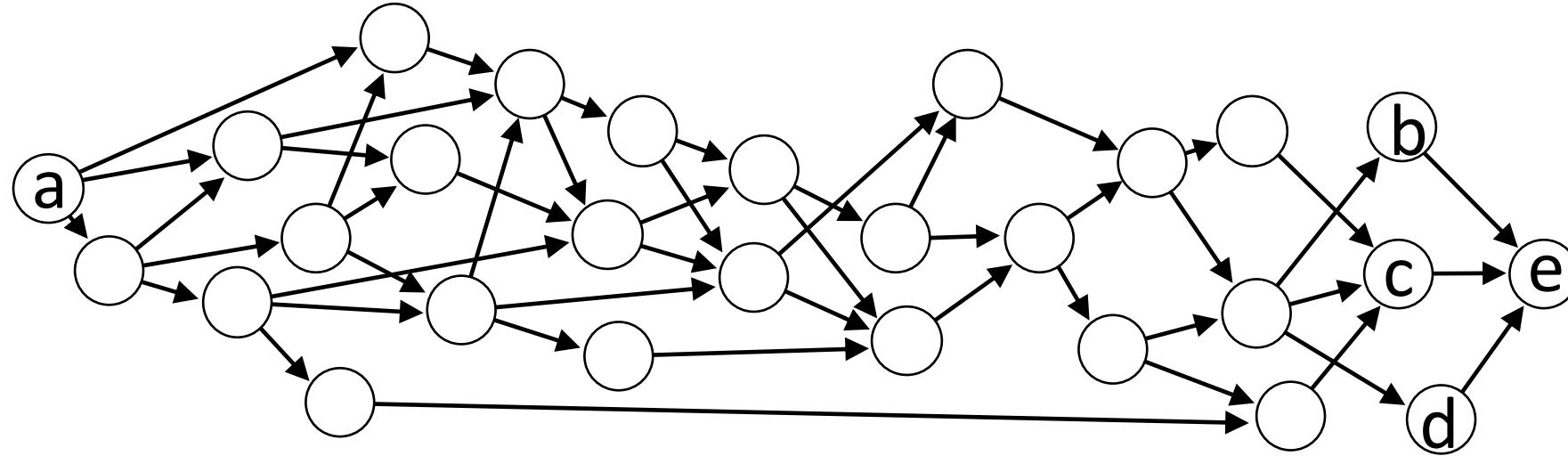
$$\text{longest path to e} = \max \begin{pmatrix} \text{longest path to b} \\ \text{longest path to c} \\ \text{longest path to d} \end{pmatrix} + 1$$

# Find the Longest Path in a DAG



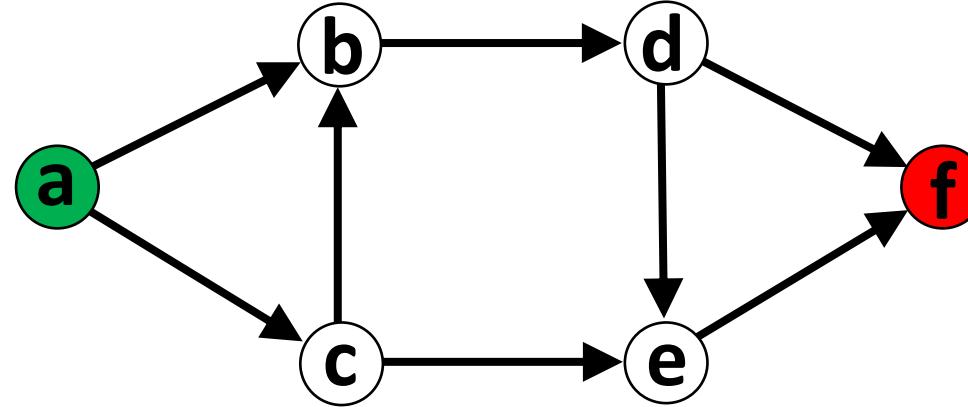
In general: We are ready to calculate the longest path to a vertex if we know the longest path for all incoming neighbors.

# Find the Longest Path in a DAG



Topological Ordering of a graph: ordering of its vertices such that for every directed edge  $(u, v)$ , vertex  $u$  comes before vertex  $v$  in the ordering.

# Topological Ordering

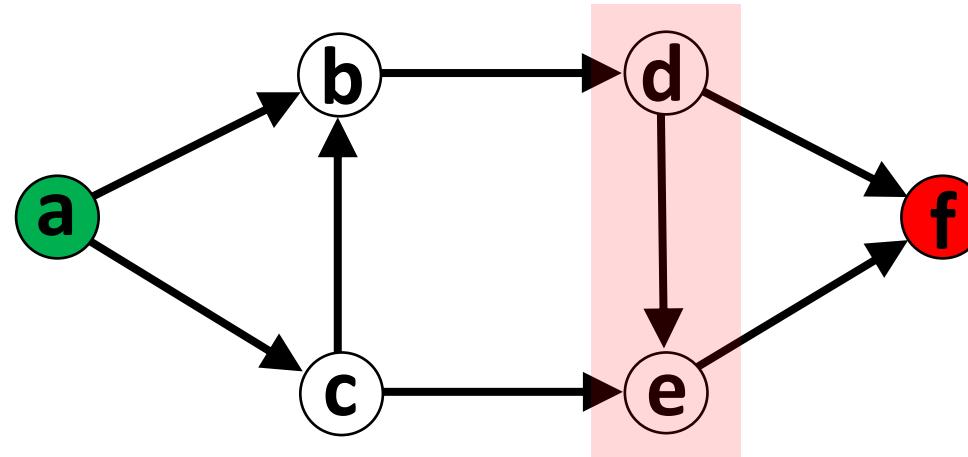


Topologically Ordered:

$\{a, c, b, d, e, f\}$



# Topological Ordering

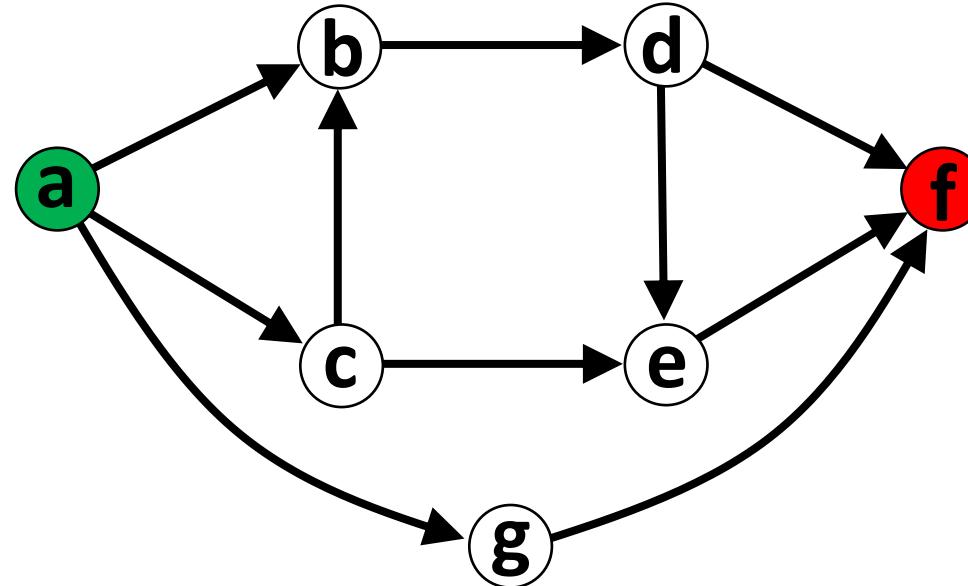


Topologically Ordered:

$\{a, c, b, d, e, f\}$  ✓

$\{a, c, b, e, d, f\}$  ✗

# Topological Ordering

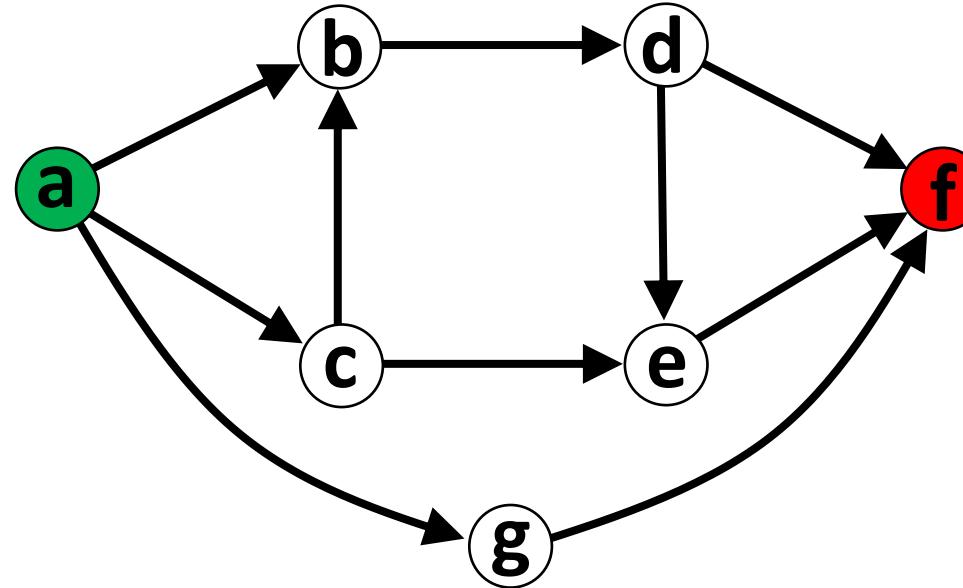


Topologically Ordered:

{a, c, g, b, d, e, f}

{a, c, b, d, e, g, f}

# Topological Ordering

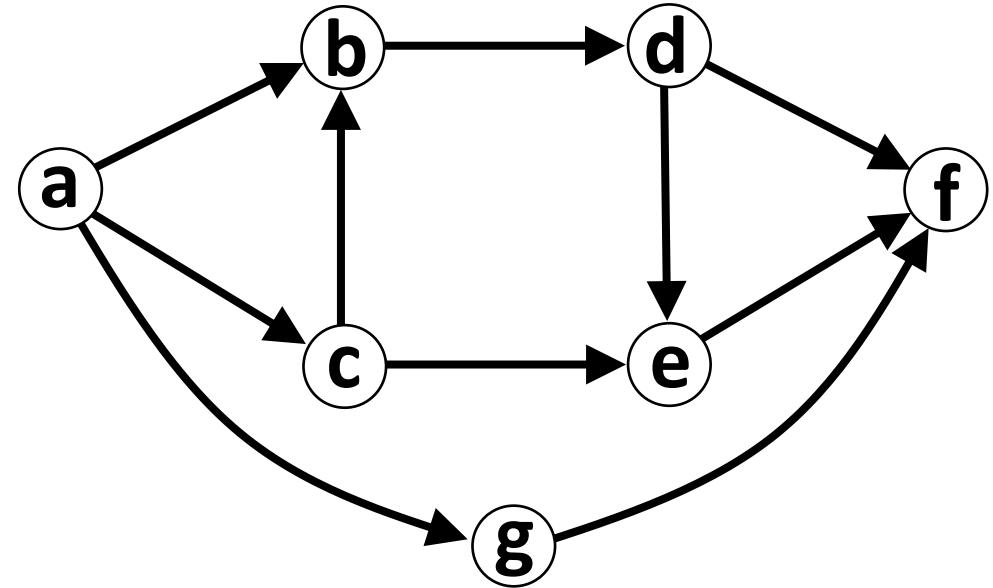


- There are various algorithms to find topological orderings
- Standard running time =  $O(|V| + |E|)$ .

# Find the Longest Path in a DAG

Plan:

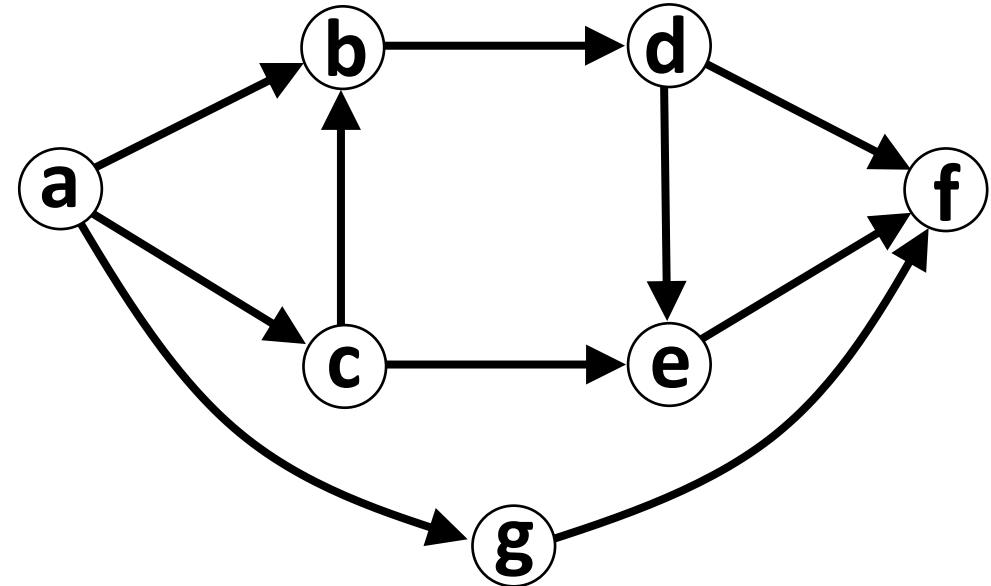
- ??



# Find the Longest Path in a DAG

Plan:

- Topologically sort vertices.

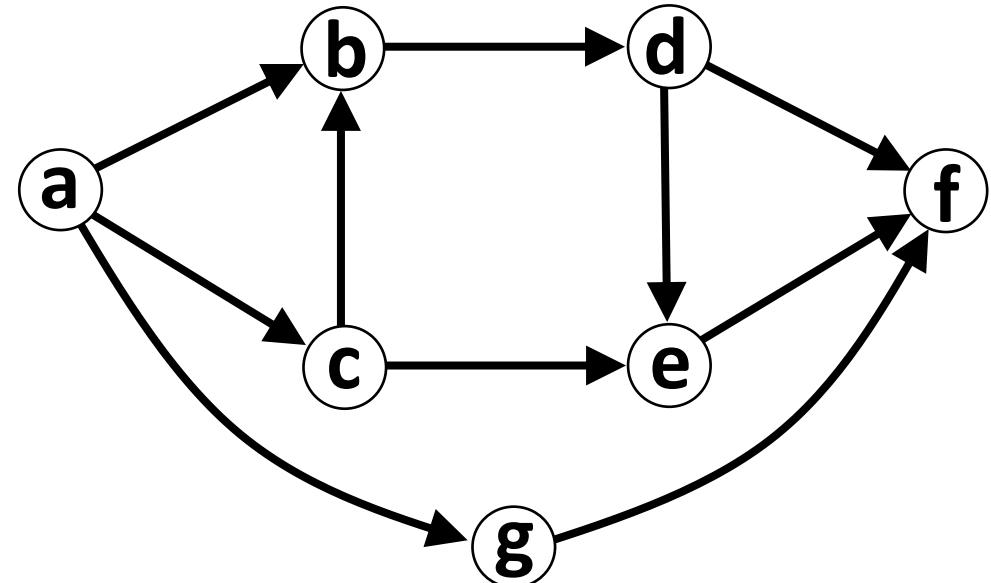


$\{a, c, g, b, d, e, f\}$

# Find the Longest Path in a DAG

Plan:

- Topologically sort vertices.
- Make array to store length of longest path that ends at each vertex.



$\{a, c, g, b, d, e, f\}$

Length of longest path that ends at c.

a	b	c	d	e	f	g
0	0	0	0	0	0	0

# Find the Longest Path in a DAG

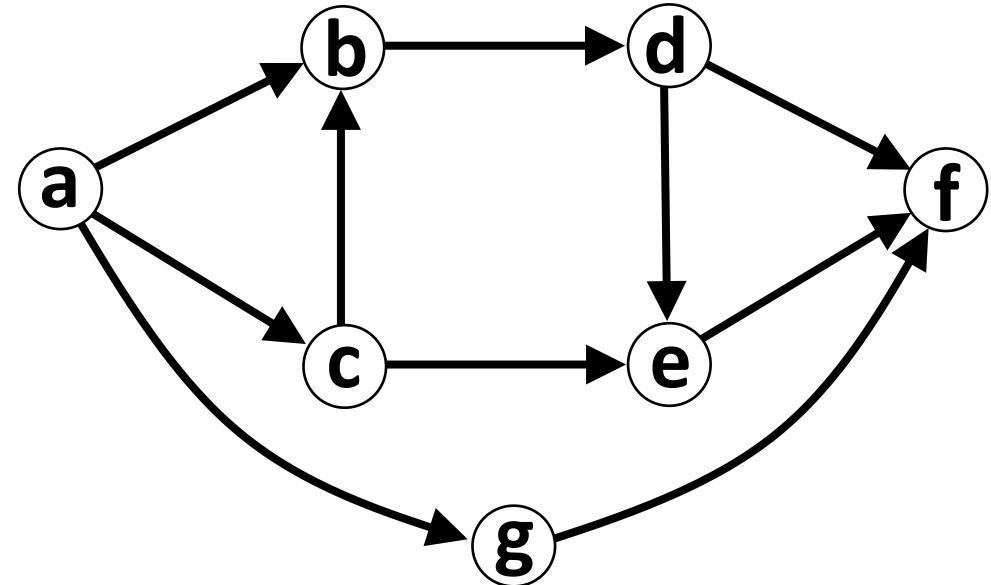
Plan:

- Topologically sort vertices.
- Make array to store length of longest path that ends at each vertex.

- For each vertex in order, calculate longest path as:

$\max_n(\text{longest path to } n) + 1$ ,  
for all incoming neighbors  $n$ .

(Or 0 if there are no incoming neighbors)



{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	0	0	0	0	0

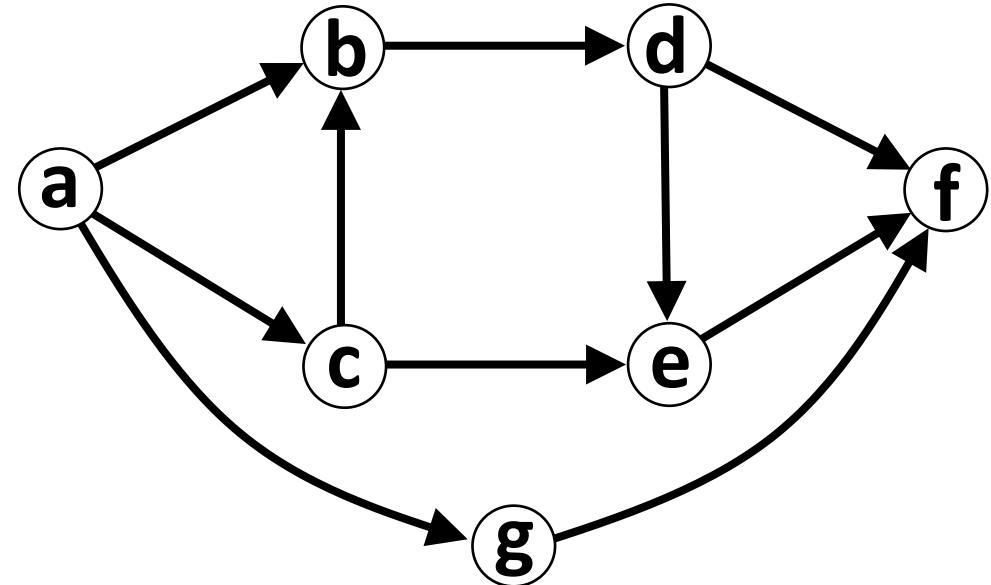
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{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	0	0	0	0	0

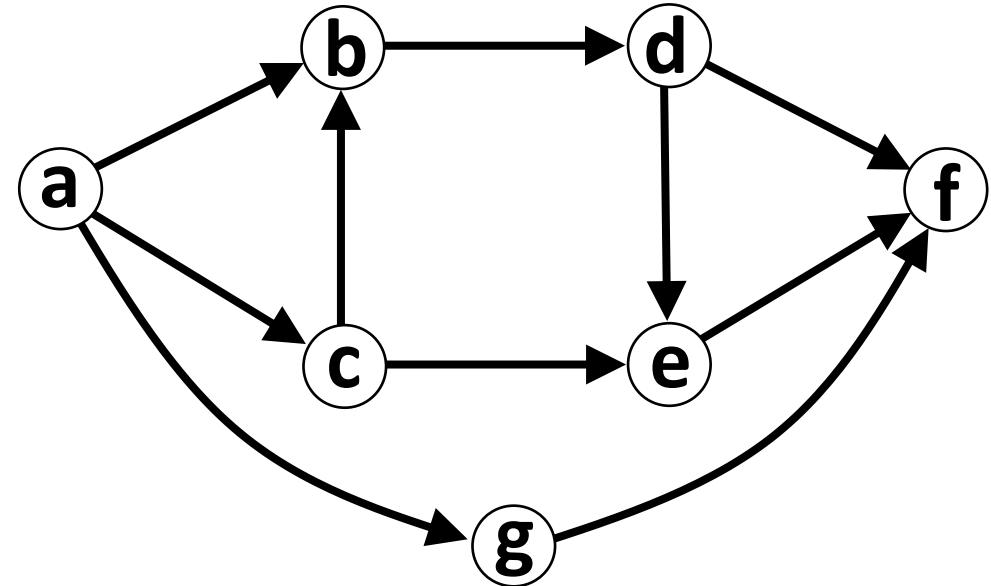
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a	b	c	d	e	f	g
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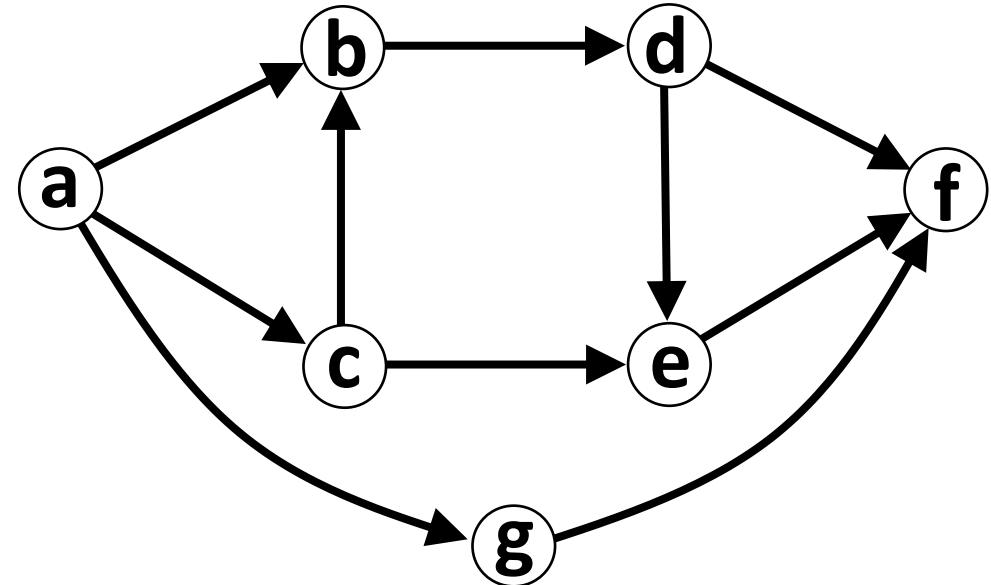
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{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	1	0	0	0	0

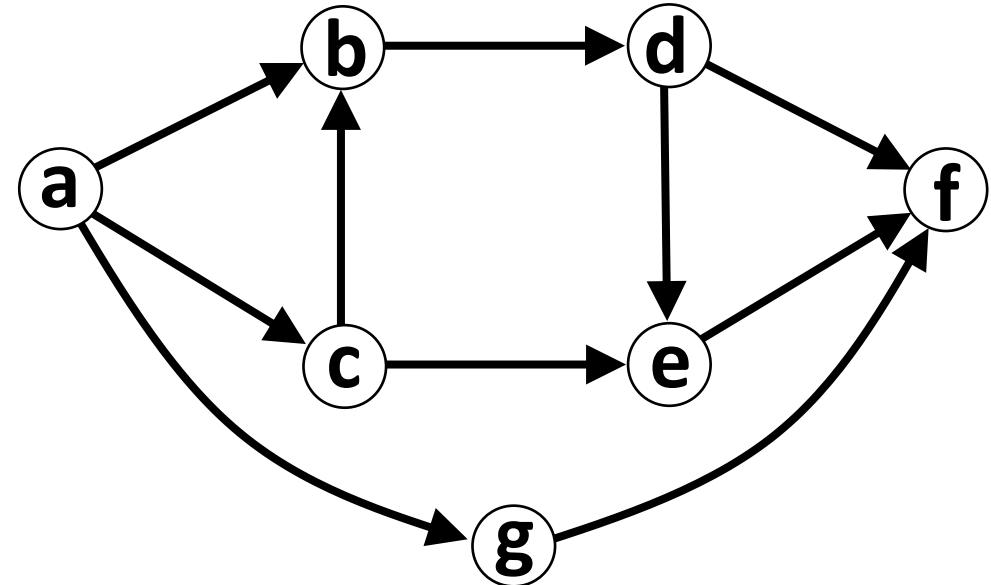
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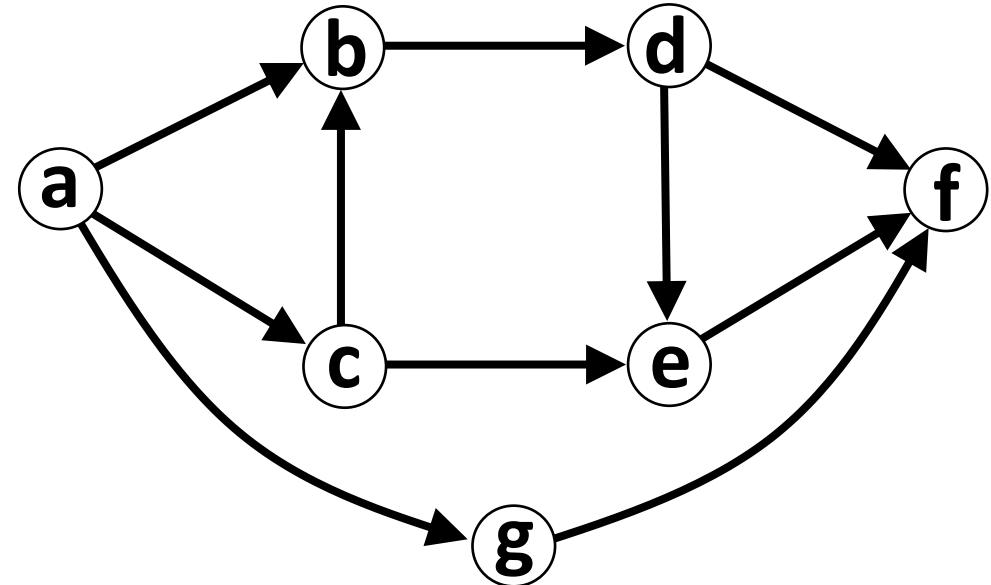
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{a, c, g, b, d, e, f}

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0	0	1	0	0	0	1

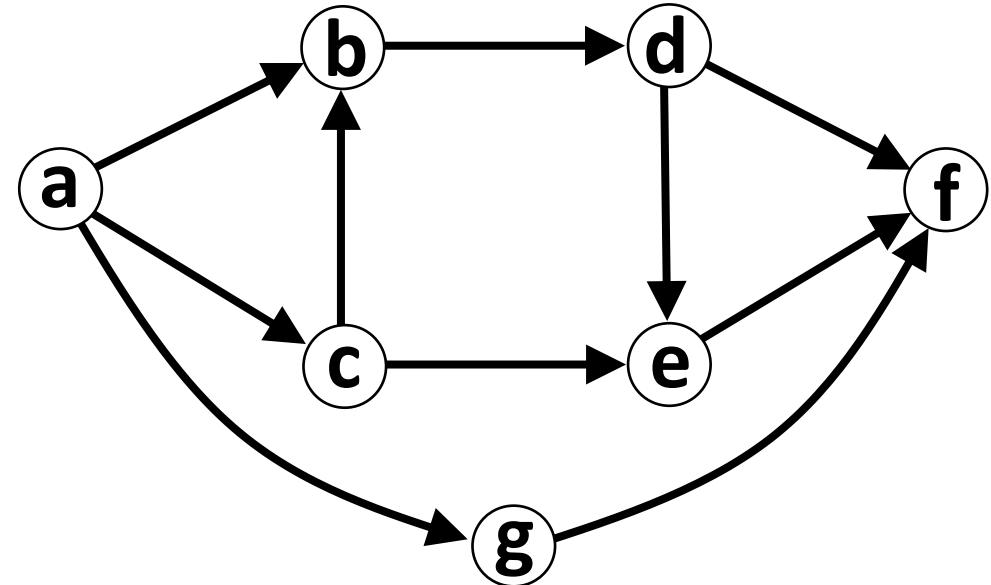
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{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	1	0	0	0	1

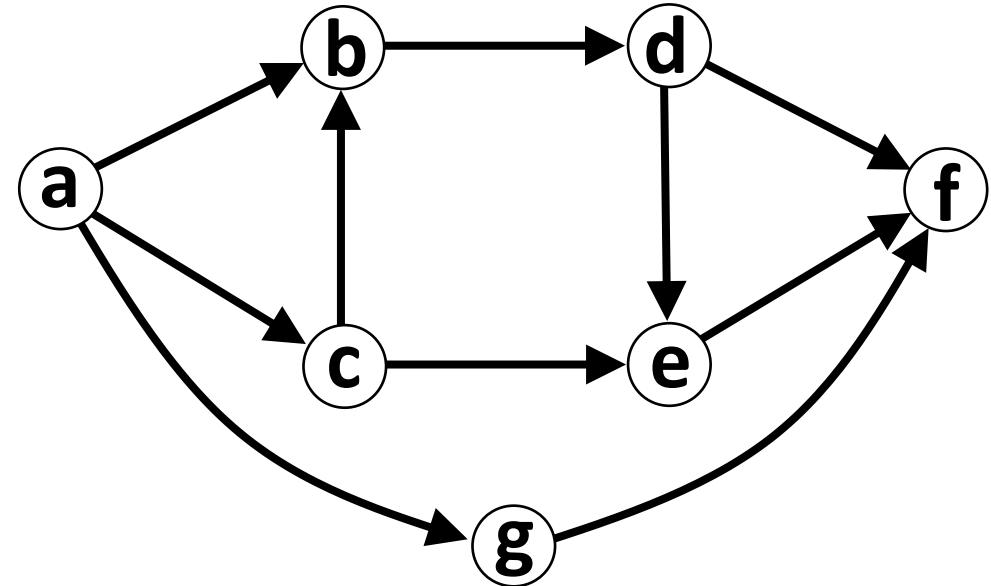
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{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	0	0	0	1

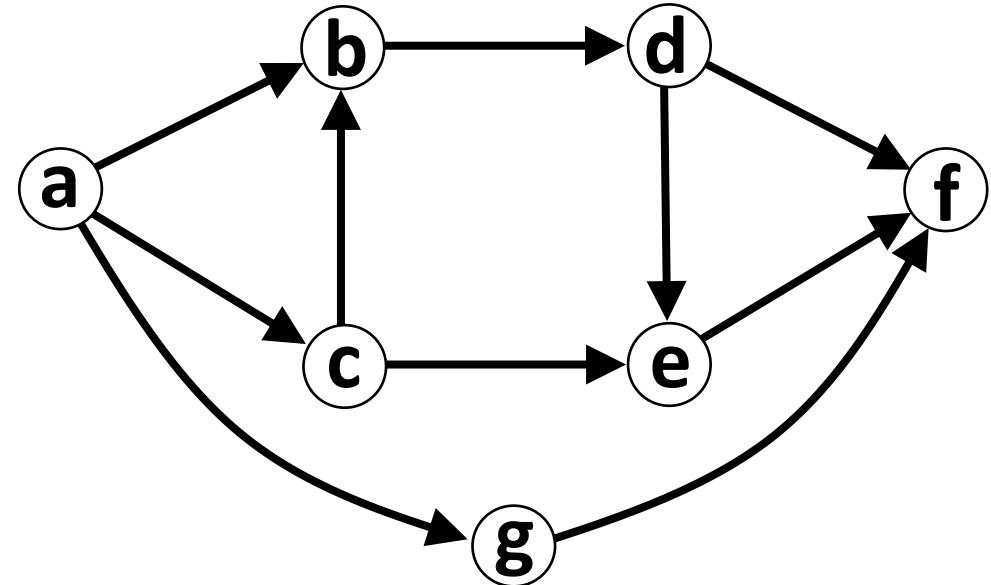
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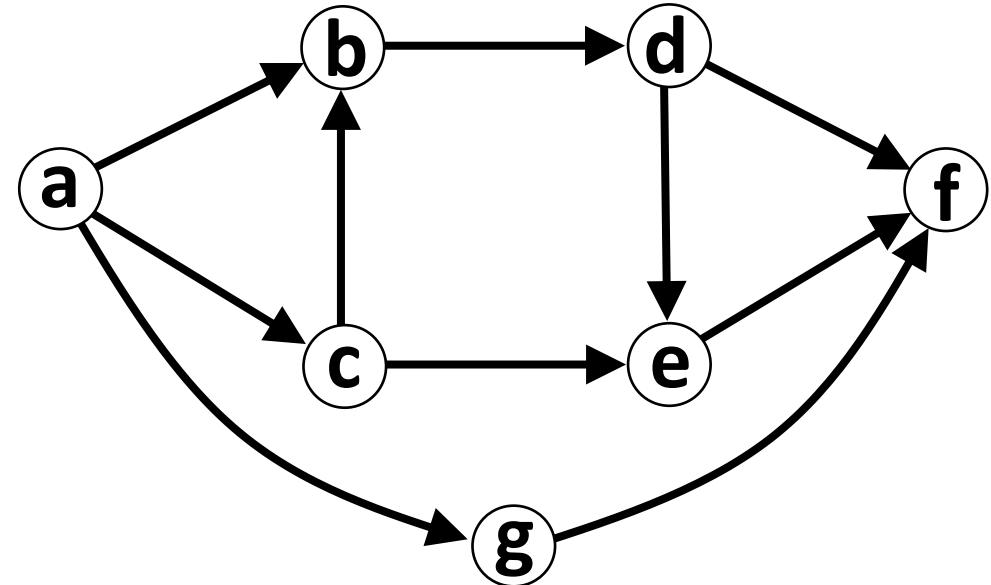
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1

# Find the Longest Path in a DAG

Plan:

- Topologically sort vertices.
- Make array to store length of longest path that ends at each vertex.
- For each vertex in order, calculate longest path as:  
$$\max_n(\text{longest path to } n) + 1,$$
 for all incoming neighbors  $n.$
- Largest value in array = Longest path.



{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1

# Find the Longest Path in a DAG

```
longest_path(G=(v, E)):  
    pathLengths = [0, ..., 0]  
    Let  $v_{\text{sort}}$  be topologically sort vertices  
    for each vertex  $v$  in  $v_{\text{sort}}$ :  
        for each incoming neighbor  $n$  of  $v$ :  
            if  $\text{pathLengths}[n] + 1 > \text{pathLengths}[v]$ :  
                 $\text{pathLengths}[v] = \text{pathLengths}[n] + 1$   
    return maxvalue(pathLengths)
```

**Running time: ?**

# Find the Longest Path in a DAG

```
longest_path(G=(V, E)):
```

```
    pathLengths = [0, ..., 0]
```

Let  $V_{\text{sort}}$  be topologically sort vertices

```
for each vertex v in  $V_{\text{sort}}$ :
```

```
    for each incoming neighbor n of v:
```

```
        if pathLengths[n] + 1 > pathLengths[v]:
```

```
            pathLengths[v] = pathLengths[n] + 1
```

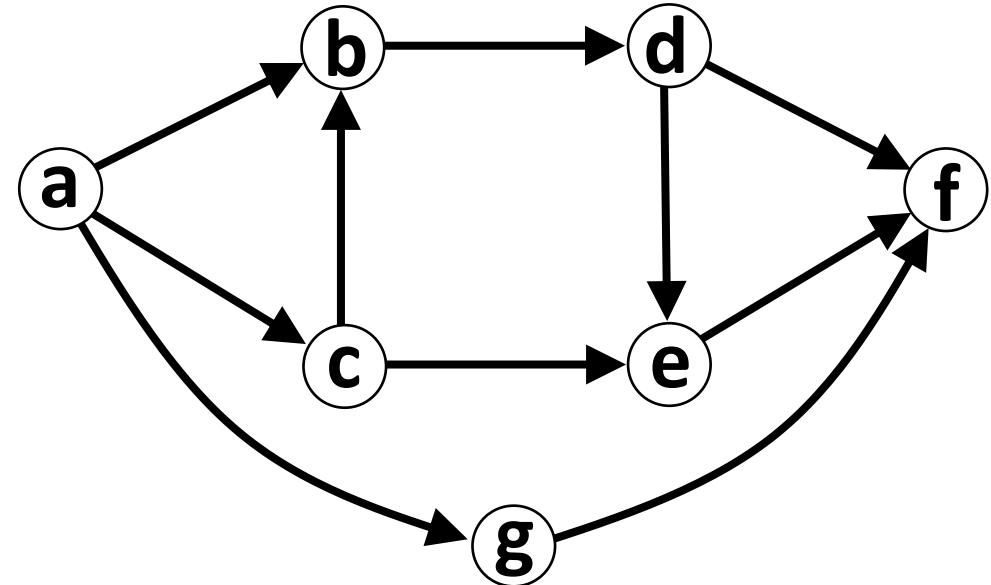
```
return maxvalue(pathLengths)
```

Running time:  $O(\text{Topological Sort} + |V|^2) \in O(|V|^2)$

# Find the Longest Path in a DAG

Plan:

- Topologically sort vertices.
- Make array to store length of longest path that ends at each vertex.
- For each vertex in order, calculate longest path as:  
$$\max_n(\text{longest path to } n) + 1,$$
 for all incoming neighbors  $n.$
- Largest value in array = Longest path.



{a, c, g, b, d, e, f}

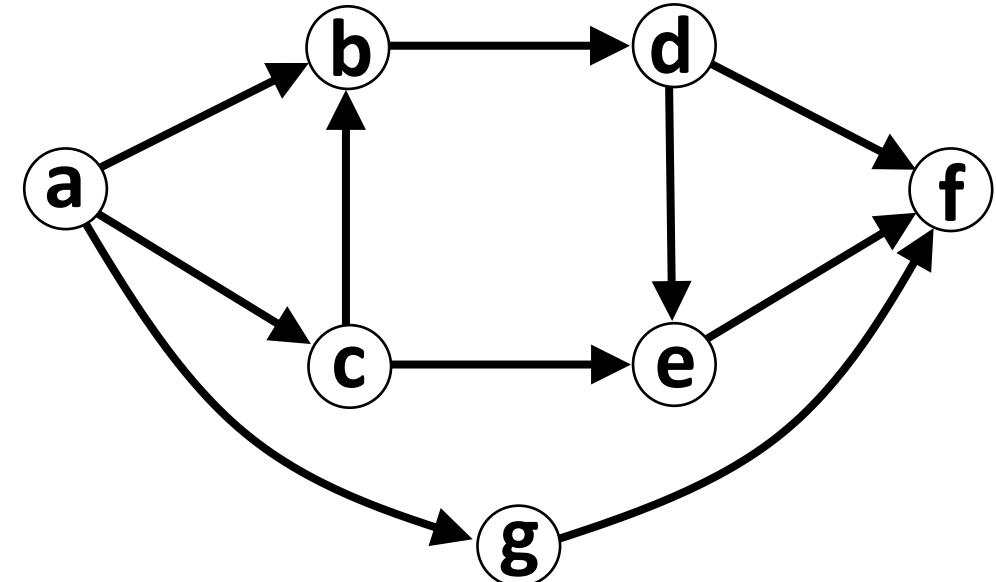
a	b	c	d	e	f	g
0	2	1	3	4	5	1

# Find the Longest Path in a DAG

Plan:

- Topologically sort vertices.
- Make array to store length of longest path that ends at each vertex.
- For each vertex  $n$ , calculate longest path to  $n$  + 1, among incoming neighbors  $n$ .
- Largest value in array = Longest path.

**So, what's the path??**



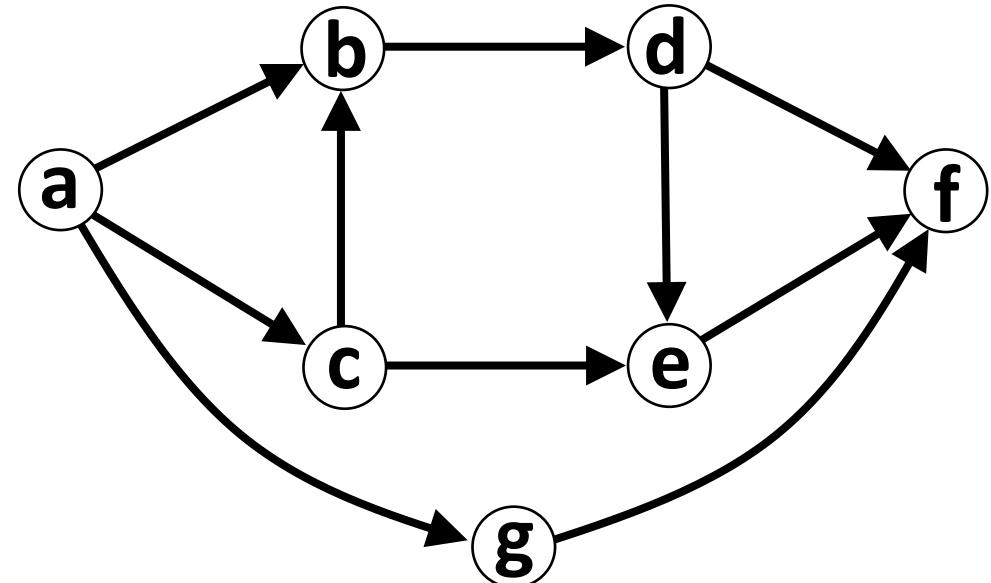
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.



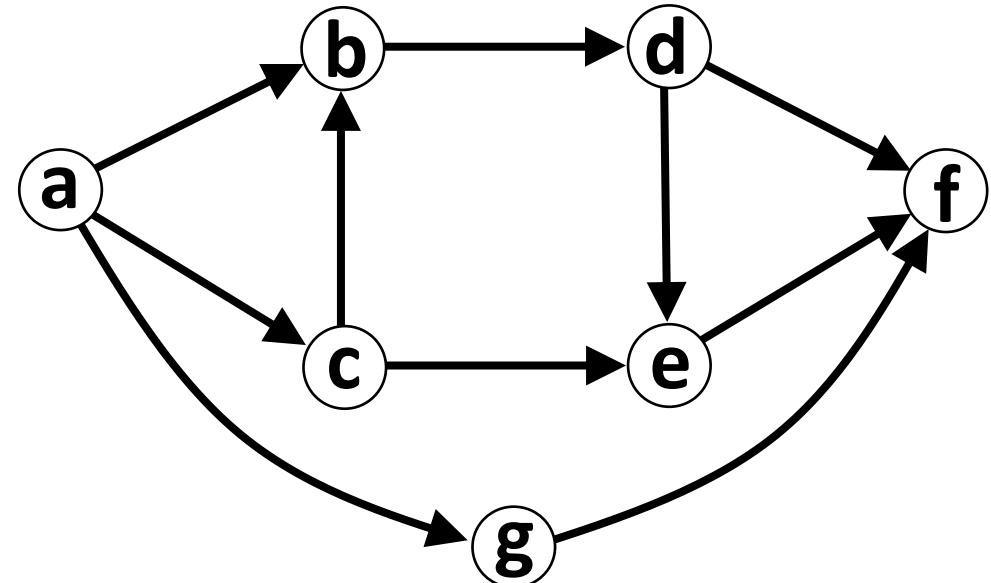
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	-	-	-	-	-	-

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.



{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	-	-	-	-	-	-

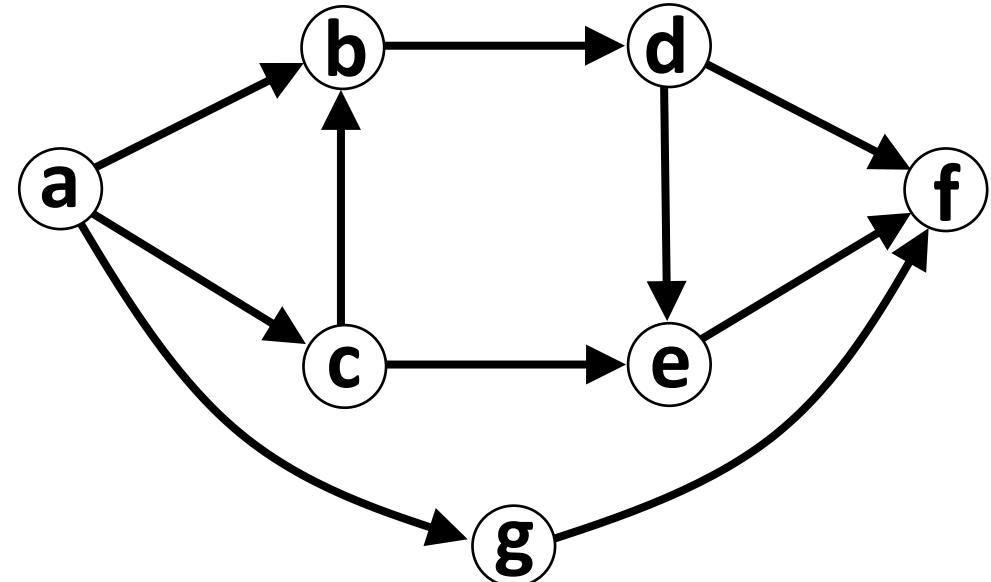
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{a, c, g, b, d, e, f}

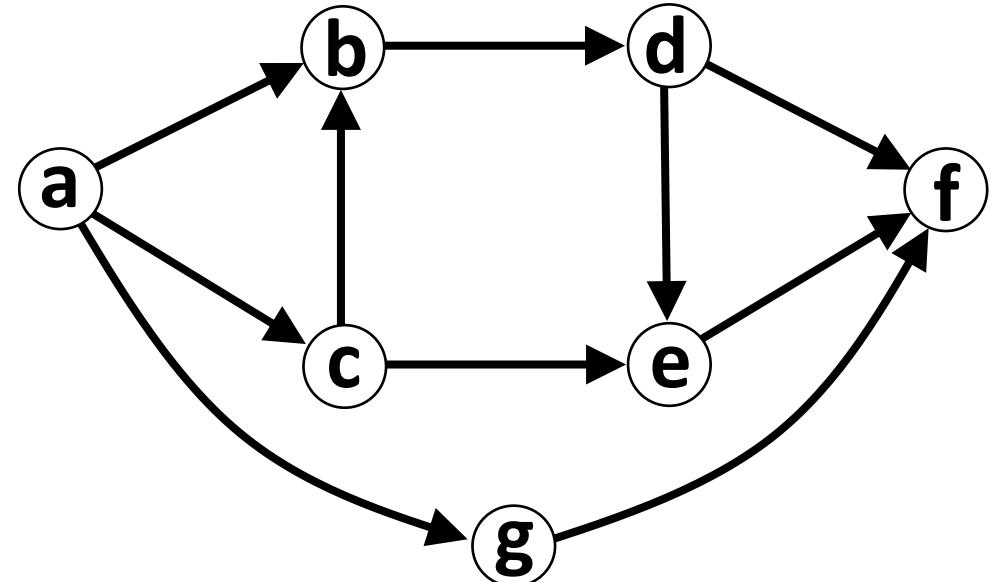
a	b	c	d	e	f	g
0	0	0	0	0	0	0
-	-	-	-	-	-	-

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0	0	0	0	0	0	0
-	-	-	-	-	-	-

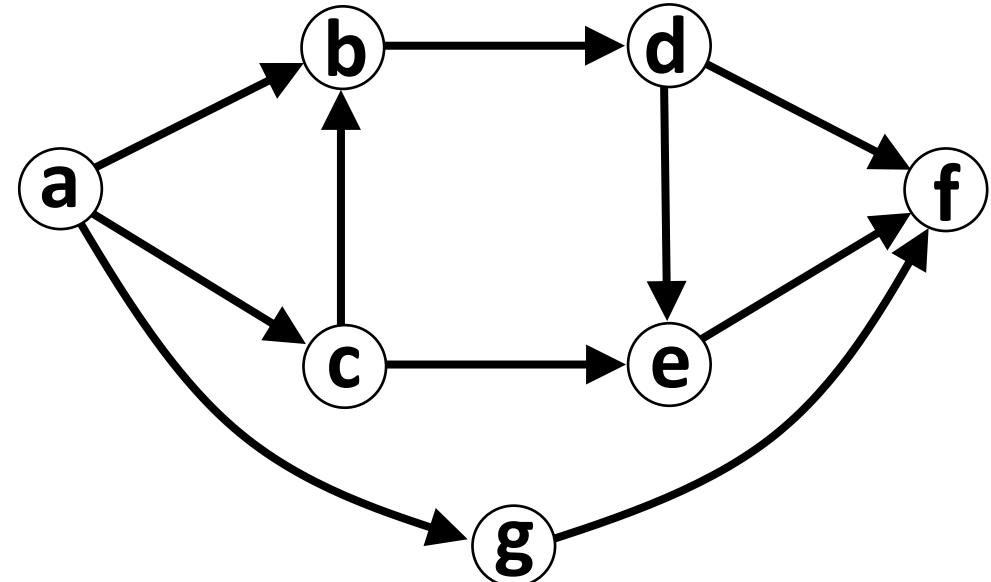
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{a, **c**, g, b, d, e, f}

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0	0	0	0	0	0	0
-	-	-	-	-	-	-

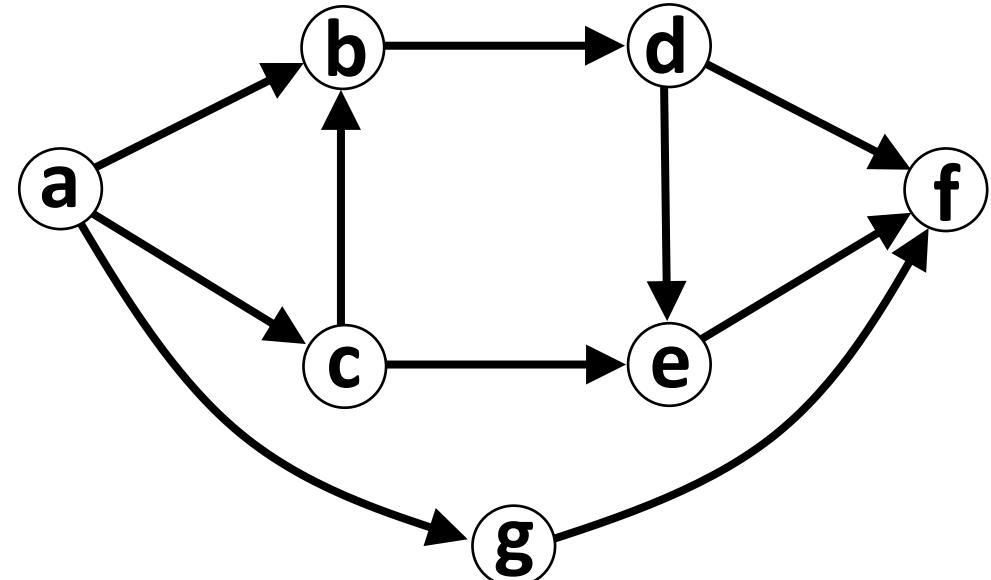
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{a, **c**, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	1	0	0	0	0
-	-	-	-	-	-	-

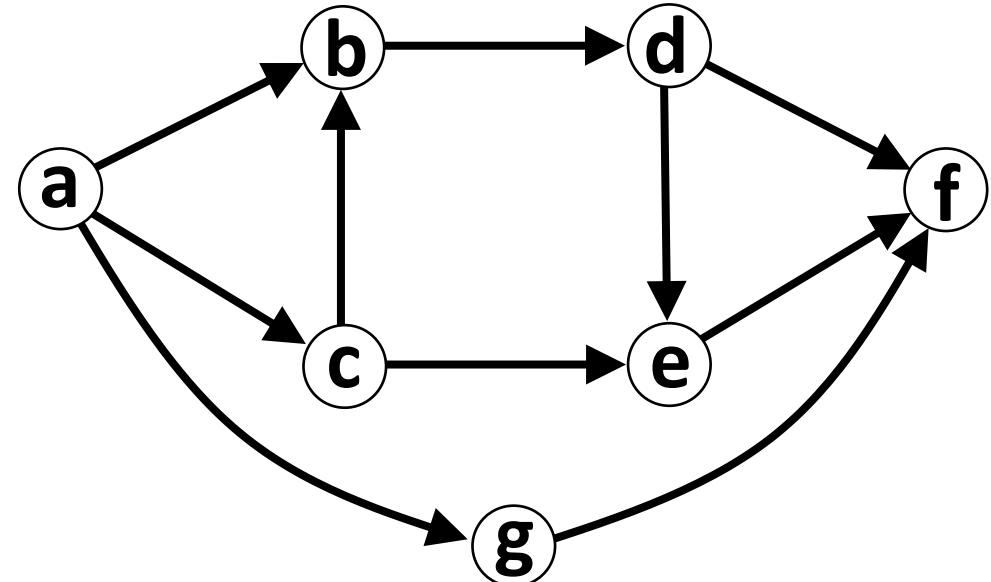
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for all incoming neighbors  $n$ .



{a, **c**, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	1	0	0	0	0
-	-	a	-	-	-	-

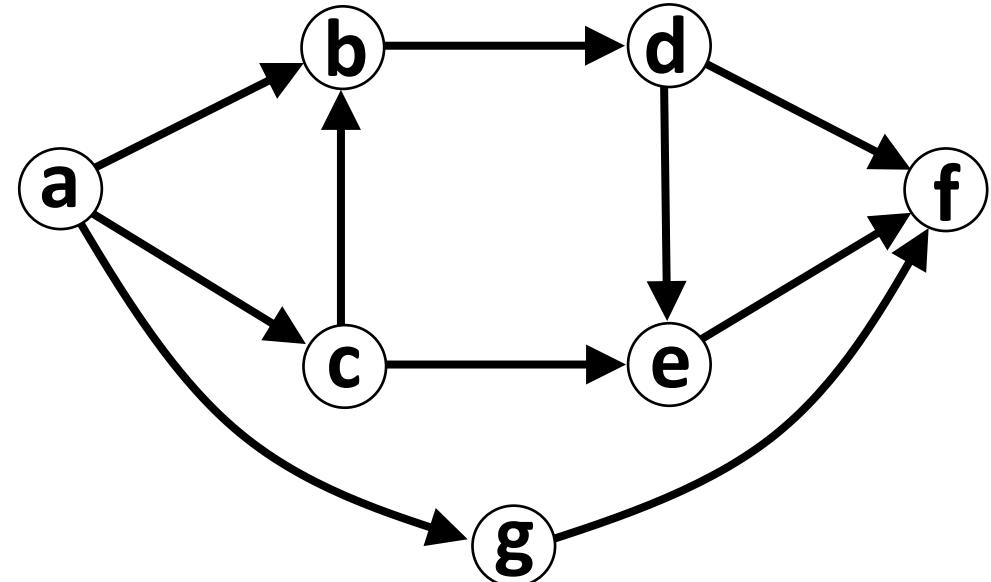
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{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	0	1	0	0	0	1
-	-	a	-	-	-	a

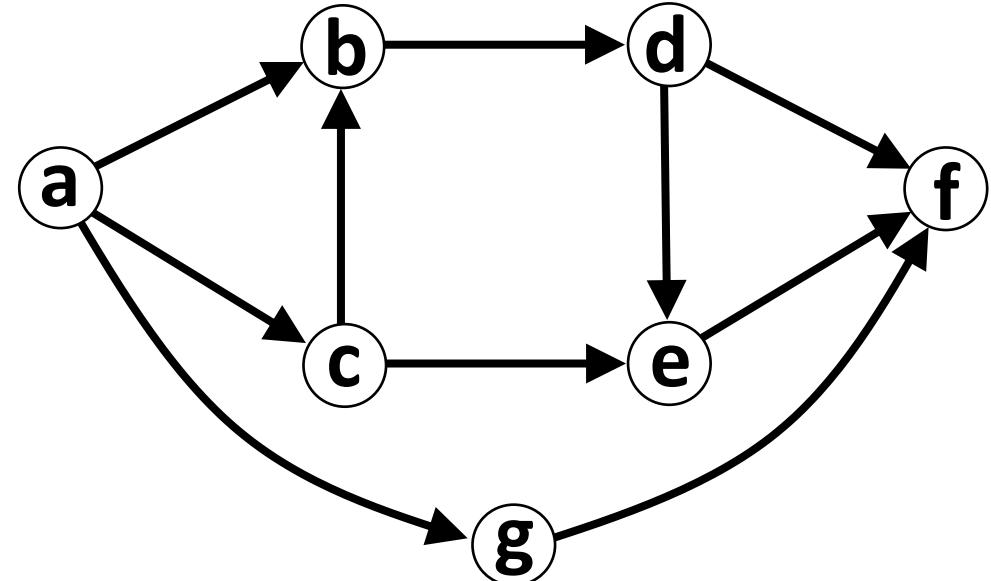
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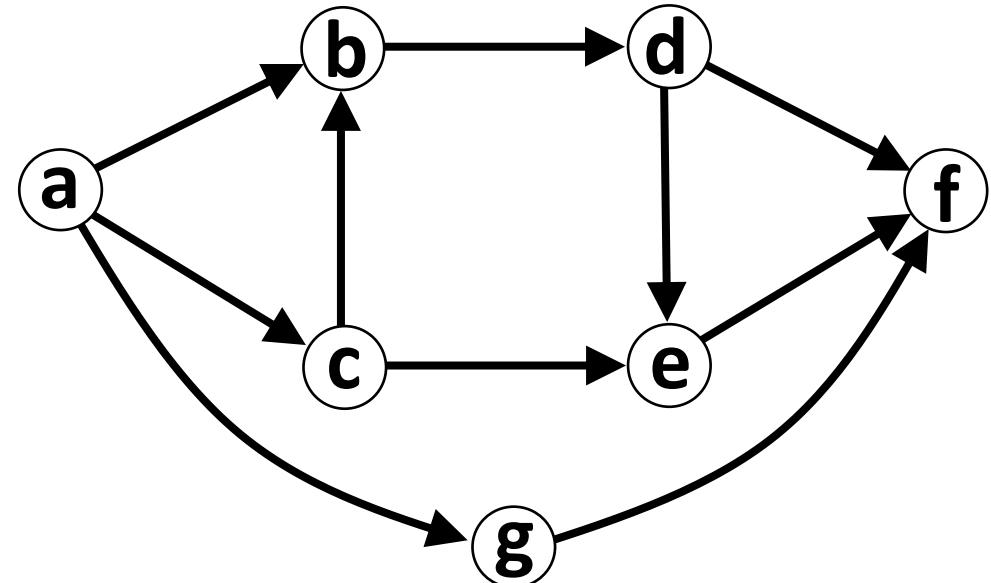
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	0	0	0	1
-	c	a	-	-	-	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.



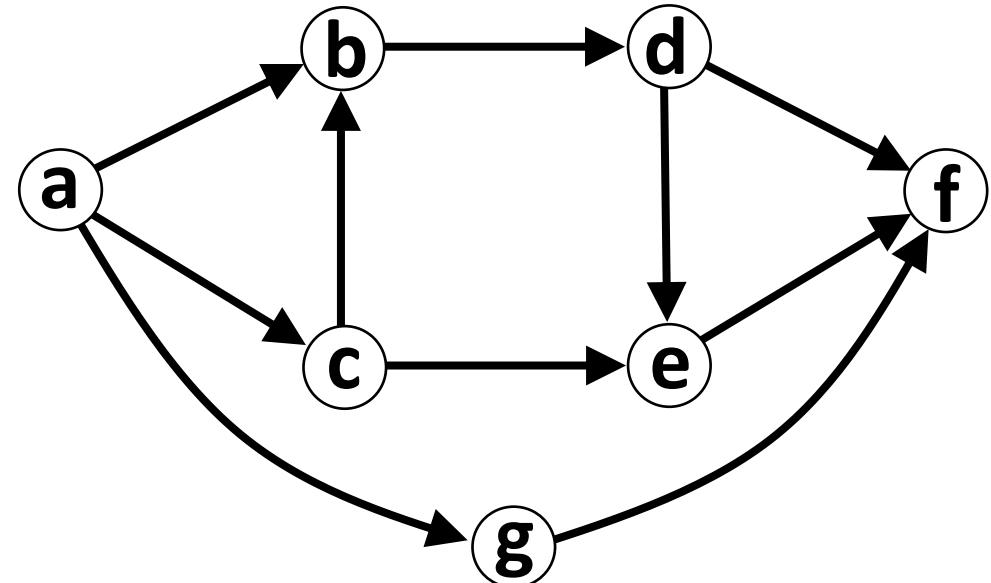
{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.



{a, c, g, b, d, e, f}

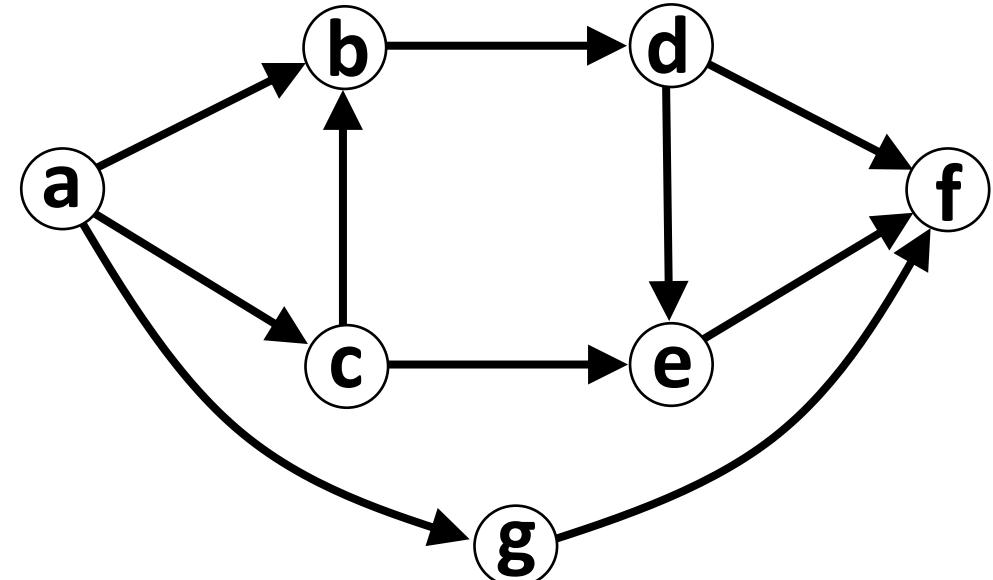
a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.

path: f



{a, c, g, b, d, e, f}

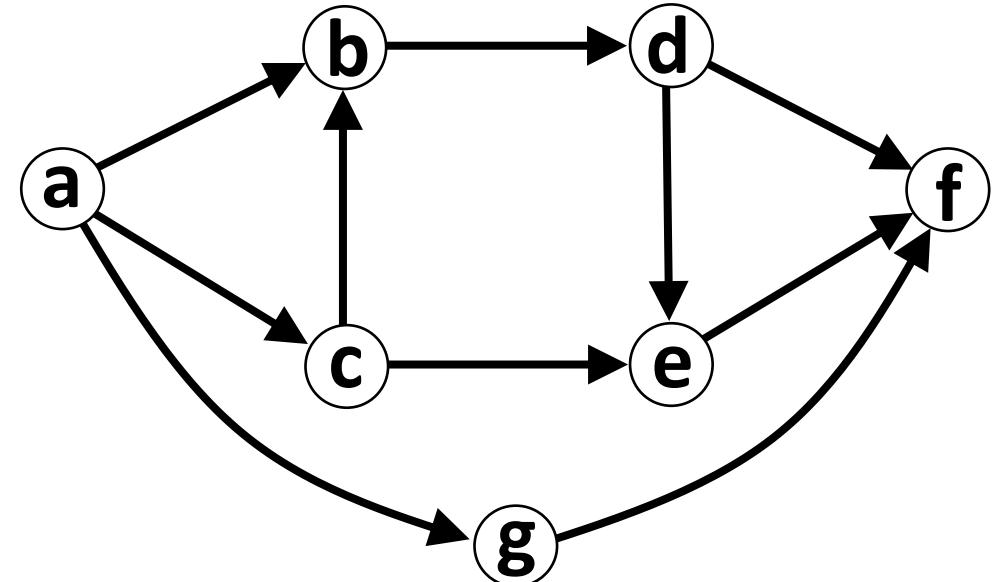
a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.

path: f <- e



{a, c, g, b, d, e, f}

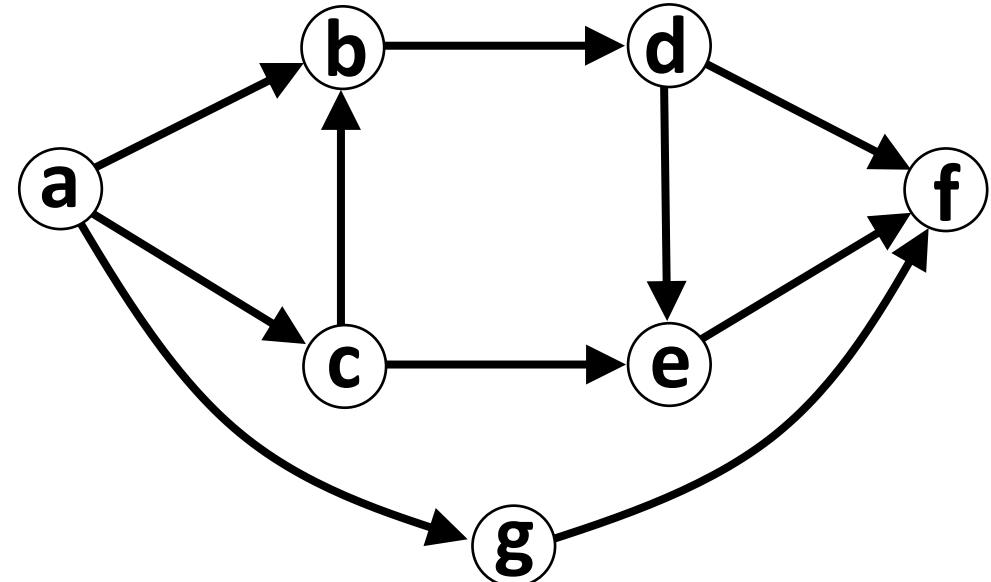
a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.

path: f <- e <- d



{a, c, g, b, d, e, f}

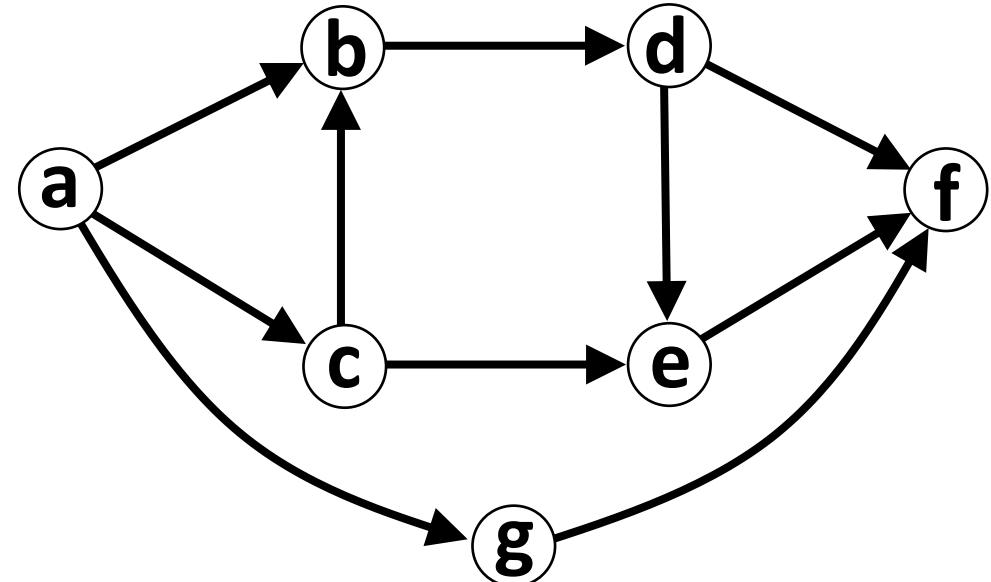
a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.

path: f <- e <- d <- b



{a, c, g, b, d, e, f}

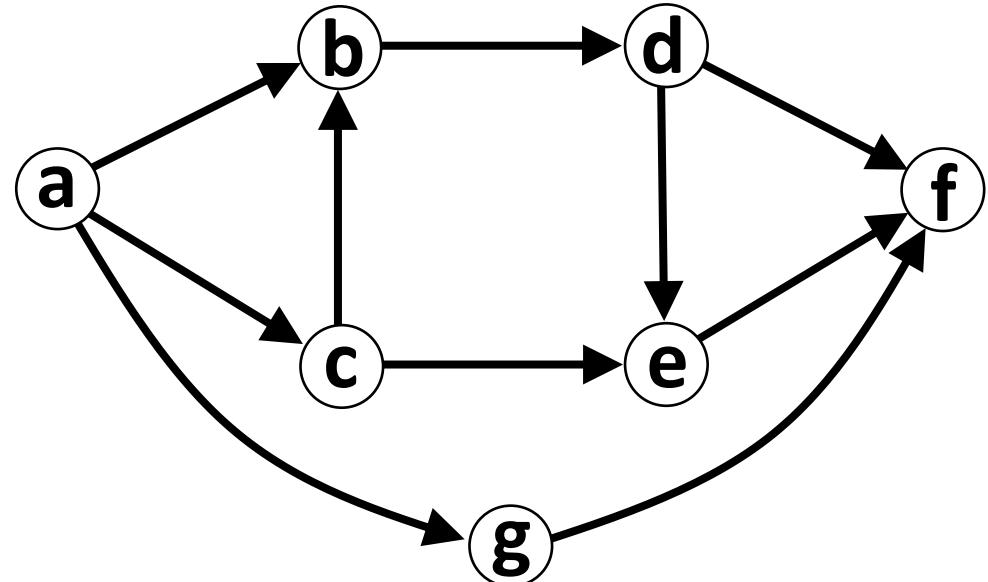
a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a

# Find the Longest Path in a DAG

Plan:

- Make second array that tracks where longest path came from.
- When neighbor with longest path is determined, save that neighbor.
- Backtrack through array to construct path.

path: f <- e <- d <- b <- c <- a



{a, c, g, b, d, e, f}

a	b	c	d	e	f	g
0	2	1	3	4	5	1
-	c	a	b	d	e	a